

Tracer kinetic modelling

Basic concepts

Mark Vestergaard

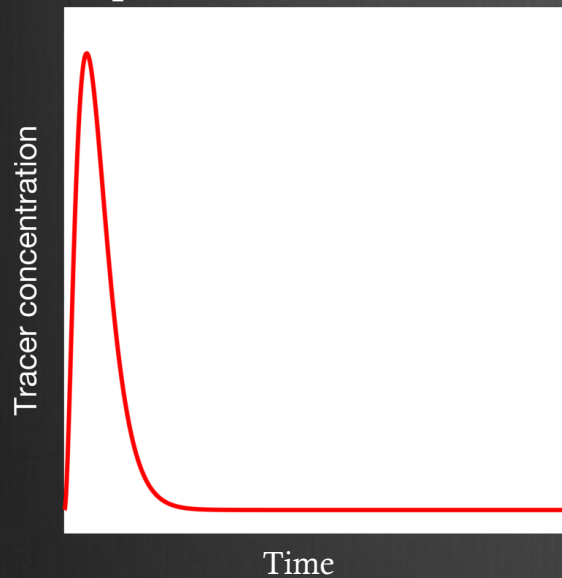
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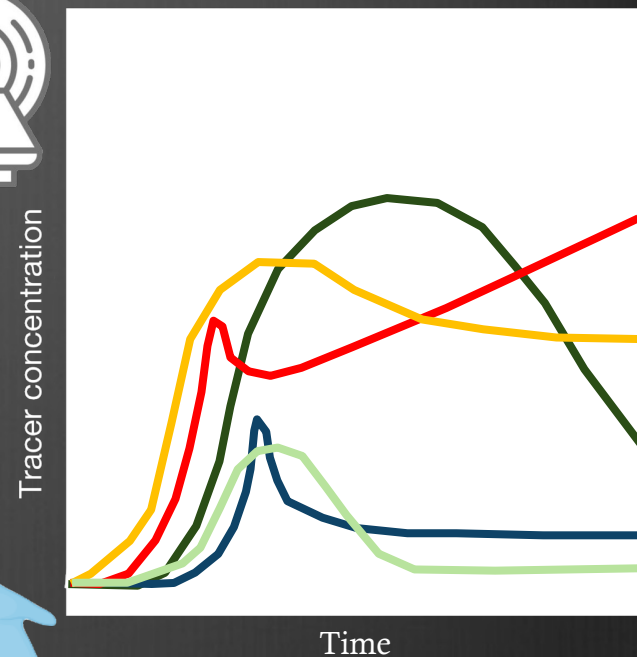
What is tracer kinetic modelling?

- Mathematical description of a tracer behavior in the body
- From the mathematical description the physiological system can be examined

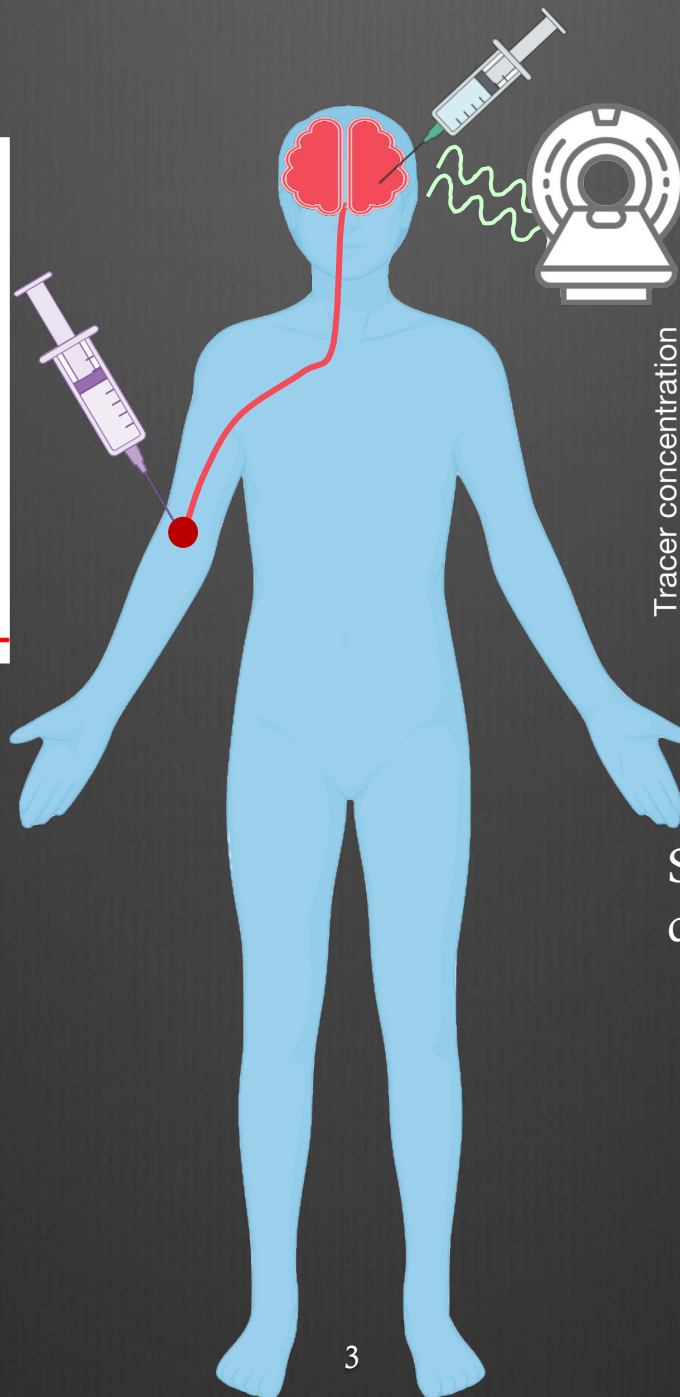
Input function



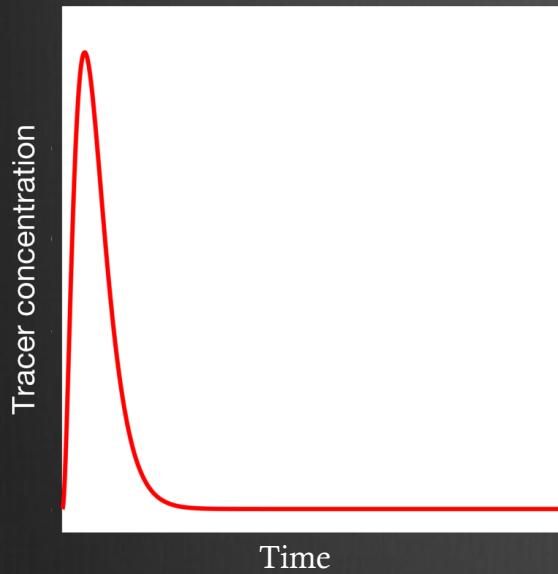
Tissue functions



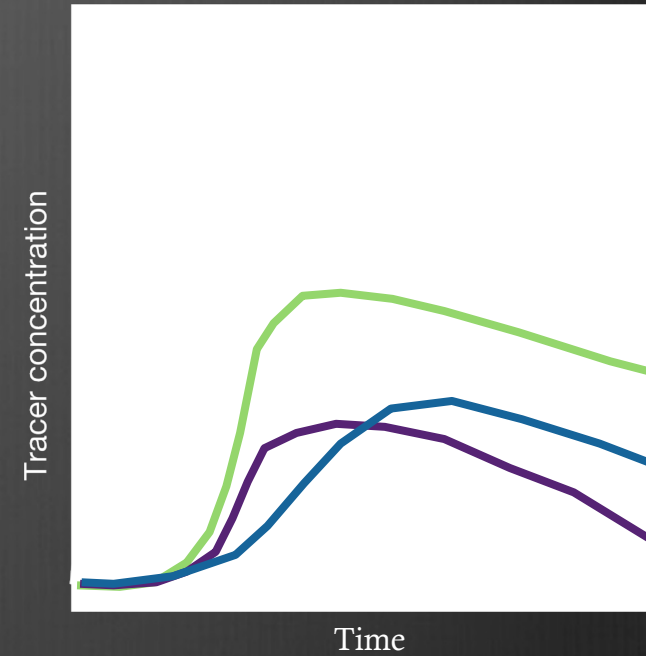
Shapes of the curves represent different physiology.



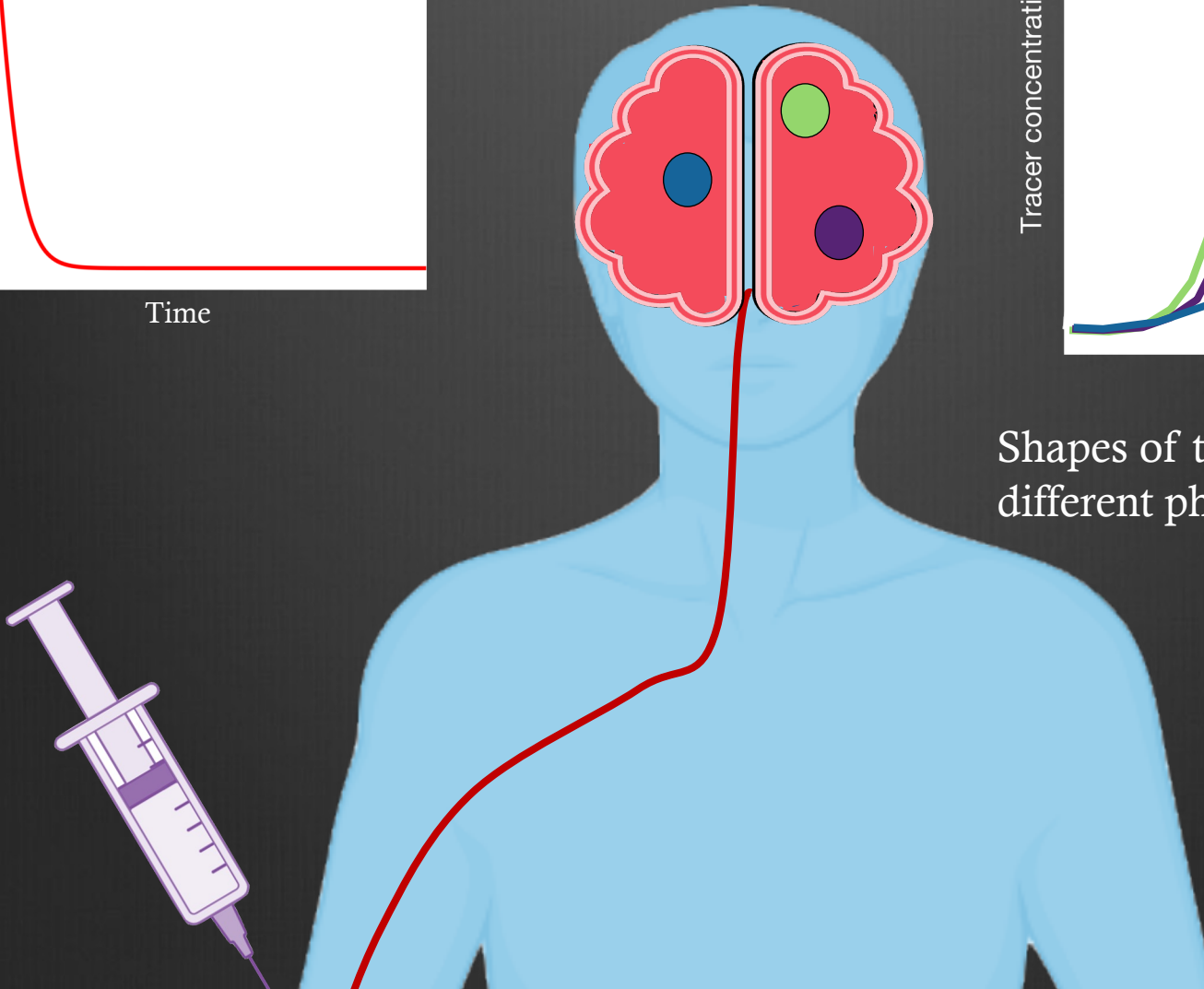
Input function

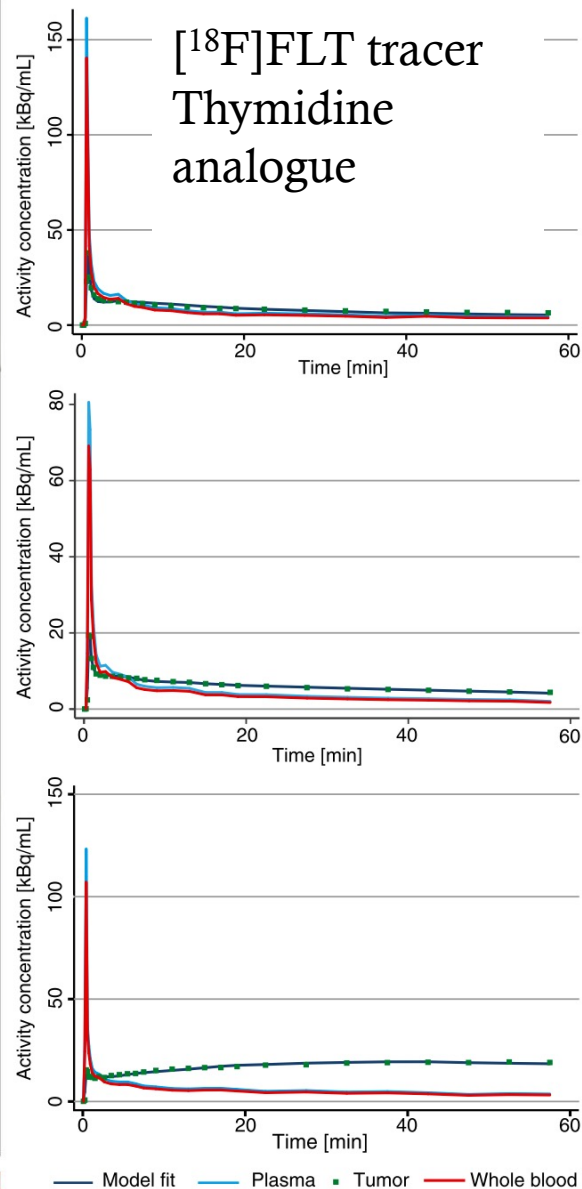
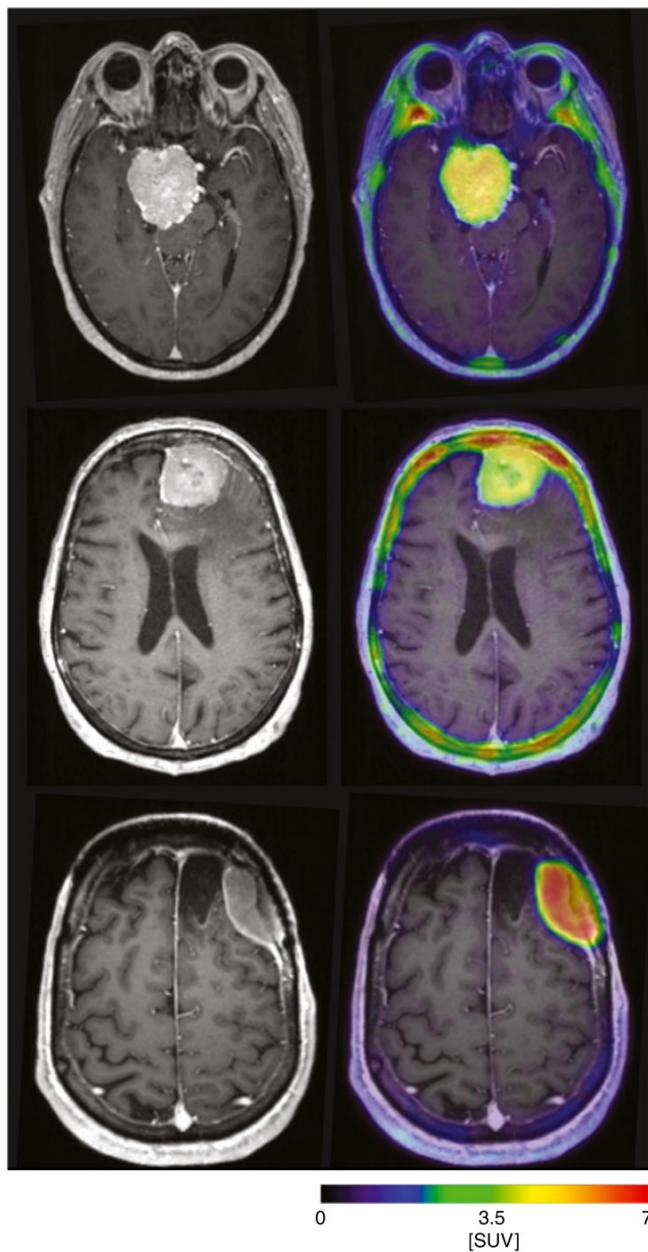


Tissue functions

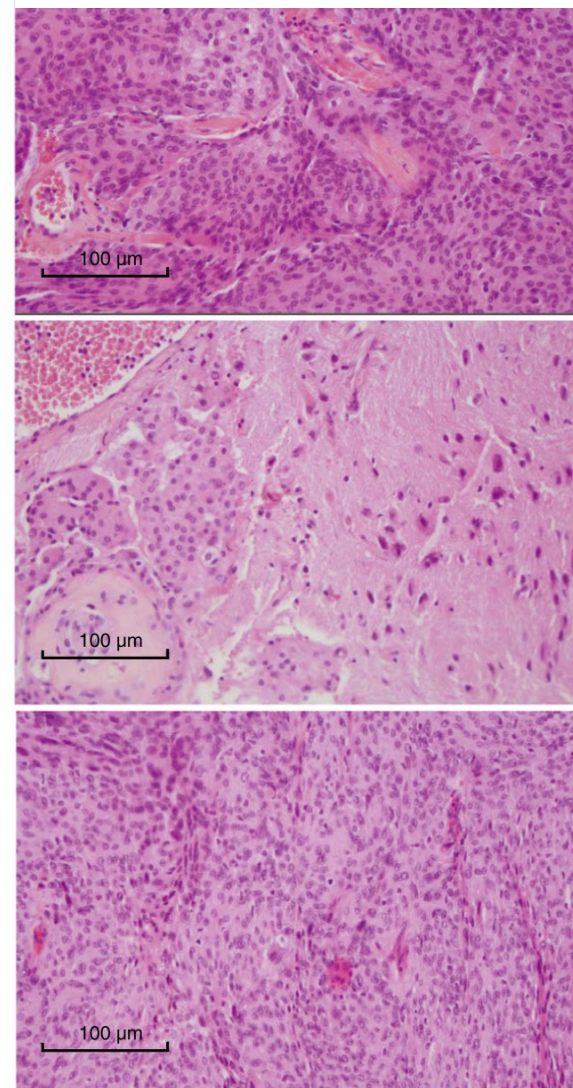


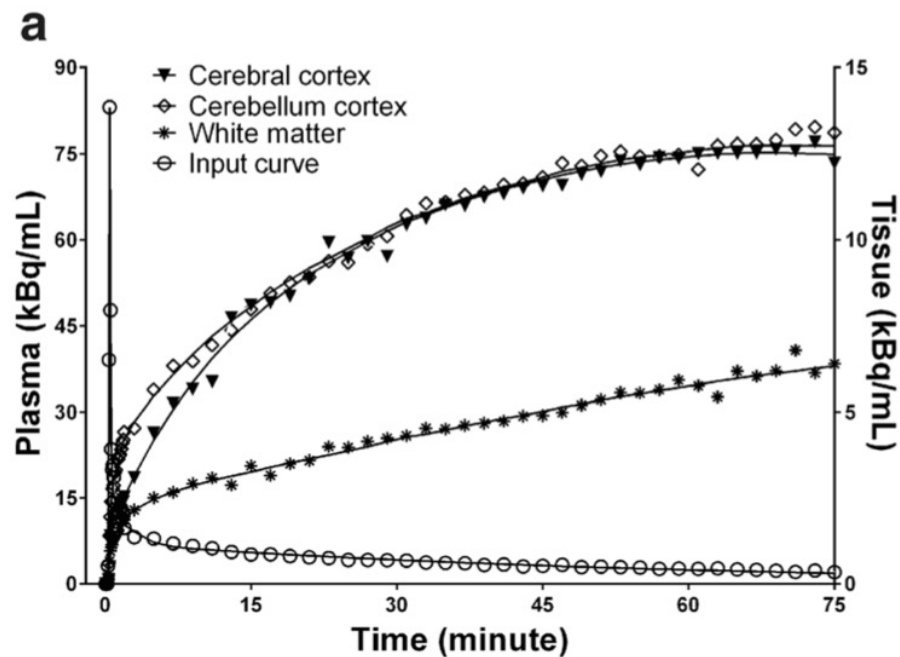
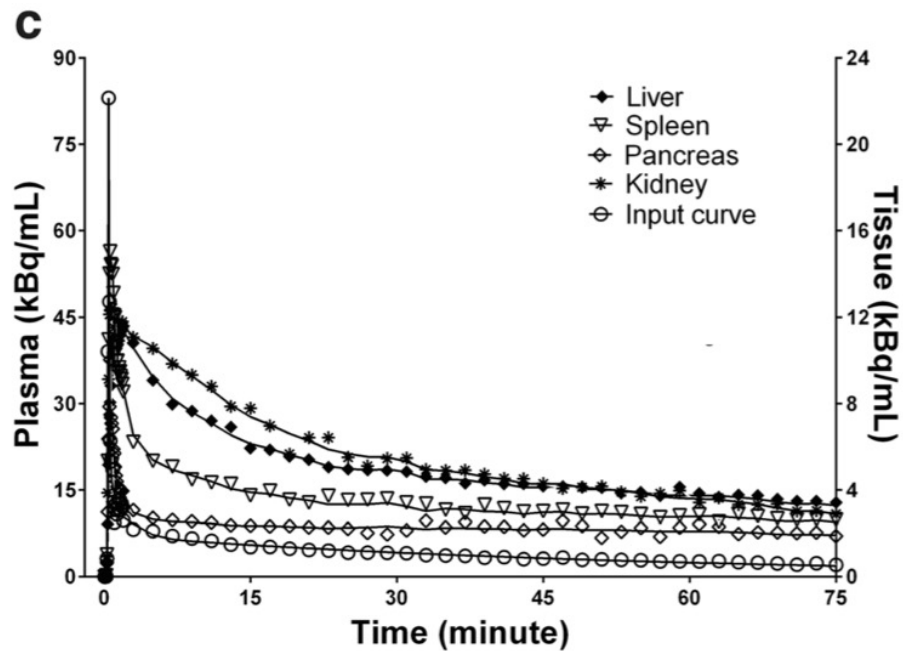
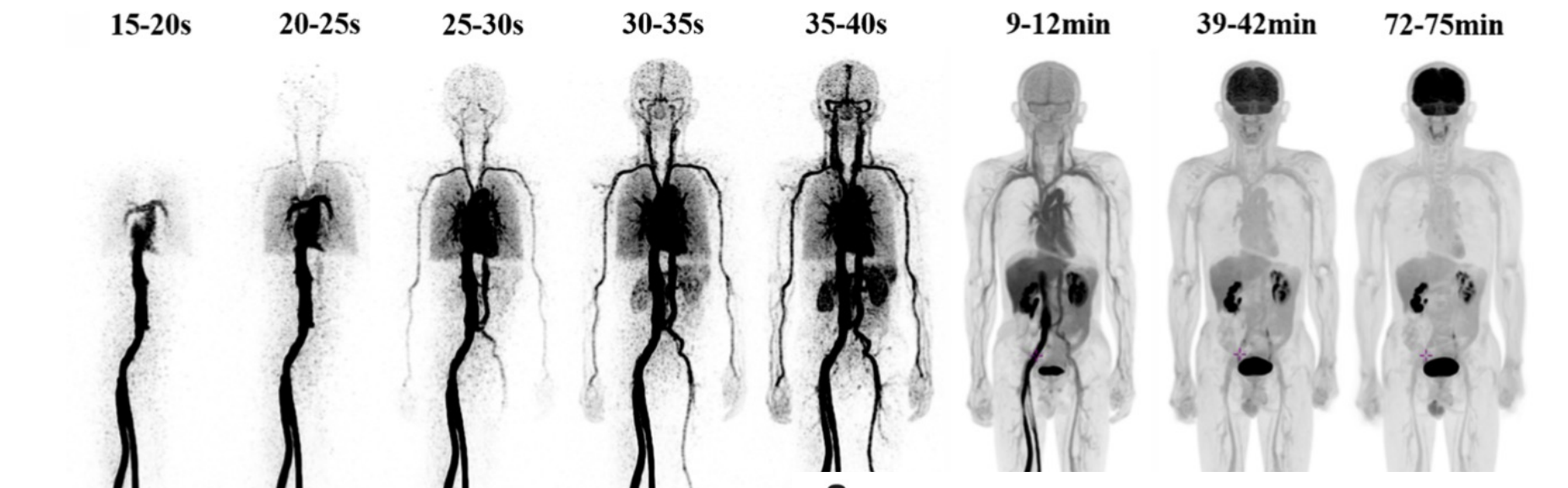
Shapes of the curves represent different physiology.





Cell proliferation



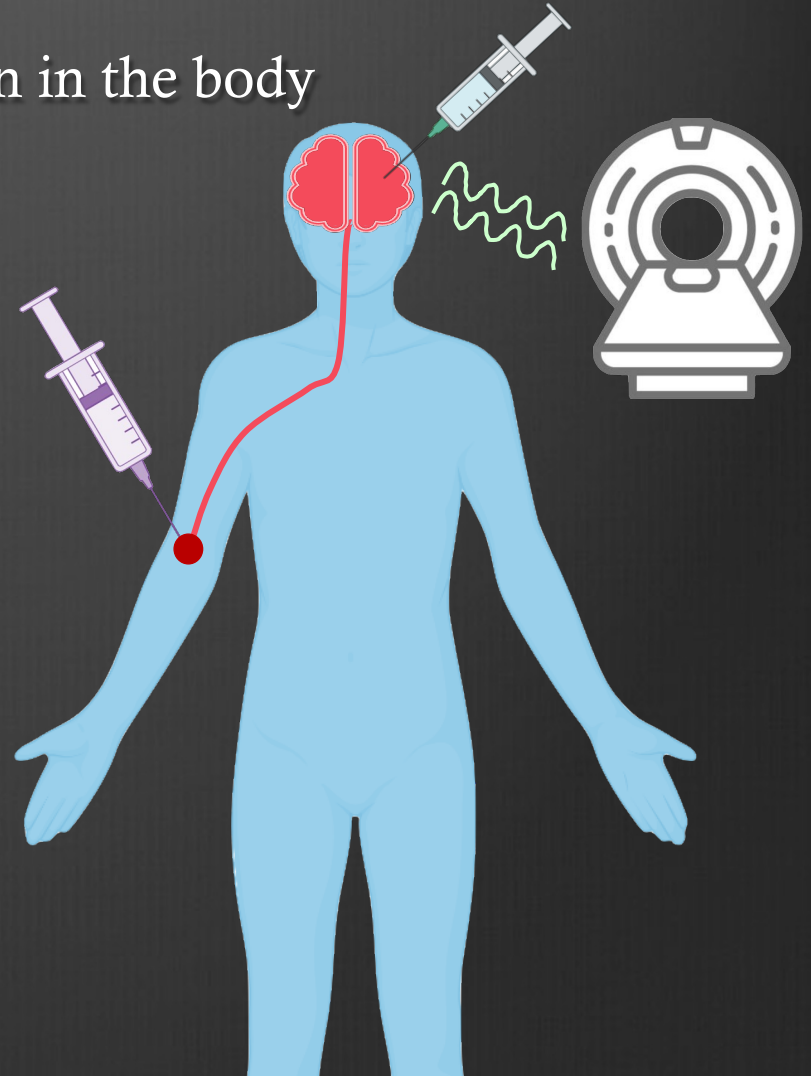


What is tracer kinetic modelling?

- Mathematical description of a tracer behavior in the body
- From the mathematical description the physiological system can be examined
- A tracer is injected in a physiological system
- The dynamic changes of the tracer concentration in the tissue is measured
 - Tracer concentration as a function of time
- Create a mathematical model which relate tracer input to measured tracer concentration in tissue

Tracers

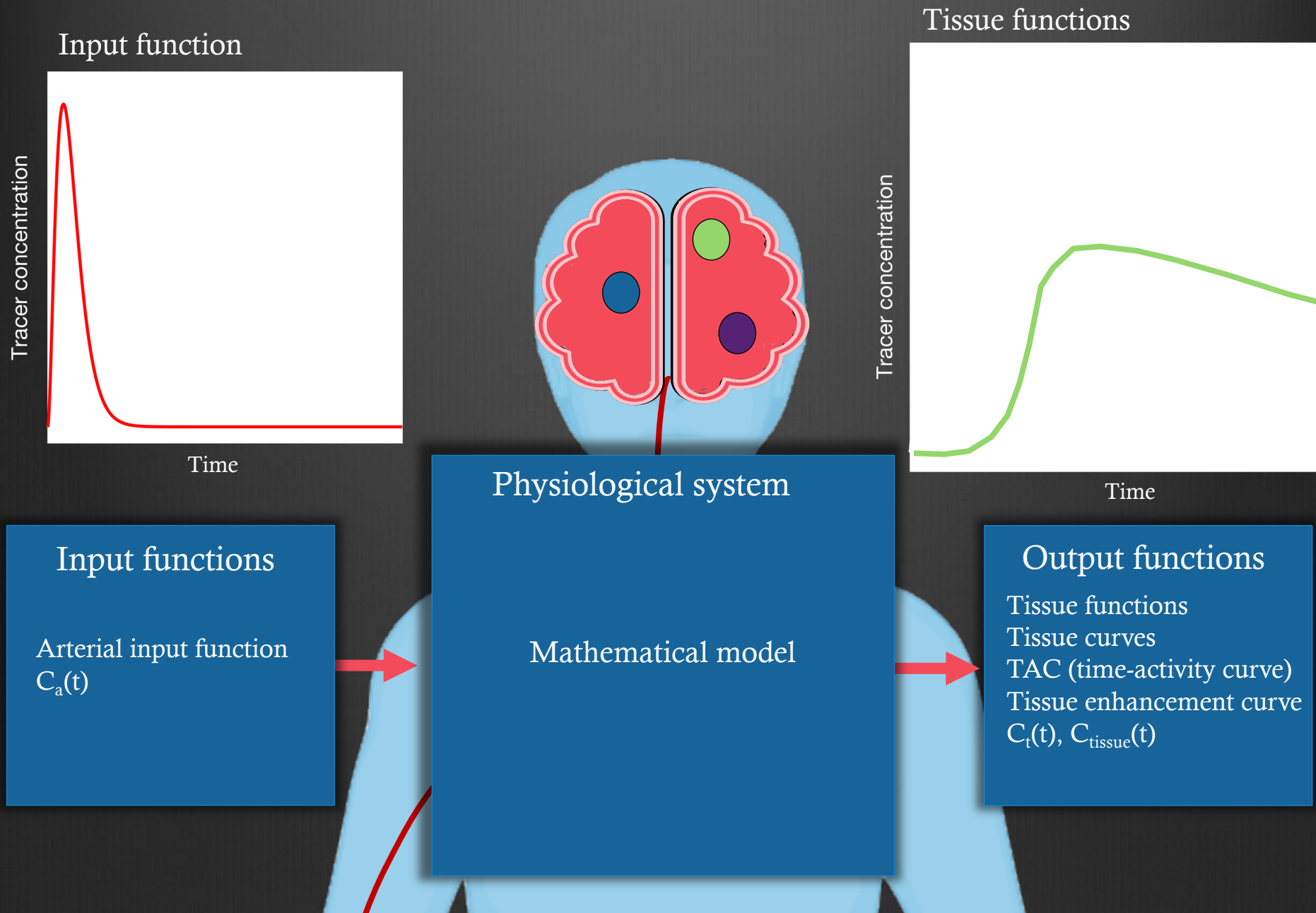
- Administrated into the body
- Measure the tracer concentration in the body
 - Radioactive
 - Affect MRI-signal
 - Blood sampling
 - Other



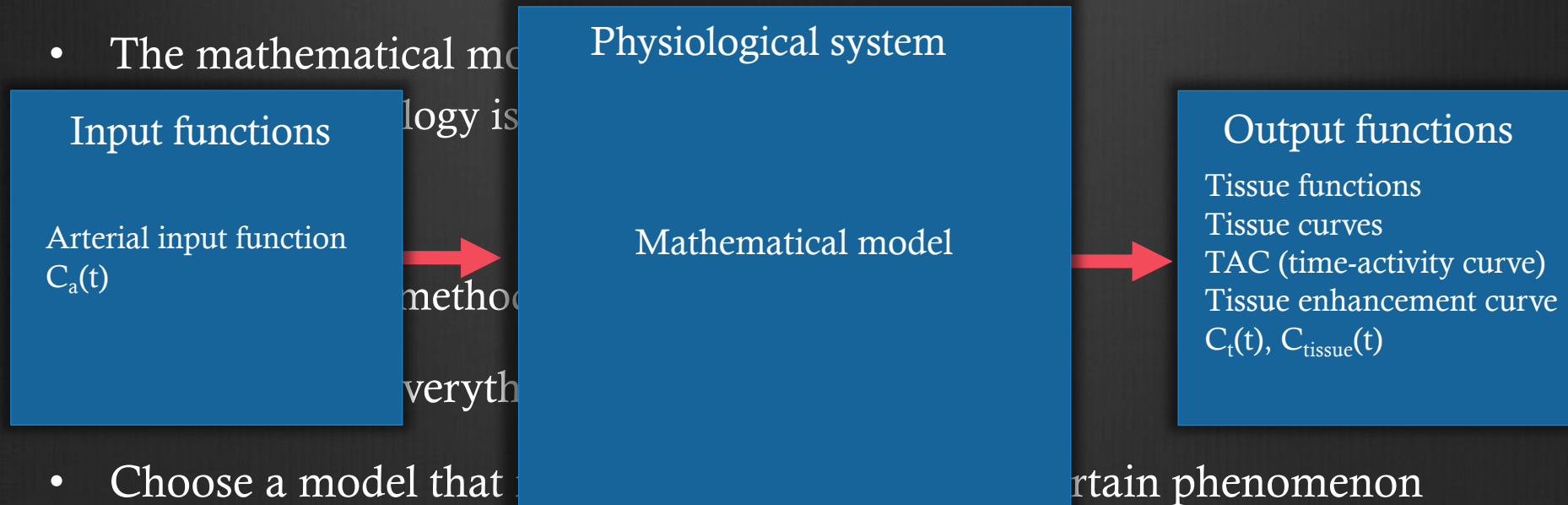
Tracers

- Tracer should provide information of certain physiology
 - Labelled substances, (nearly) behaving physically and chemically like other substance
 - $^{15}\text{O}-\text{H}_2\text{O}$, $^{18}\text{F}-\text{FDG}$
 - Tracer binding to certain receptors
 - Somatostatin receptors, Serotonin receptors, Vascular endothelial growth factor receptors
 - Indicators not related to physiological substance
 - MRI gadolinium based agents, $^{99\text{m}}\text{Tc}-\text{HMPAO}$
- Tracers can be intravascular, extracellular, free diffusible, bound to a receptor or behave in a more specific way.
- New tracers are being developed
- Should not disturb the system we are studying

Mathematics to describe the tracer concentration



- Mathematically describe the tracer behavior in the physiological system
- The mathematical model of the physiological system is

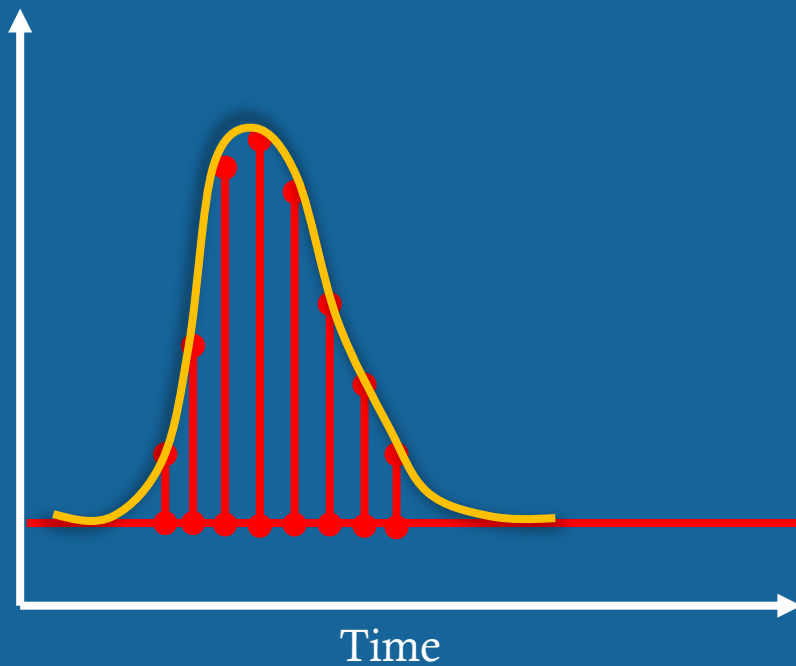


- Choose a model that describes a certain phenomenon

Impulse response

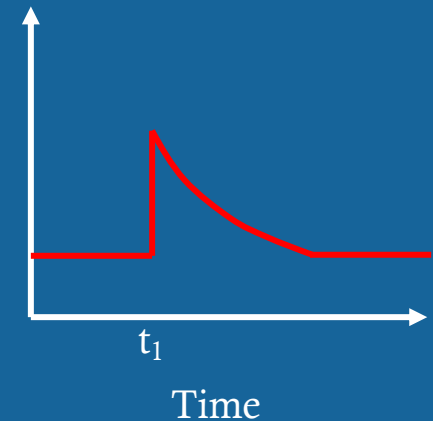
Description of system by impulse response function

Input function described as a series of delta functions



System
response
 (t)

Impulse response



The response of any system to a delta function of width

Linearity of a system



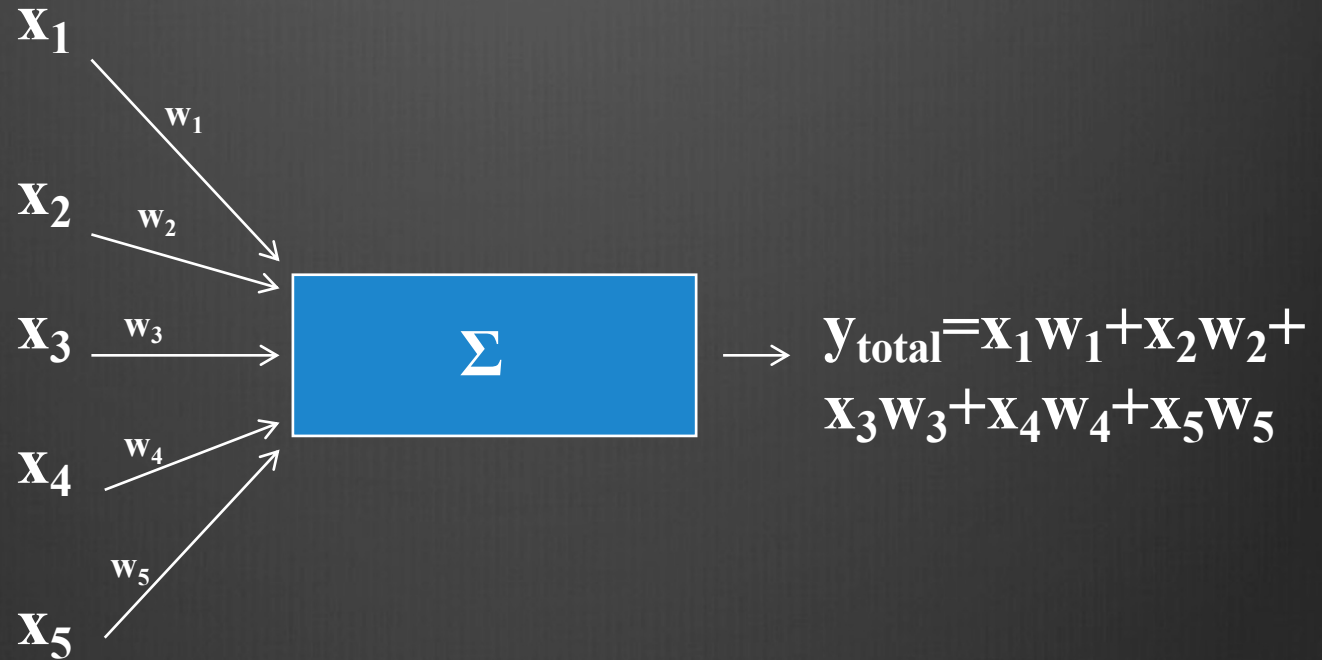
Linearity of a system



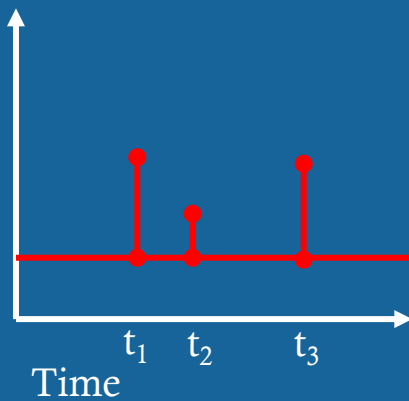
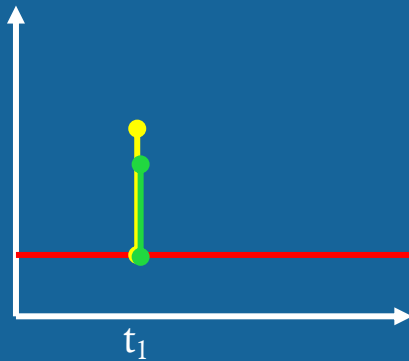
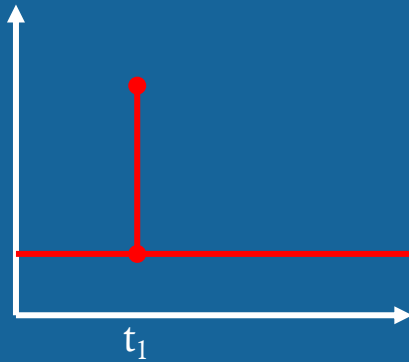
$$x_1 + x_2 \xrightarrow{RF(t)} y_1 + y_2$$

Principle of superposition

Examples



Input functions

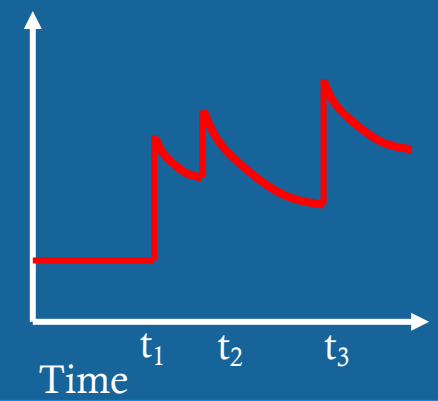
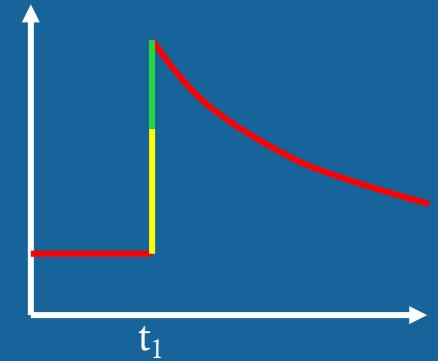
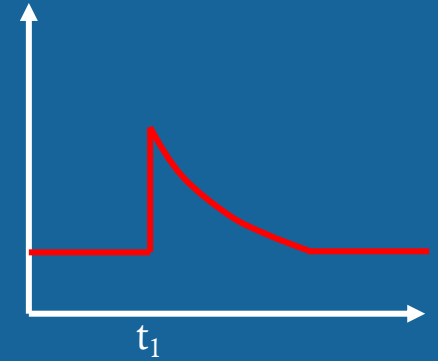


Linearity of system

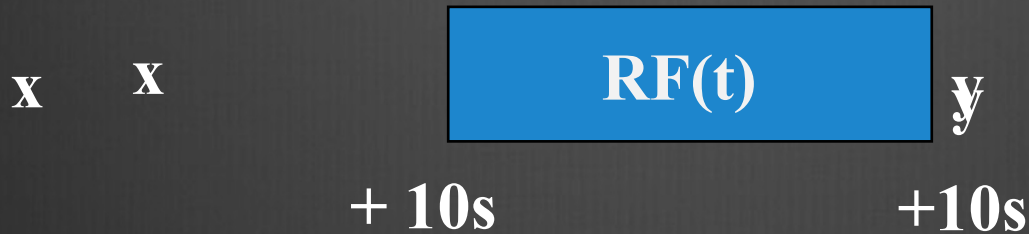
Mathematical model



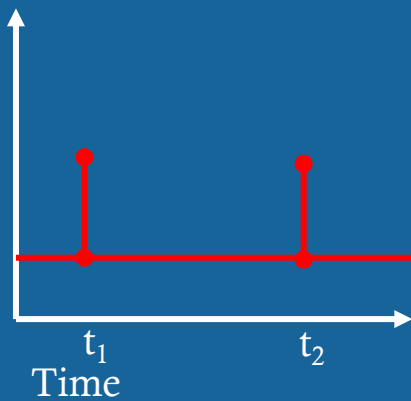
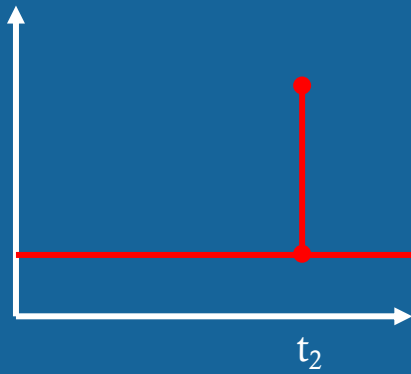
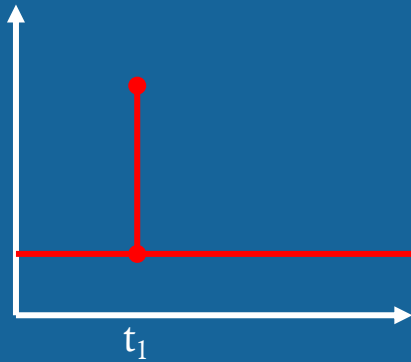
Impulse response



Time invariance of a system



Input functions

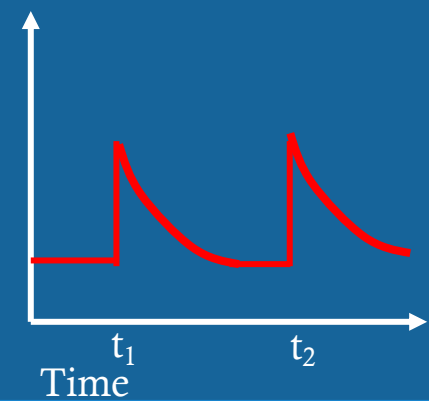
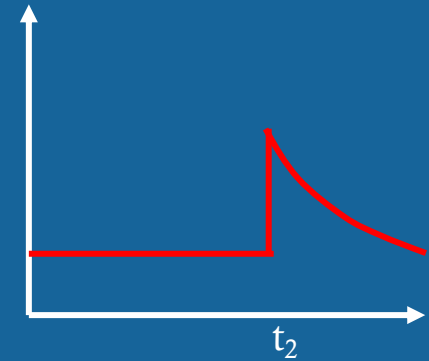
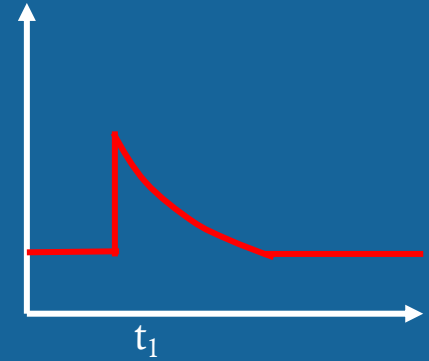


Time invariance of system

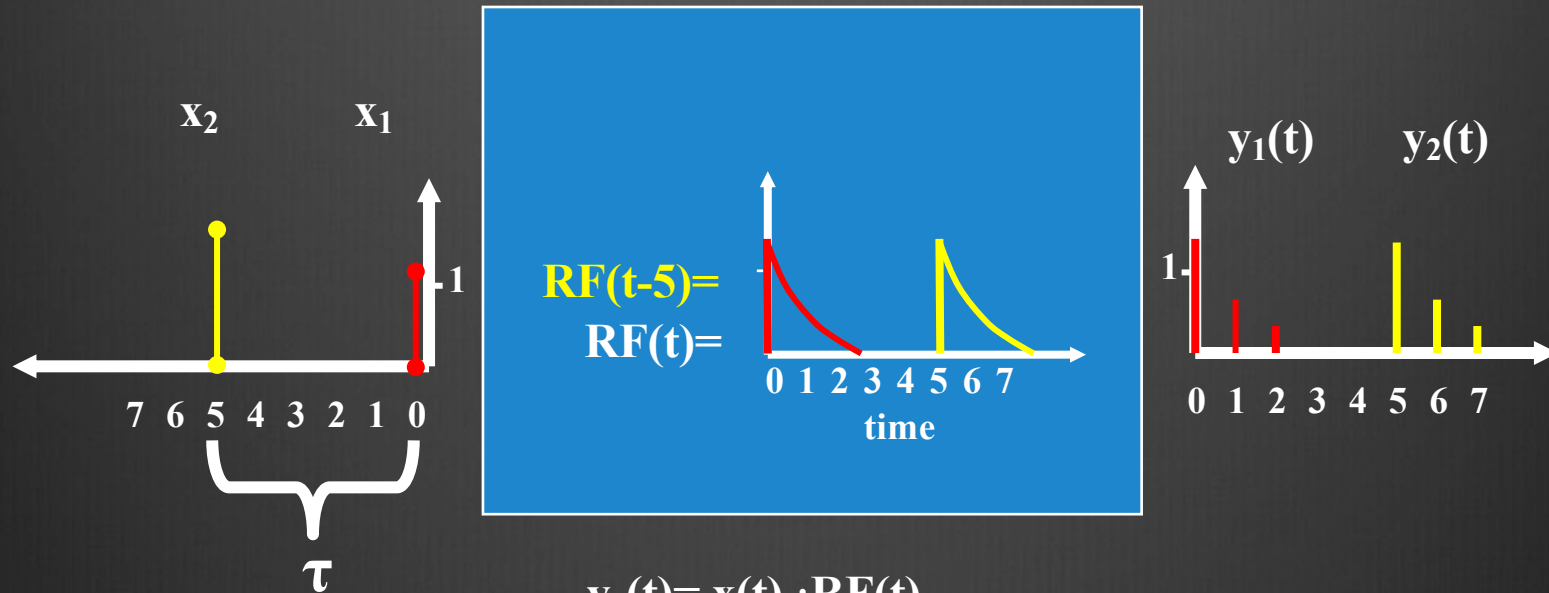
Mathematical model

$RF(t)$

Impulse response



Time delay, τ



$$y_1(t) = x(t) \cdot RF(t)$$

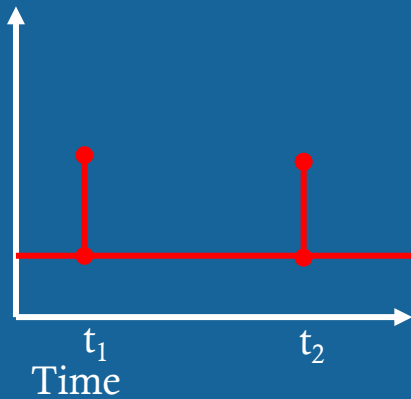
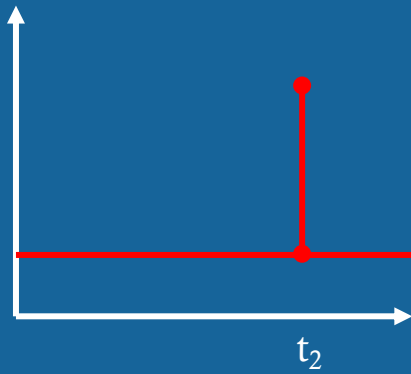
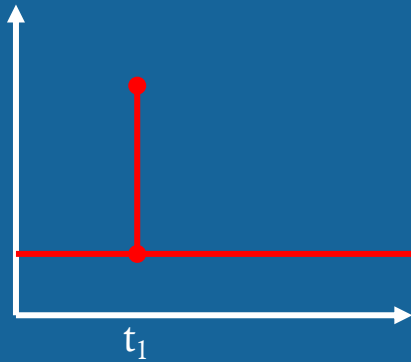
We add τ describing the delay

$$y_1(t) = x(t) \cdot RF(t-\tau)$$

$$y_1(t) = x(0) \cdot RF(t-0)$$

$$y_2(t) = x(5) \cdot RF(t-5)$$

Input functions

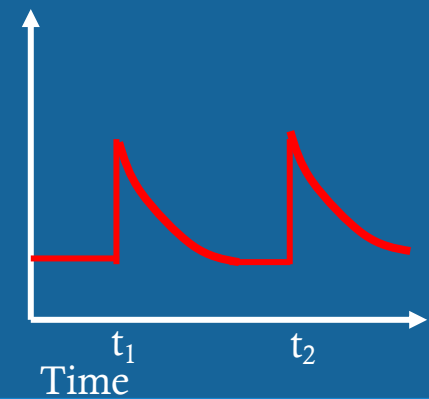
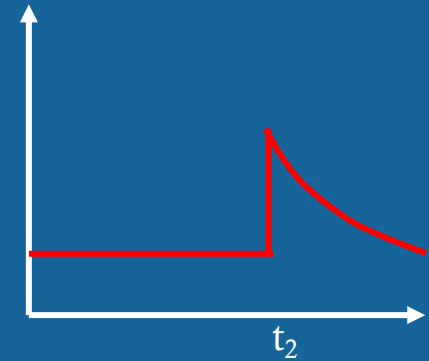
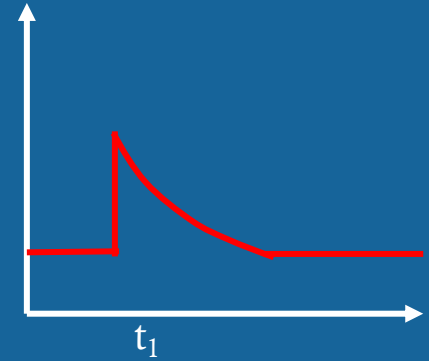


Time invariance of system

Mathematical model

$$\text{RF}(t-\tau)$$

Impulse response function



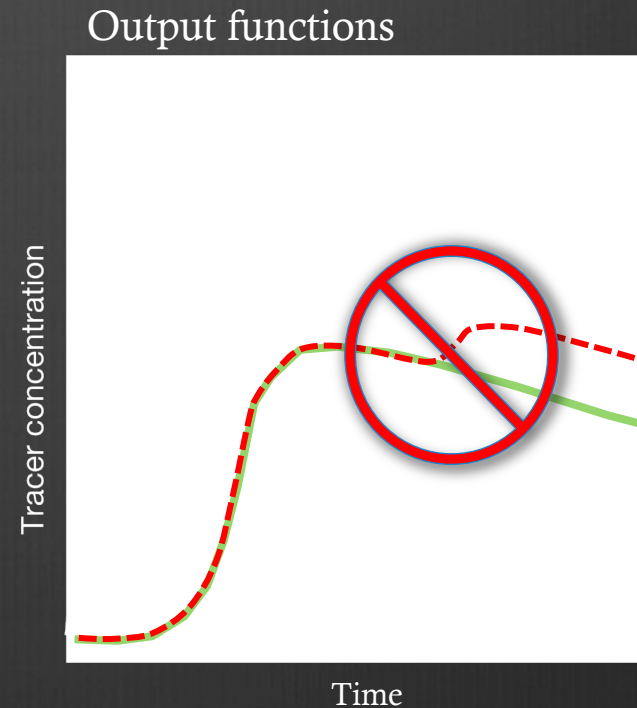
Causality of a system

Output is only observed after an input has enter the system



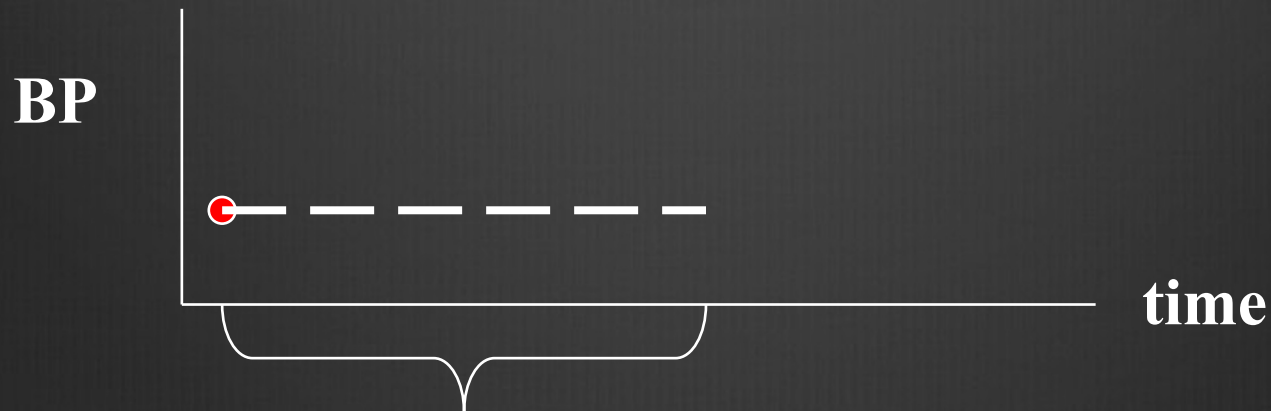
Steady state of the system

- The physiologic parameter is constant during the measurement
- Examples: Blood flow, glucose uptake
- Consider: Duration of the measurement in relation change of parameters



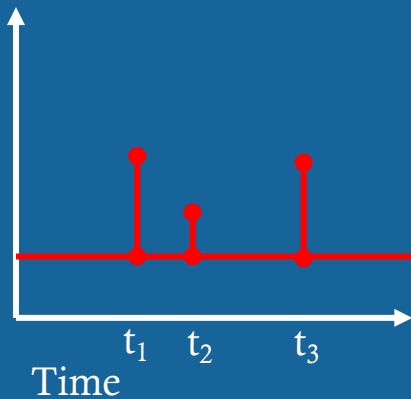
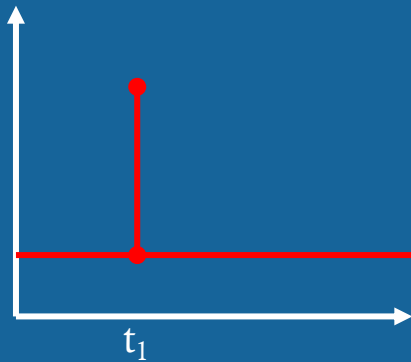
Steady state of the system

- Parameter oscillates fast compared to the duration of the measurement



Linear time-invariant causal steady-state system!

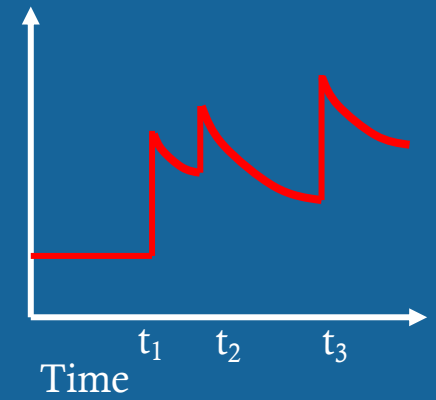
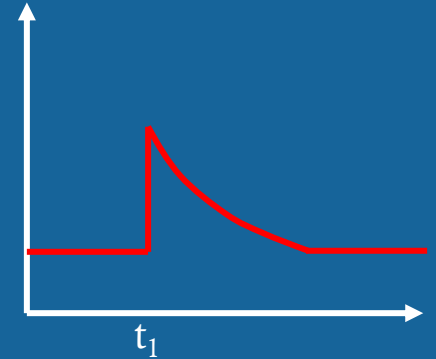
Input functions



Mathematical model

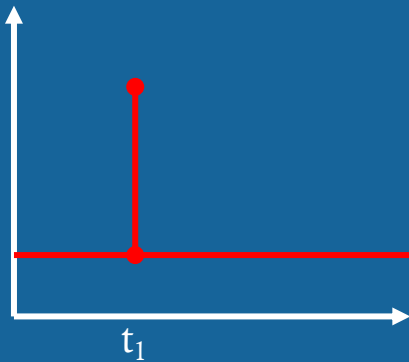
$$RF(t - \tau)$$

Impulse response

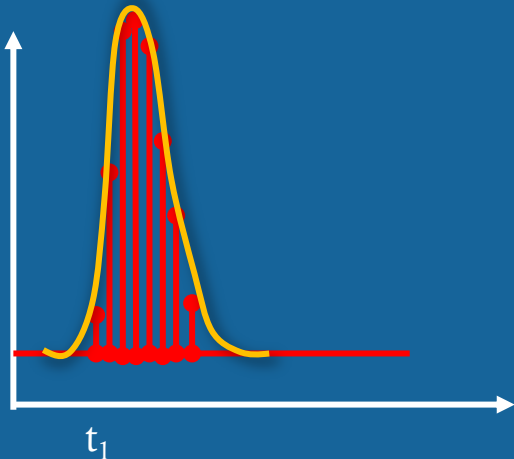


Linear time-invariant causal steady-state system!

Input functions



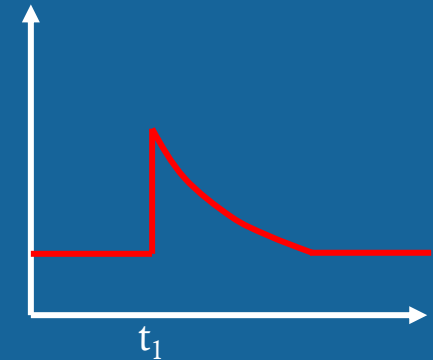
Input functions as series of delta functions



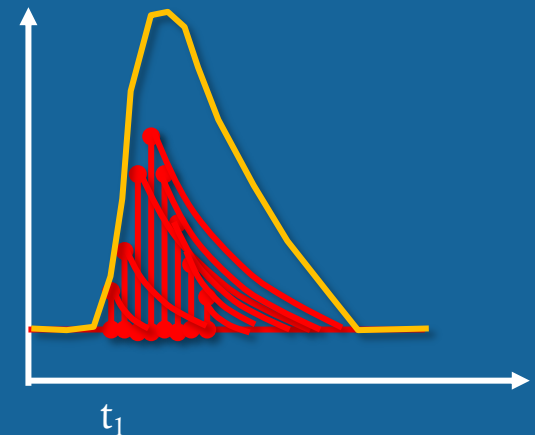
Mathematical model

$$RF(t - \tau)$$

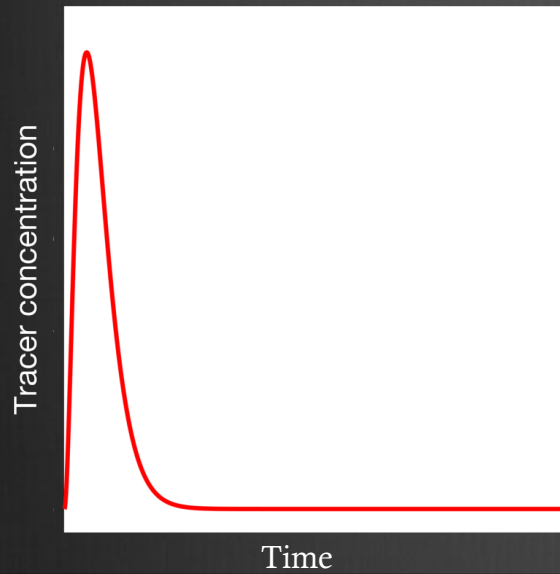
Impulse response



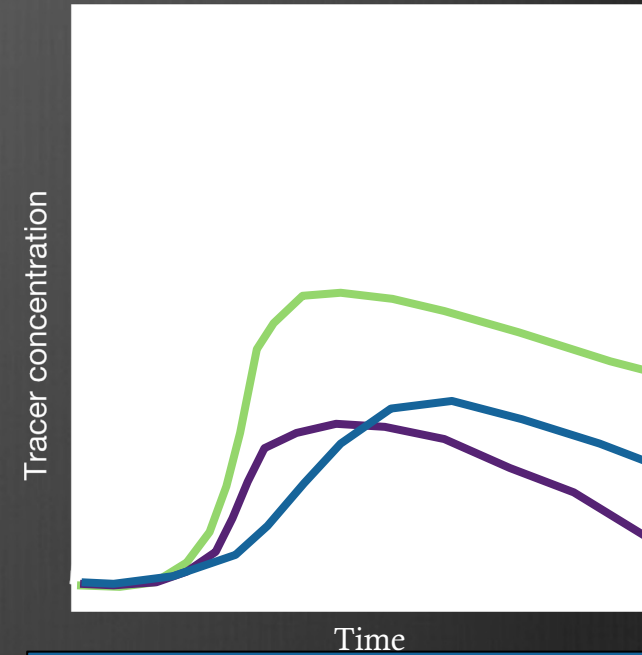
Tissue functions as sum of impulse responses



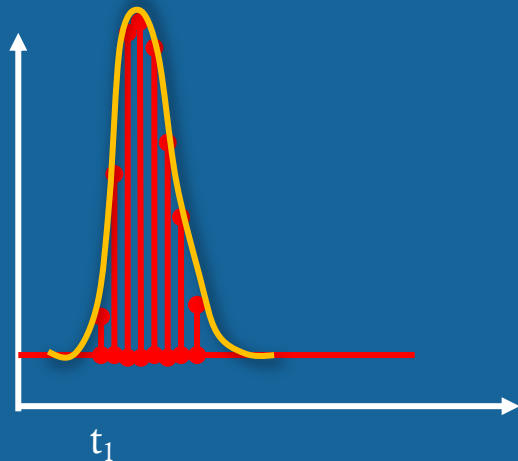
Input function



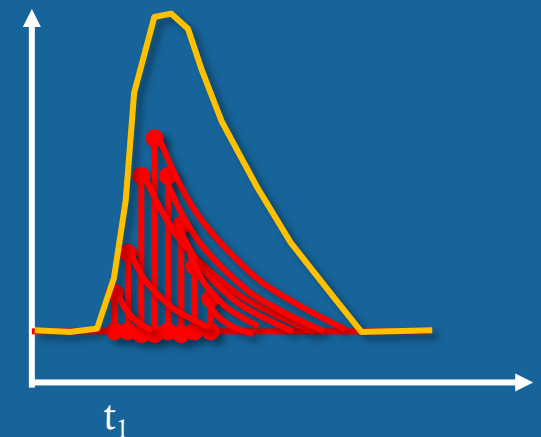
Tissue functions

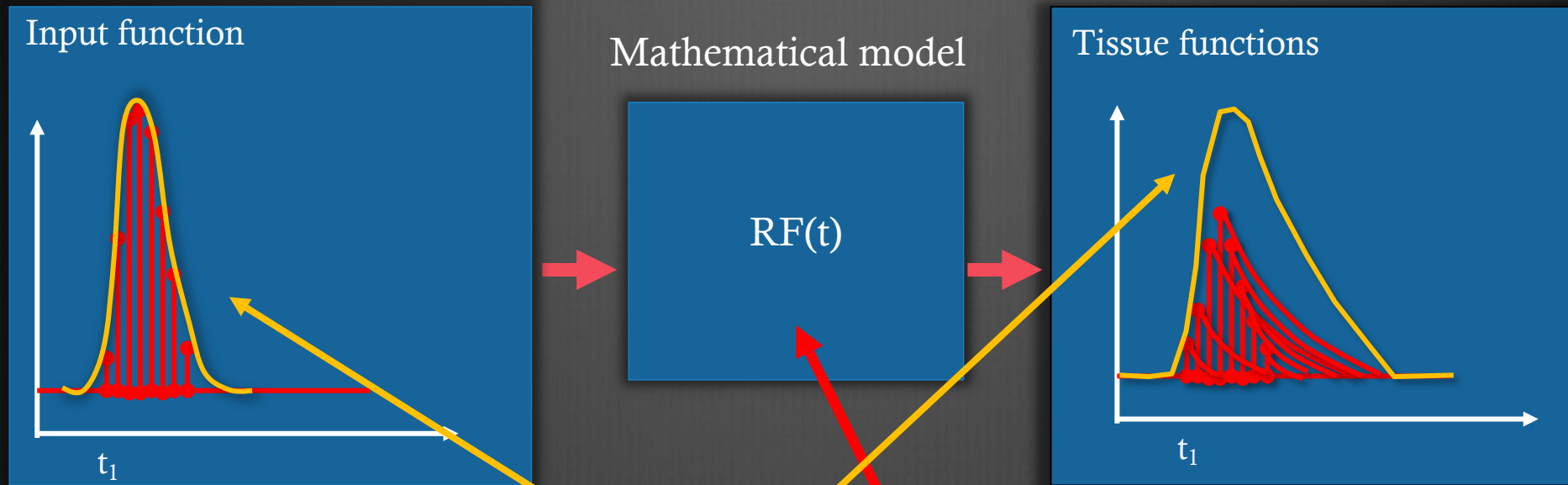


Input functions as series of delta functions



Tissue function as sum of impulse responses





The system can be described by:

$$C_{\text{tissue}}(t) = C_a(t) \otimes RF(t)$$

We measure these two

Convolution

We make an educated guess

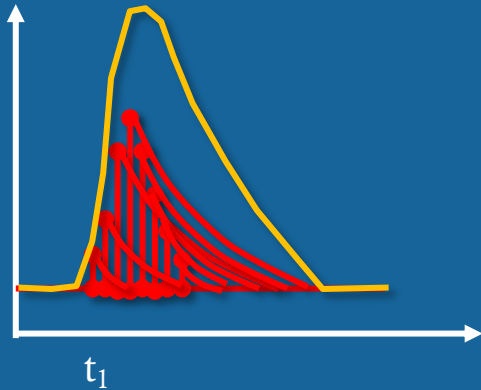
Tracer kinetic modelling is to relate C_a to $C_{\text{tissue}}(t)$ by estimating $RF(t)$

Fundamental tracer kinetic equation

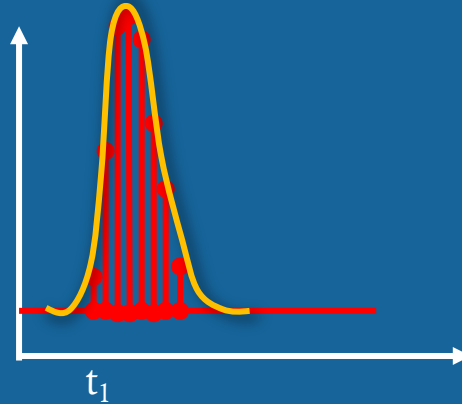
Convolution

$$C_{\text{tissue}}(t) = C_a(t) \otimes \text{RF}(t)$$

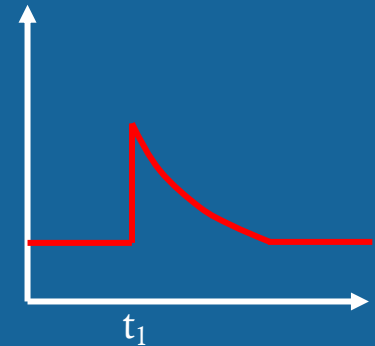
Tissue functions



Input function

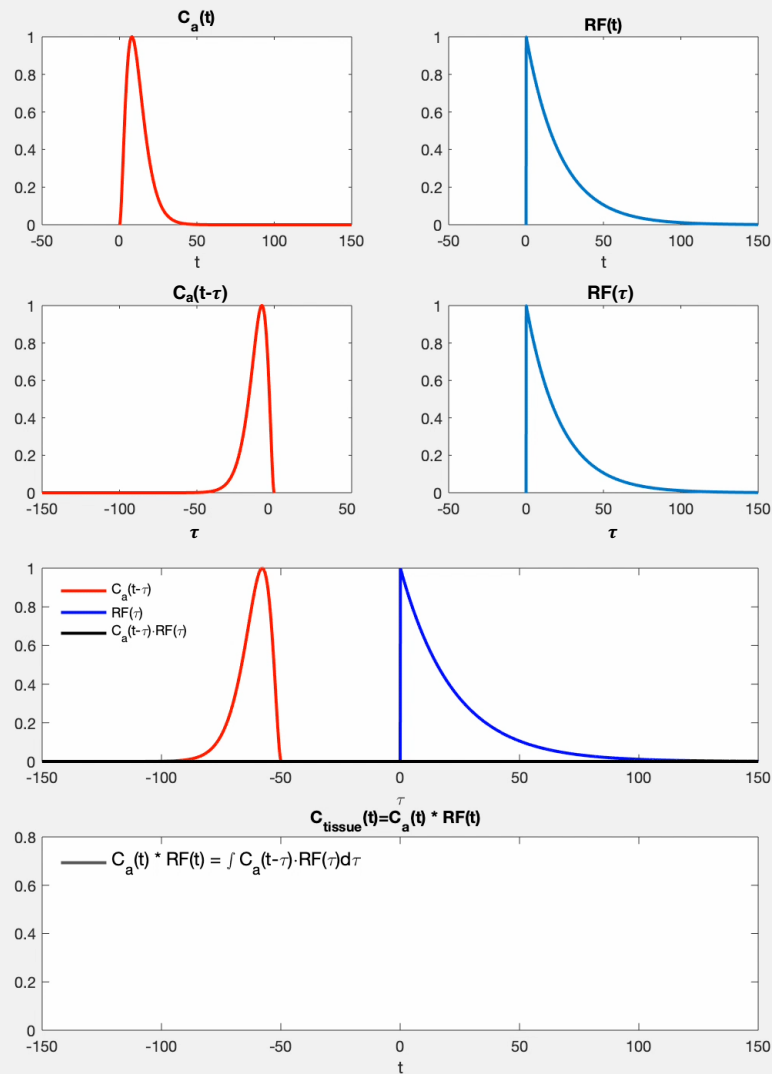


Impulse response function



$$C_{\text{tissue}}(t) = C_a(t) \otimes \text{RF}(t) = \int_{-\infty}^{\infty} C_a(t - \tau) \cdot \text{RF}(\tau) d\tau$$

$$C_{tissue}(t) = C_a(t) \otimes RF(t) = \int_{-\infty}^{\infty} C_a(t - \tau) \cdot RF(\tau) d\tau$$

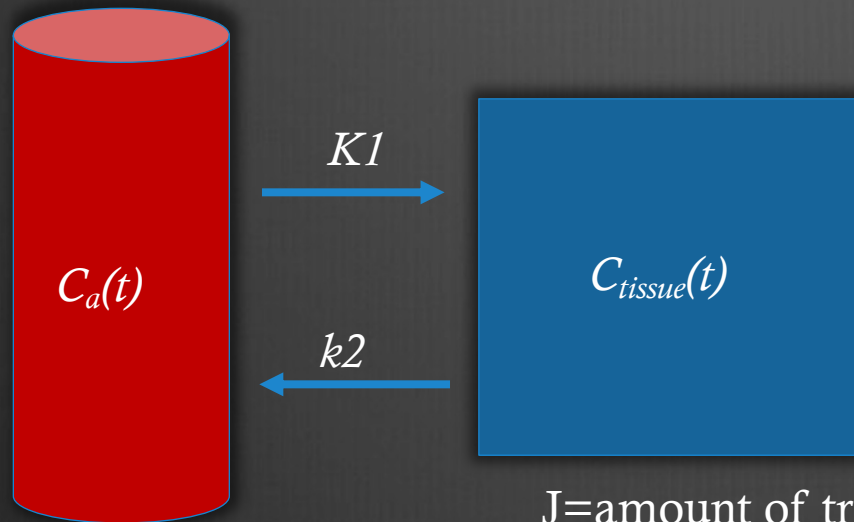


How shall we model $RF(t)$?

- Simple model, one tissue compartment model

How shall we model RF(t)?

- Simple model, one tissue compartment model

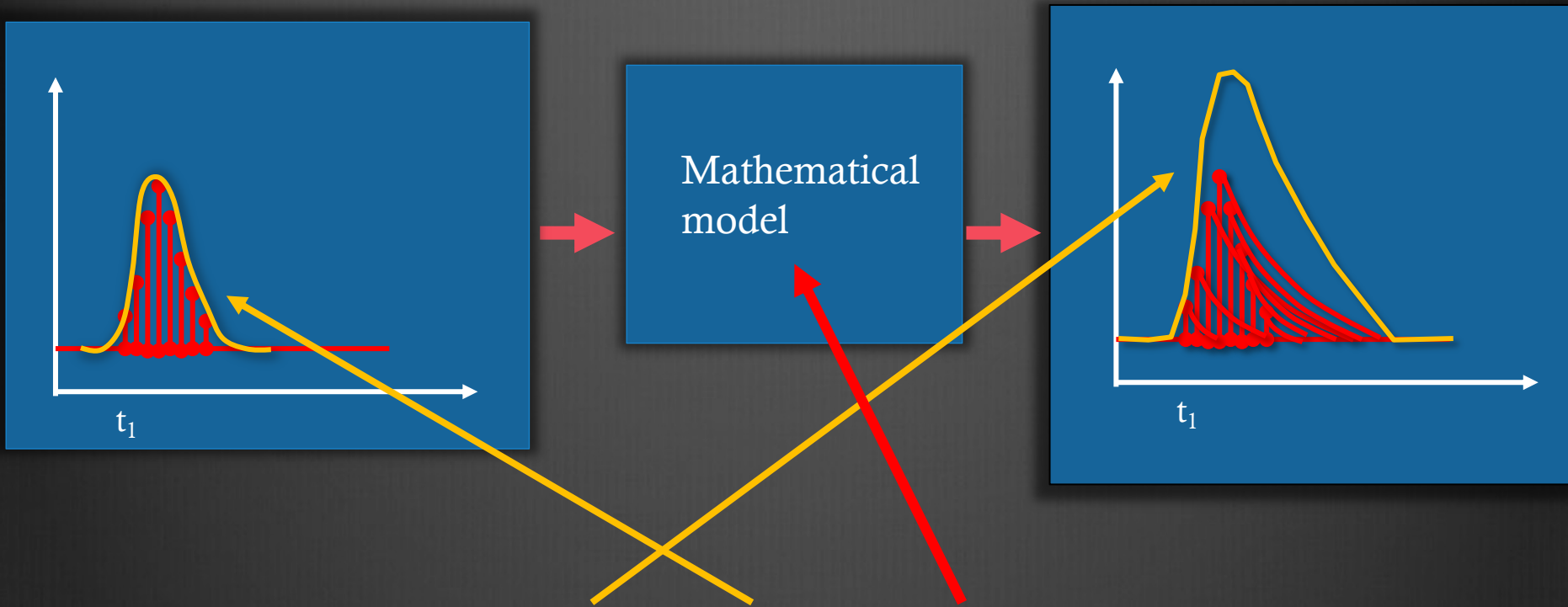


J=amount of tracer going into compartment

$$J = K_1 C_a(t) - k_2 C_{tissue}(t)$$

$$\frac{d}{dt} C_{tissue}(t) = K_1 C_a(t) - k_2 C_{tissue}(t)$$

$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t} \quad \longrightarrow \quad C_{tissue}(t) = C_a(t) \otimes \text{RF}(t)$$

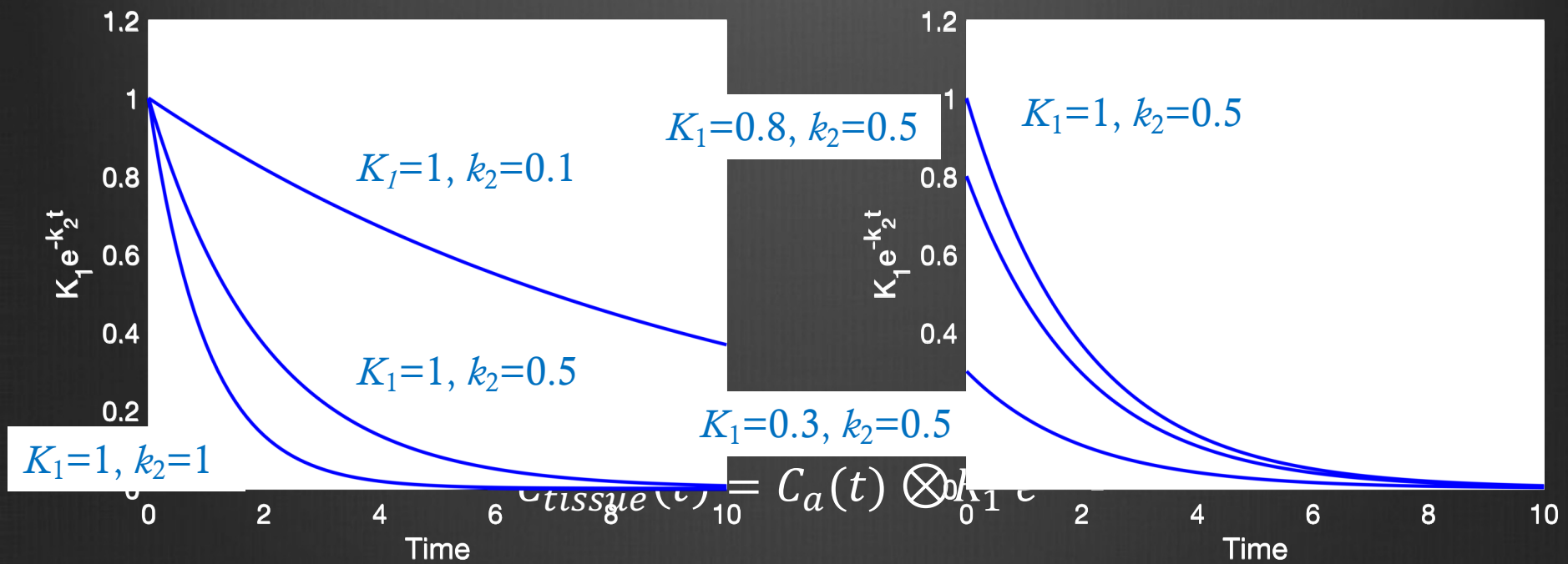


$$C_{\text{tissue}}(t) = C_a(t) \otimes \text{RF}(t)$$

$$C_{\text{tissue}}(t) = C_a(t) \otimes K_1 e^{-k_2 t}$$

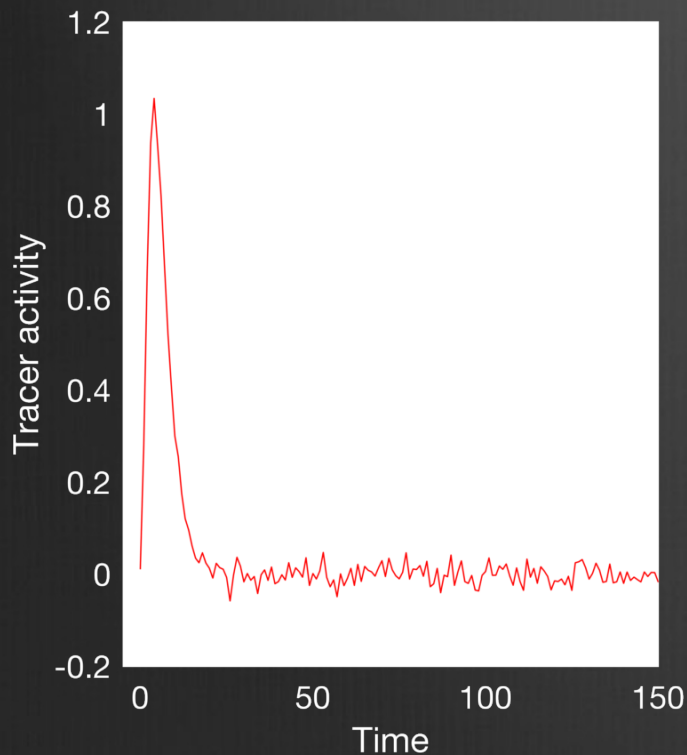
We can “guess” K_1 and k_2 from $C_a(t)$ and $C_{\text{tissue}}(t)$ curves

We use a computer for optimal guess

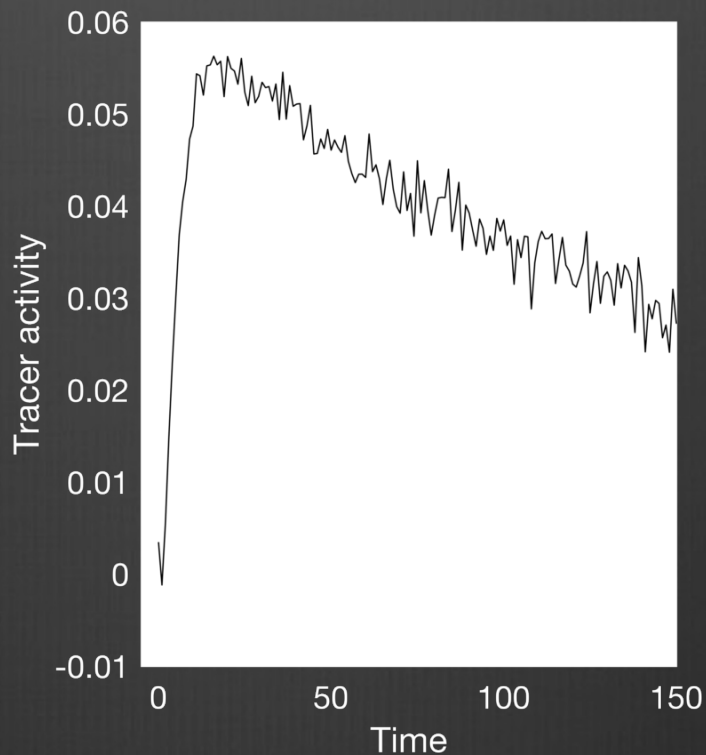


$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t}$$

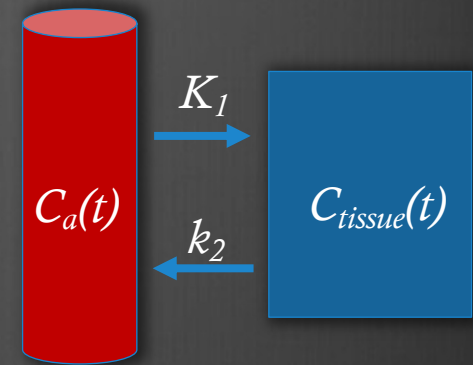
Input function, $C_a(t)$



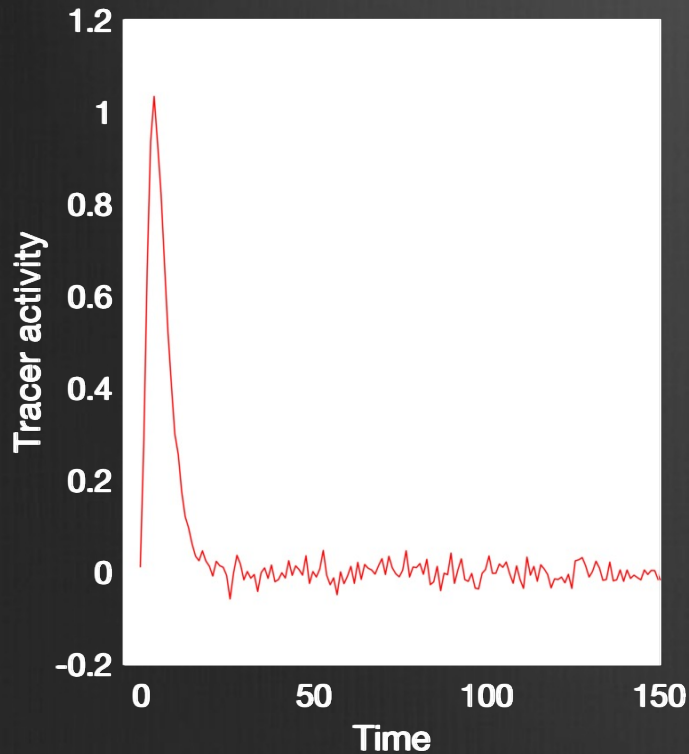
Tissue function, $C_{tissue}(t)$



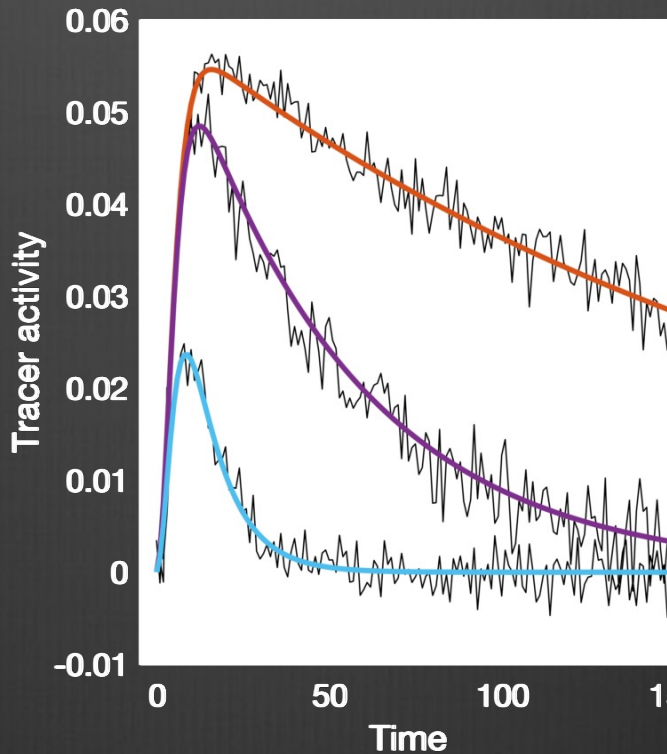
$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t}$$



Input function, $C_a(t)$



Tissue function, $C_{tissue}(t)$



$$C_{tissue}(t) = C_a(t) \otimes 0.95 e^{-0.005 t}$$

$K_1=0.95$
 $k_2=0.005$

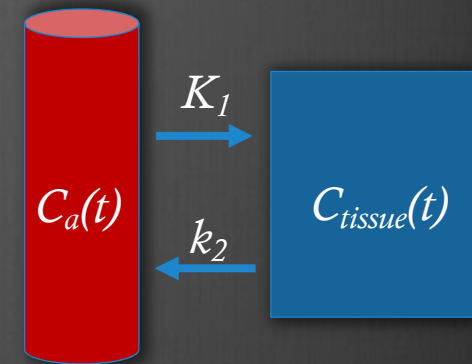
$$C_{tissue}(t) = C_a(t) \otimes 0.95 e^{-0.02 t}$$

$K_1=0.95$
 $k_2=0.02$

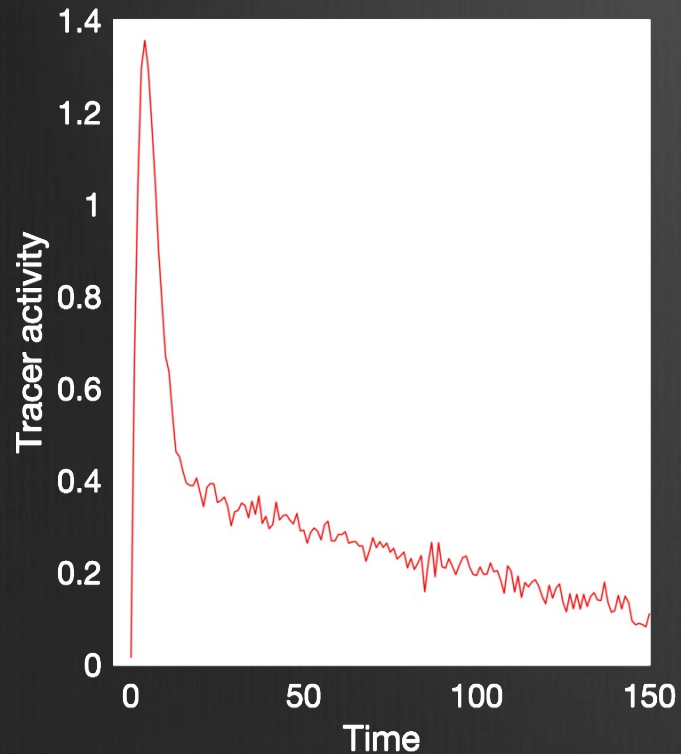
$$C_{tissue}(t) = C_a(t) \otimes 0.6 e^{-0.1 t}$$

$K_1=0.6$
 $k_2=0.1$

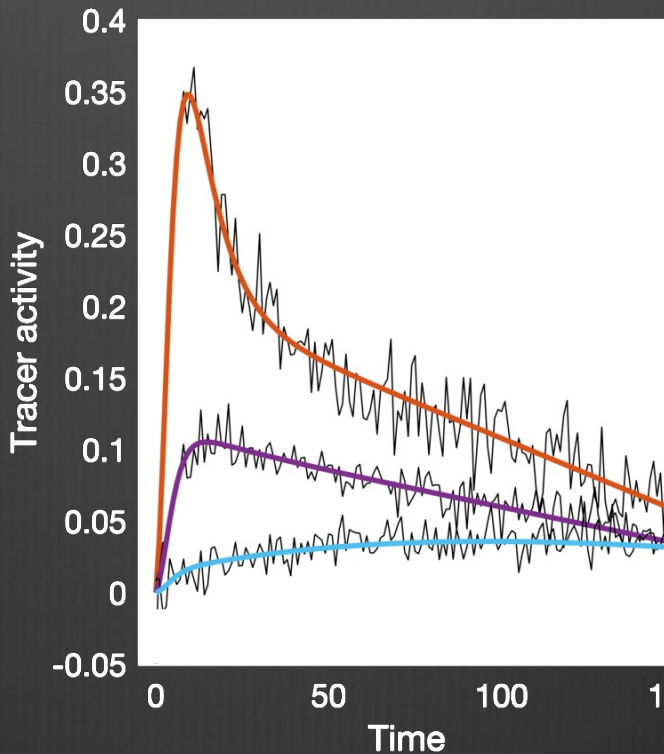
$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t}$$



Input function, $C_a(t)$



Tissue function, $C_{tissue}(t)$



$$C_{tissue}(t) = C_a(t) \otimes 0.5e^{-0.12t}$$

$$K_1=0.5$$

$$k_2=0.12$$

$$C_{tissue}(t) = C_a(t) \otimes 0.25e^{-0.05t}$$

$$K_1=0.25$$

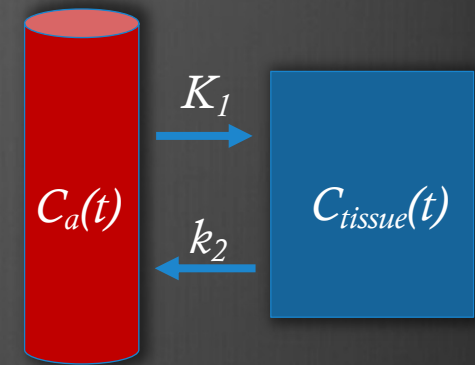
$$k_2=0.05$$

$$C_{tissue}(t) = C_a(t) \otimes 0.15e^{-0.1t}$$

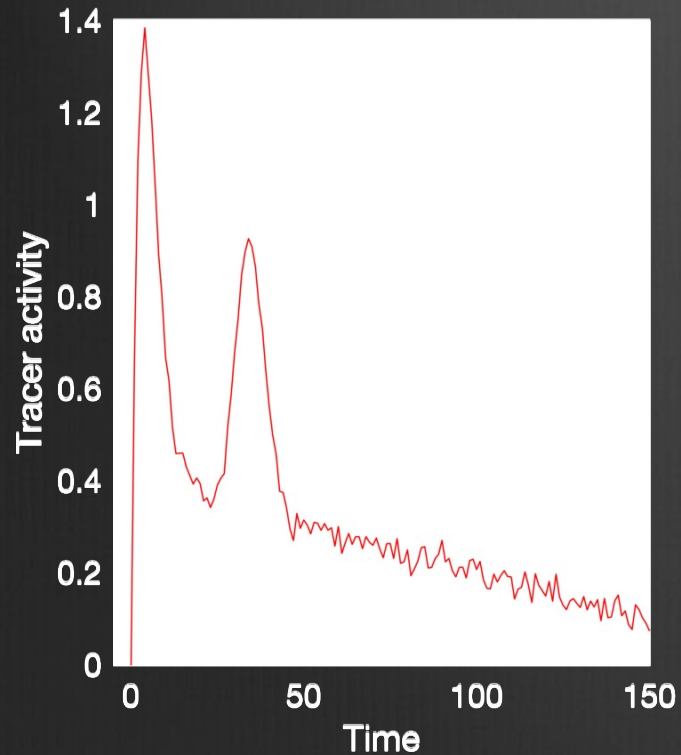
$$K_1=0.15$$

$$k_2=0.01$$

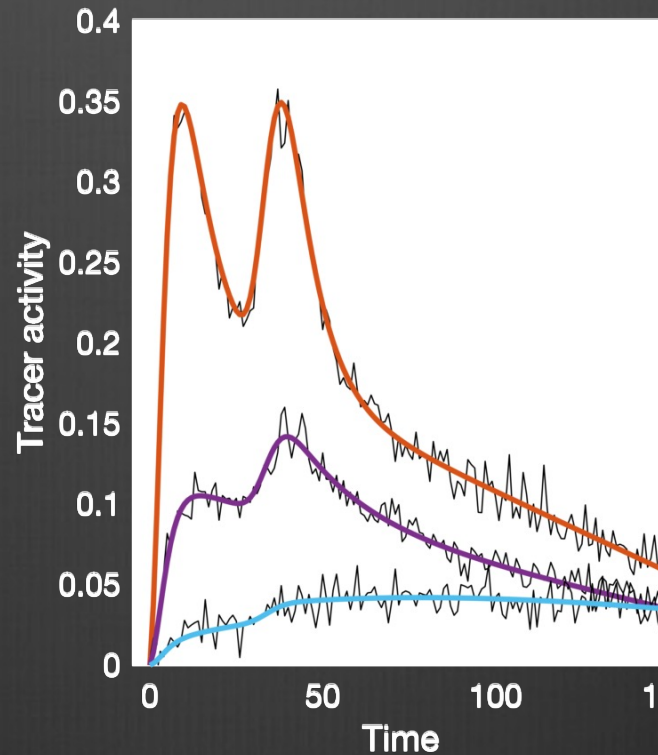
$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t}$$



Input function, $C_a(t)$



Tissue function, $C_{tissue}(t)$



$$C_{tissue}(t) = C_a(t) \otimes 0.5e^{-0.12t}$$

$$K_1=0.5$$

$$k_2=0.12$$

$$C_{tissue}(t) = C_a(t) \otimes 0.25e^{-0.05t}$$

$$K_1=0.25$$

$$k_2=0.05$$

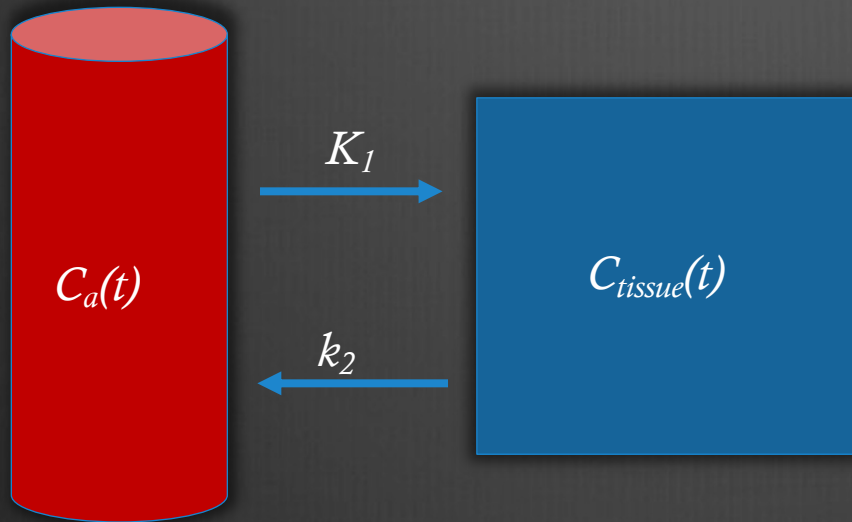
$$C_{tissue}(t) = C_a(t) \otimes 0.15e^{-0.1t}$$

$$K_1=0.15$$

$$k_2=0.01$$

How shall we model RF(t)?

- Simple model, one tissue compartment model

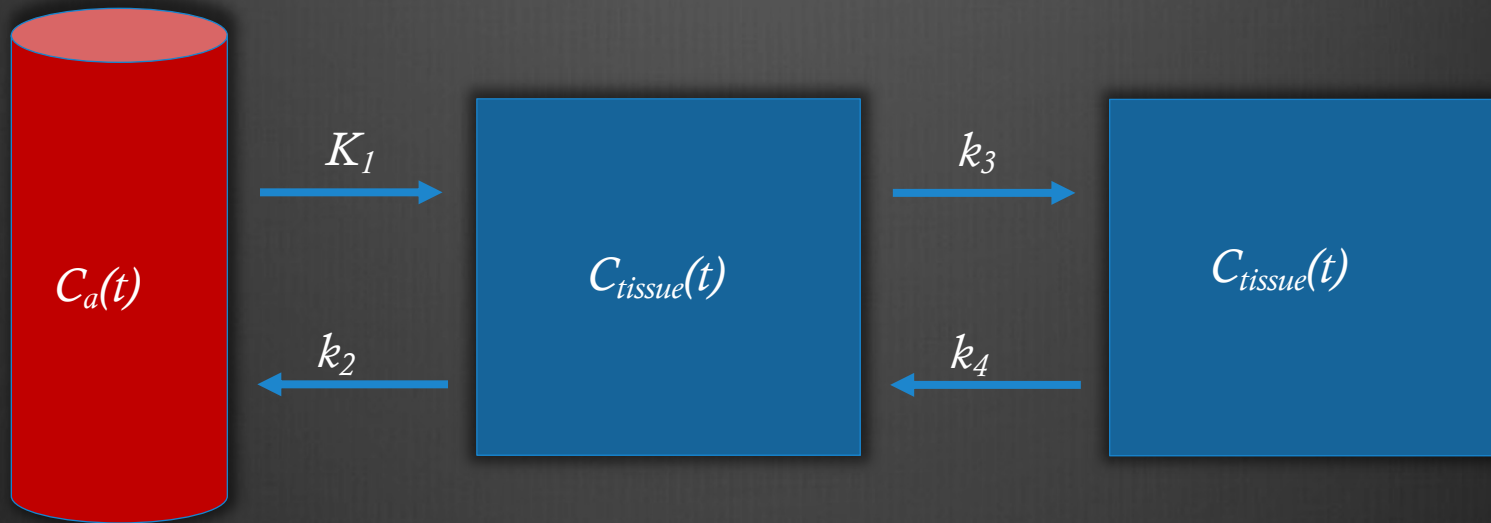


$$\frac{d}{dt}C_{tissue}(t) = K_1 C_a(t) - k_2 C_{tissue}(t)$$

$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t} \quad \longrightarrow \quad C_{tissue}(t) = C_a(t) \otimes \text{RF}(t)$$

How shall we model RF(t)?

- Complex model, two tissue compartment model

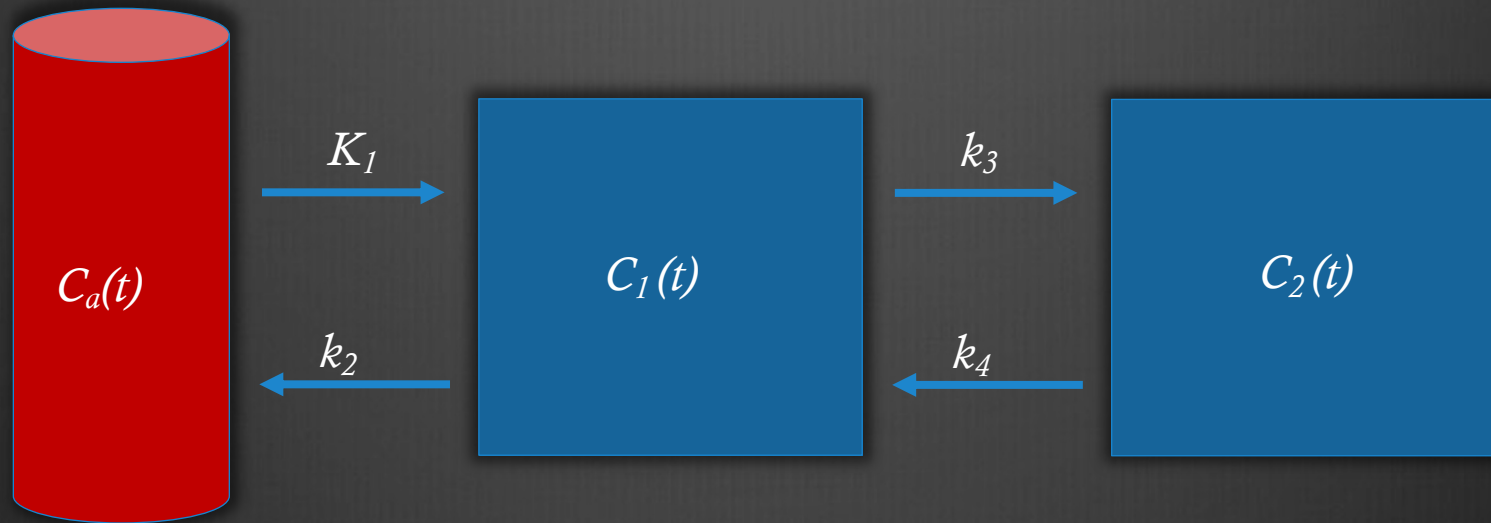


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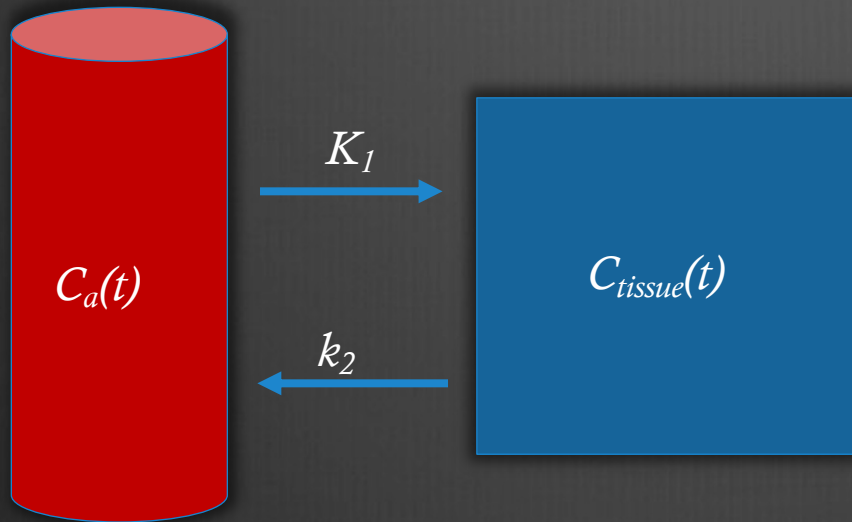


$$\frac{d}{dt}C_1(t) = K_1C_a(t) - (k_2 + k_3)C_1(t) + k_4C_2(t)$$

$$\frac{d}{dt}C_2(t) = K_3C_1(t) - k_4C_2(t)$$

How shall we model RF(t)?

- Simple model, one tissue compartment model

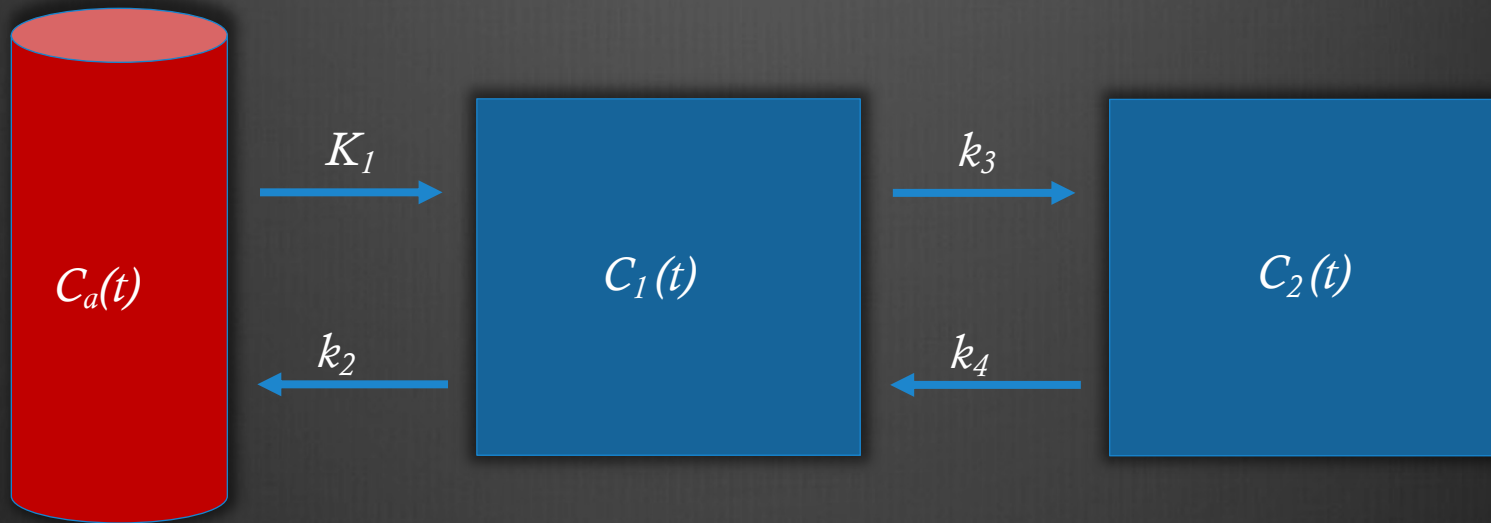


$$\frac{d}{dt}C_{tissue}(t) = K_1 C_a(t) - k_2 C_{tissue}(t)$$

$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t} \quad \longrightarrow \quad C_{tissue}(t) = C_a(t) \otimes \text{RF}(t)$$

How shall we model RF(t)?

- Complex model, two tissue compartment model

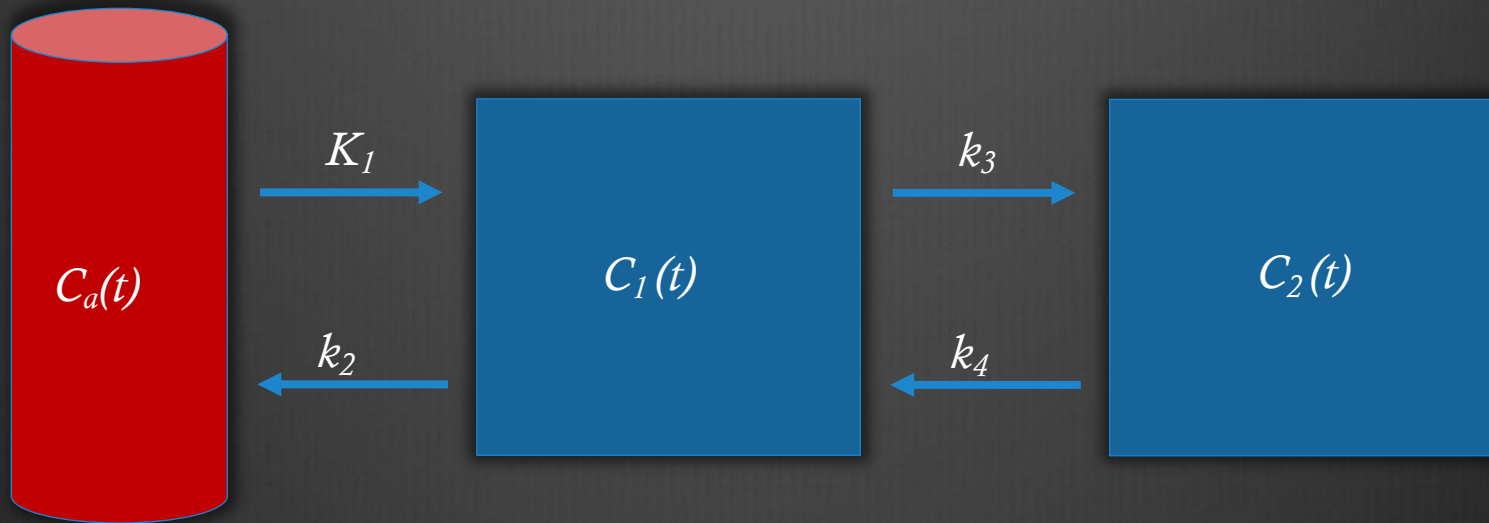


$$\frac{d}{dt}C_1(t) = K_1C_a(t) - (k_2 + k_3)C_1(t) + k_4C_2(t)$$

$$\frac{d}{dt}C_2(t) = K_3C_1(t) - k_4C_2(t)$$

How shall we model RF(t)?

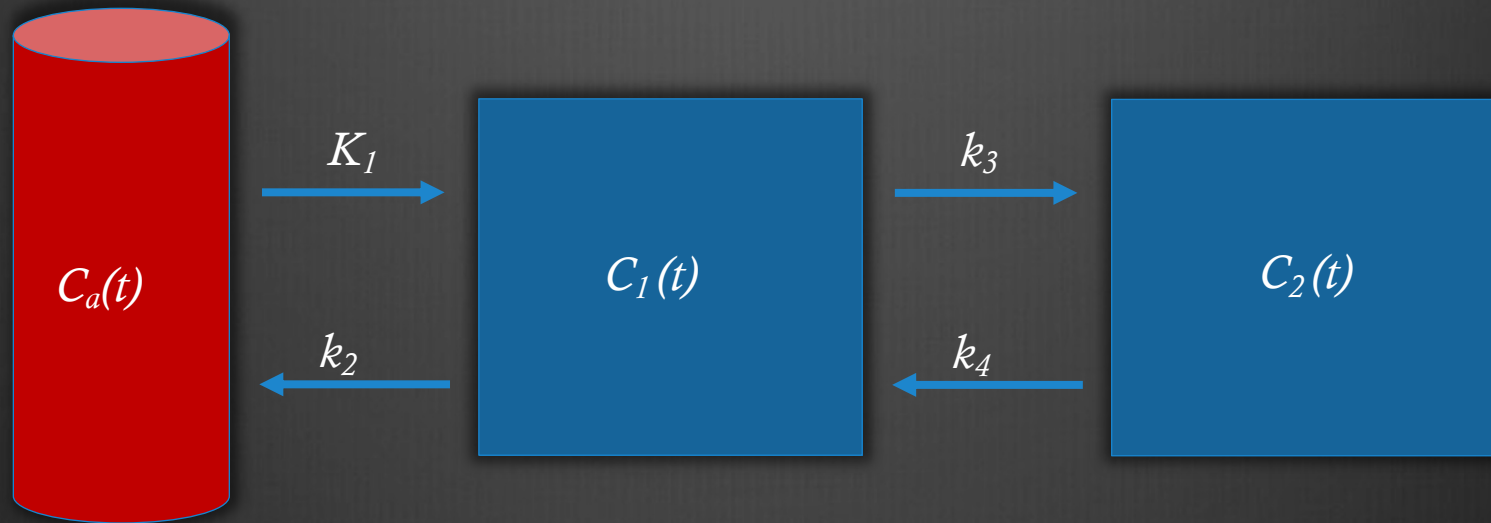
- Complex model, two tissue compartment model



$$C_1 = C_a(t) \otimes \frac{K_1}{\frac{k_2 + k_3 + k_4 + \sqrt{(k_2 + k_3 + k_4)^2 - 4k_2k_4}}{2} - \frac{k_2 + k_3 + k_4 - \sqrt{(k_2 + k_3 + k_4)^2 - 4k_2k_4}}{2}} * \left[\left(K_4 - \frac{k_2 + k_3 + k_4 - \sqrt{(k_2 + k_3 + k_4)^2 - 4k_2k_4}}{2} \right) e^{-t * \frac{k_2 + k_3 + k_4 - \sqrt{(k_2 + k_3 + k_4)^2 - 4k_2k_4}}{2}} + \left(\frac{k_2 + k_3 + k_4 - \sqrt{(k_2 + k_3 + k_4)^2 - 4k_2k_4}}{2} - K_4 \right) e^{-t * \frac{k_2 + k_3 + k_4 + \sqrt{(k_2 + k_3 + k_4)^2 - 4k_2k_4}}{2}} \right]$$

How shall we model RF(t)?

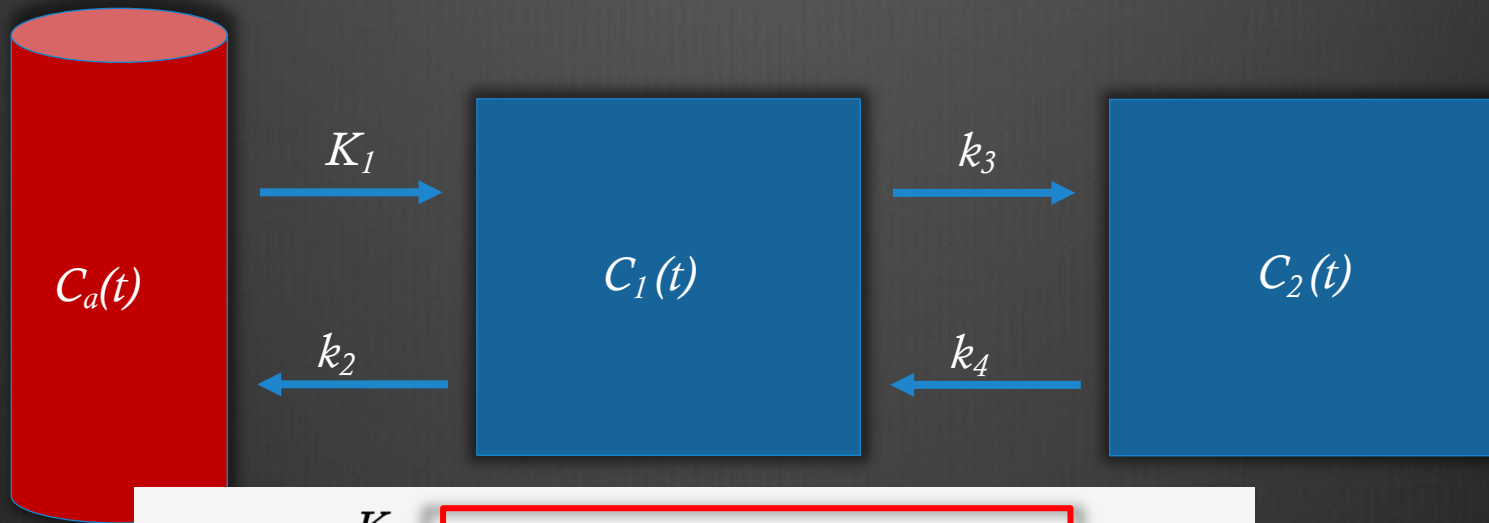
- Complex model, two tissue compartment model



$$C_2 = C_a(t) \otimes \frac{K_1 K_3}{\frac{k_2 + k_3 + k_4 + \sqrt{(k_2 + k_3 + k_4)^2 - 4k_2 k_4}}{2} - \frac{k_2 + k_3 + k_4 - \sqrt{(k_2 + k_3 + k_4)^2 - 4k_2 k_4}}{2}} * \left[e^{-t * \frac{k_2 + k_3 + k_4 - \sqrt{(k_2 + k_3 + k_4)^2 - 4k_2 k_4}}{2}} - e^{-t * \frac{k_2 + k_3 + k_4 + \sqrt{(k_2 + k_3 + k_4)^2 - 4k_2 k_4}}{2}} \right]$$

How shall we model RF(t)?

- Complex model, two tissue compartment model



$$C_1(t) = \frac{K_1}{\alpha_2 - \alpha_1} [(k_4 - \alpha_1)e^{-\alpha_1 t} + (\alpha_2 - k_4)e^{-\alpha_2 t}] \otimes C_0(t)$$

$$C_2(t) = \frac{K_1 k_3}{\alpha_2 - \alpha_1} [e^{-\alpha_1 t} - e^{-\alpha_2 t}] \otimes C_0(t)$$

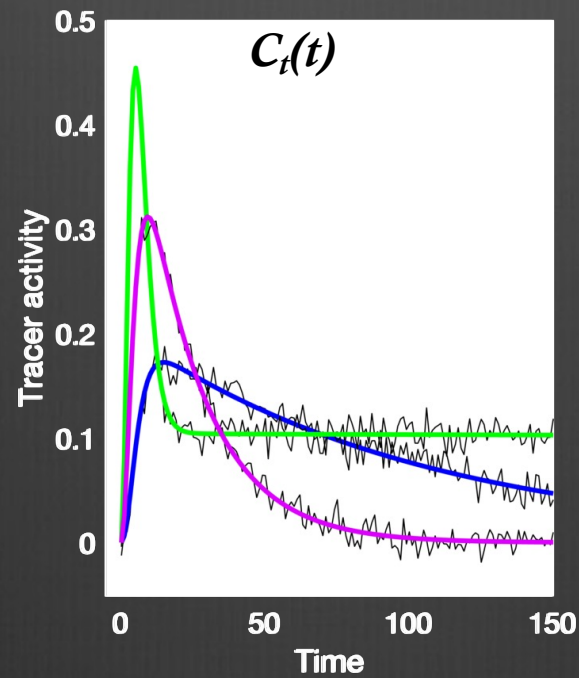
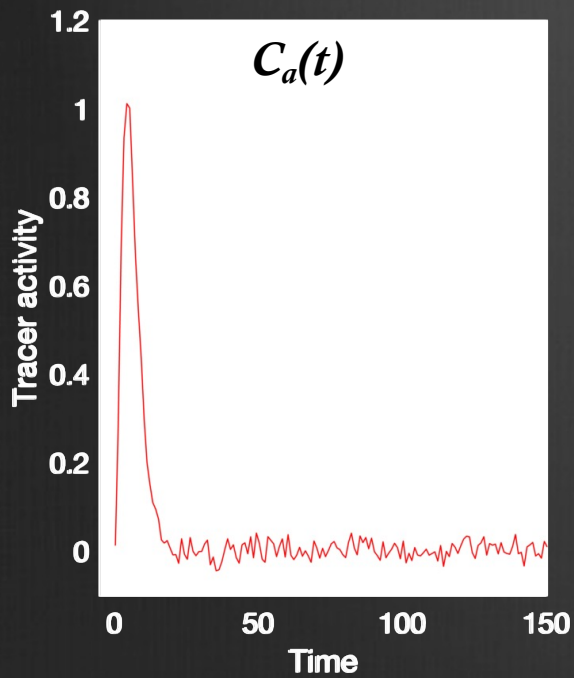
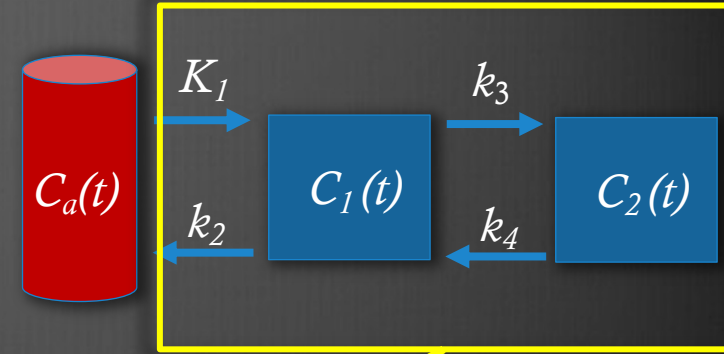
, where

$$\alpha_1 = \frac{k_2 + k_3 + k_4 - \sqrt{(k_2 + k_3 + k_4)^2 - 4k_2 k_4}}{2}$$

$$\alpha_2 = \frac{k_2 + k_3 + k_4 + \sqrt{(k_2 + k_3 + k_4)^2 - 4k_2 k_4}}{2}$$

$$\frac{d}{dt}C_1(t) = K_1C_a(t) - (k_2 + k_3)C_1(t) + k_4C_2(t)$$

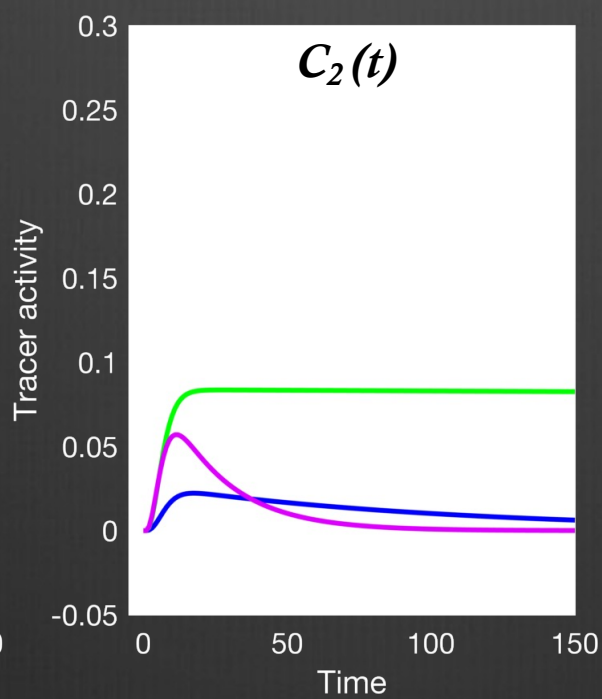
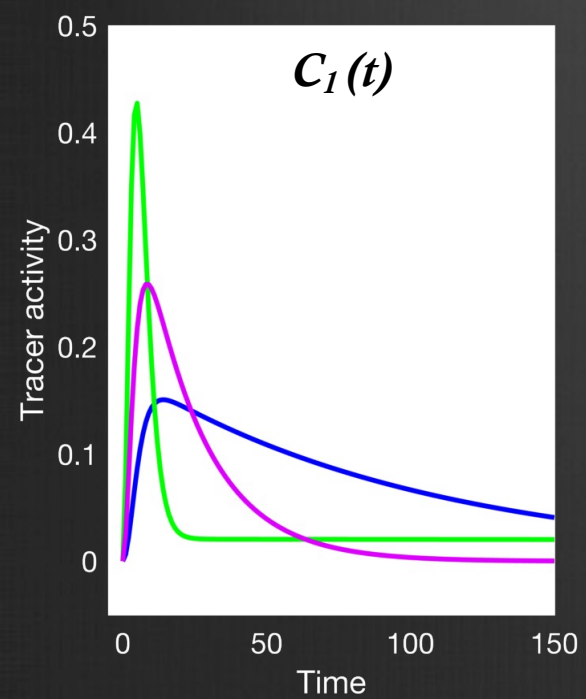
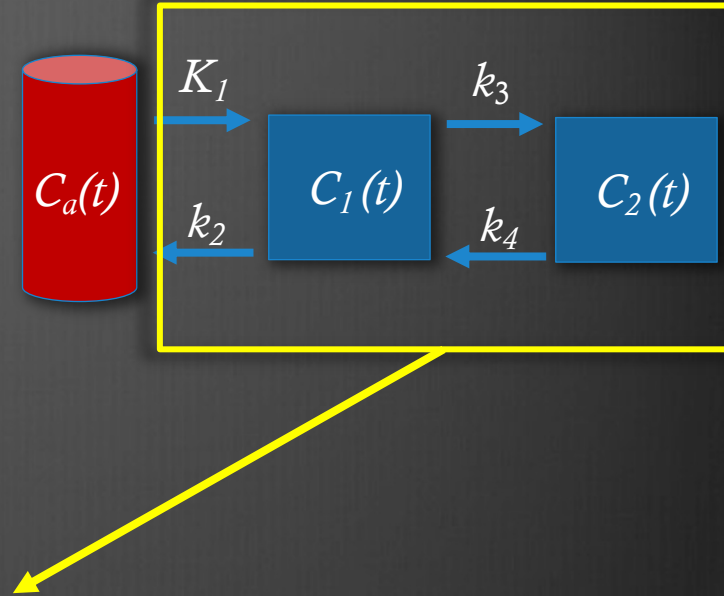
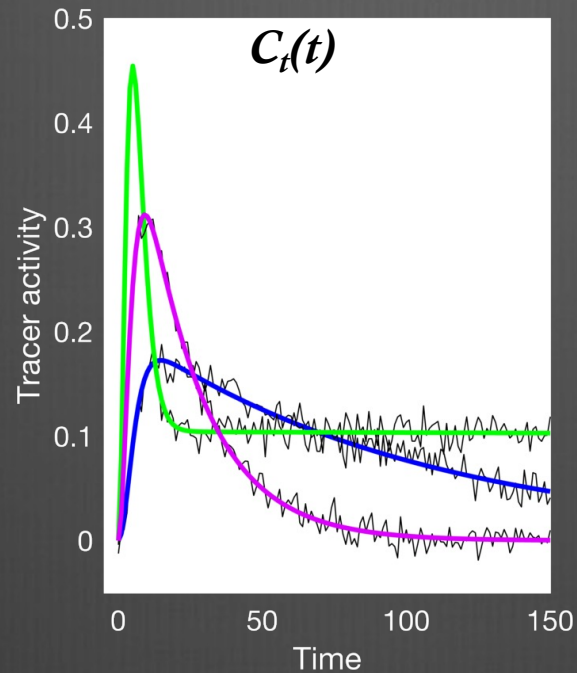
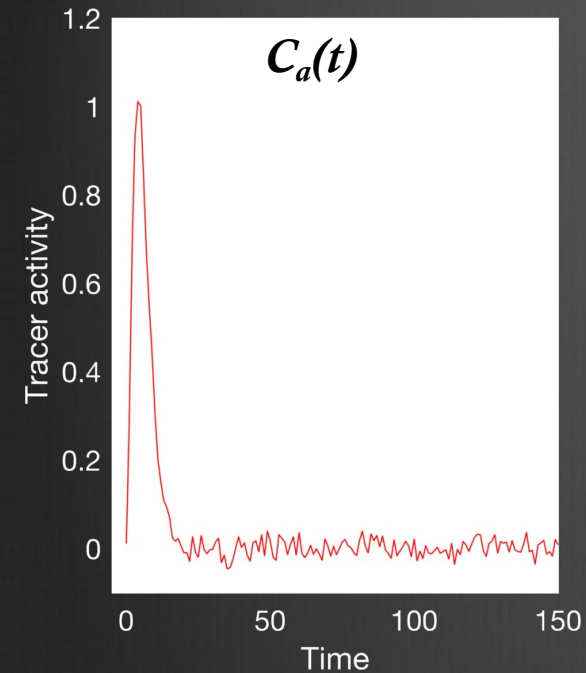
$$\frac{d}{dt}C_2(t) = K_3C_1(t) - k_4C_2(t)$$



$K_1=1$
 $k_2=0.01$
 $k_3=1$
 $k_4=0.01$

$K_1=0.5$
 $k_2=0.01$
 $k_3=0.01$
 $k_4=0.5$

$K_1=1$
 $k_2=0.1$
 $k_3=0.8$
 $k_4=0.8$

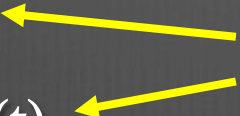


$K_1=1$
 $k_2=0.01$
 $k_3=1$
 $k_4=0.01$

$K_1=0.5$
 $k_2=0.01$
 $k_3=0.01$
 $k_4=0.5$

$K_1=1$
 $k_2=0.1$
 $k_3=0.8$
 $k_4=0.8$

Summary

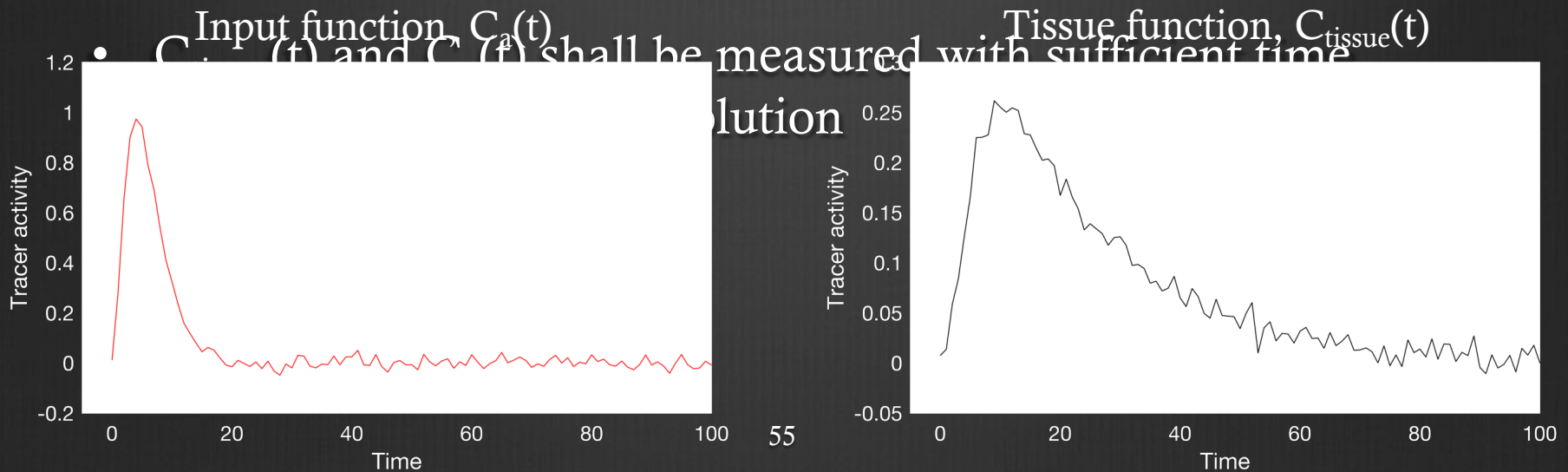
- Input function, $C_a(t)$
 - Tissue function, $C_{\text{tissue}}(t)$
 - The input function is related to tissue function by modelling
 - The input function and tissue functions is related by the impulse reponse function of the system
- We measure $C_a(t)$ and $C_{\text{tissue}}(t)$**
- 

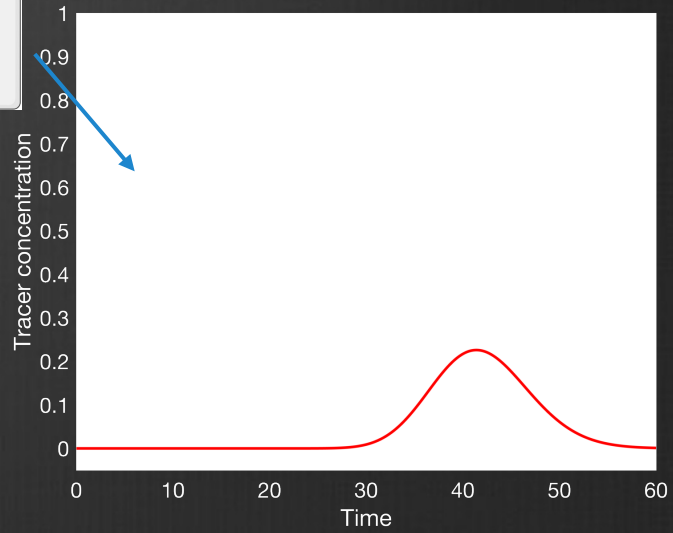
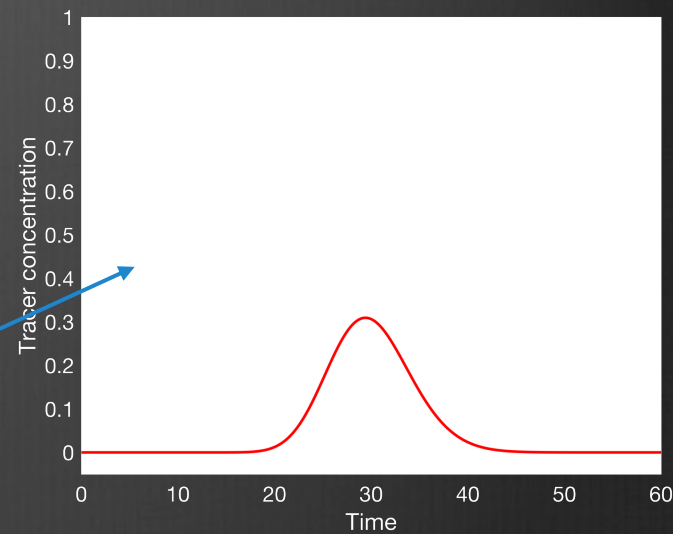
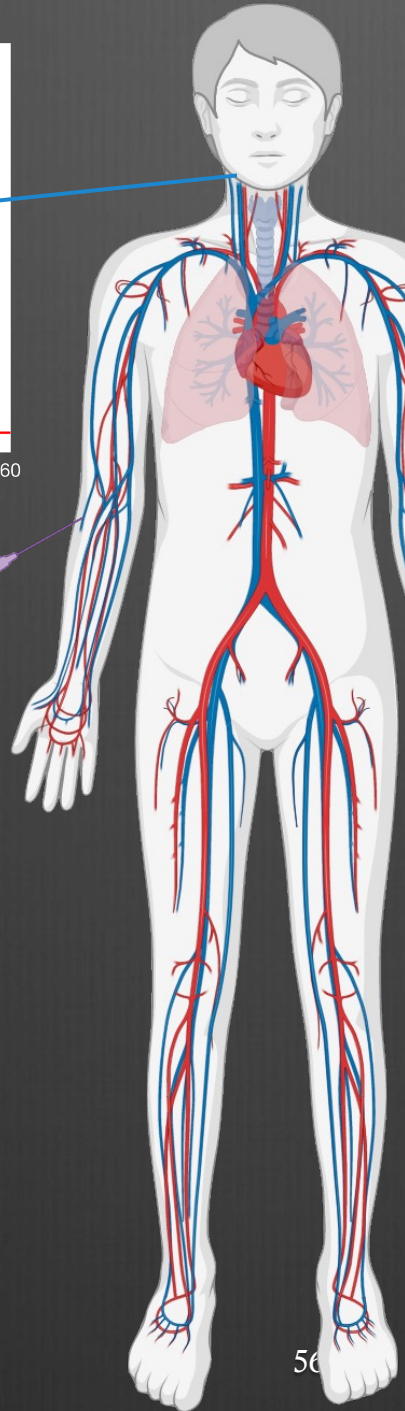
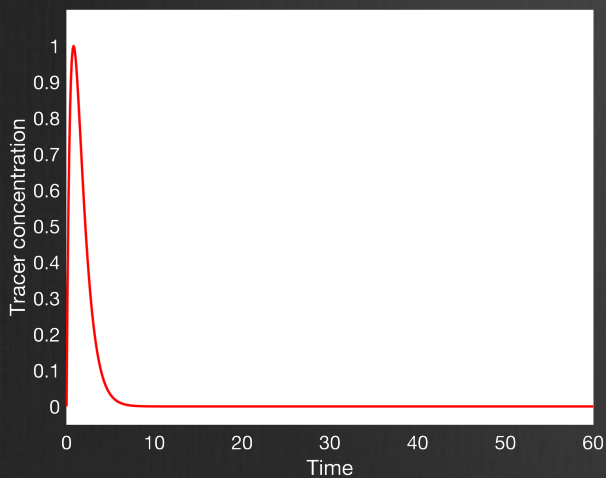
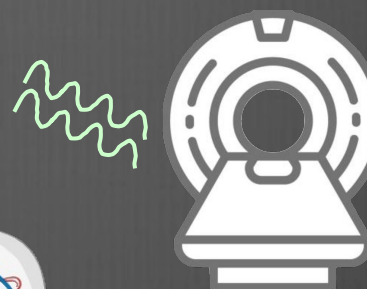
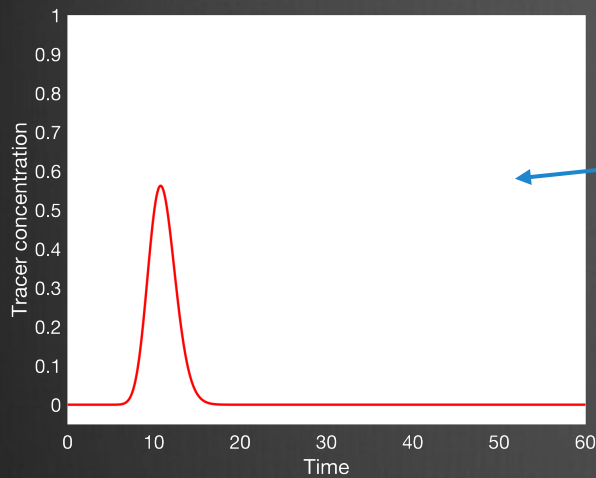
$$C_{\text{tissue}}(t) = C_a(t) \otimes \text{RF}(t)$$

- We model the impulse response function of the system
 - Compartment model
 - Choose most simple but correct model
 - The parameters used to fit the model can be related to physiology

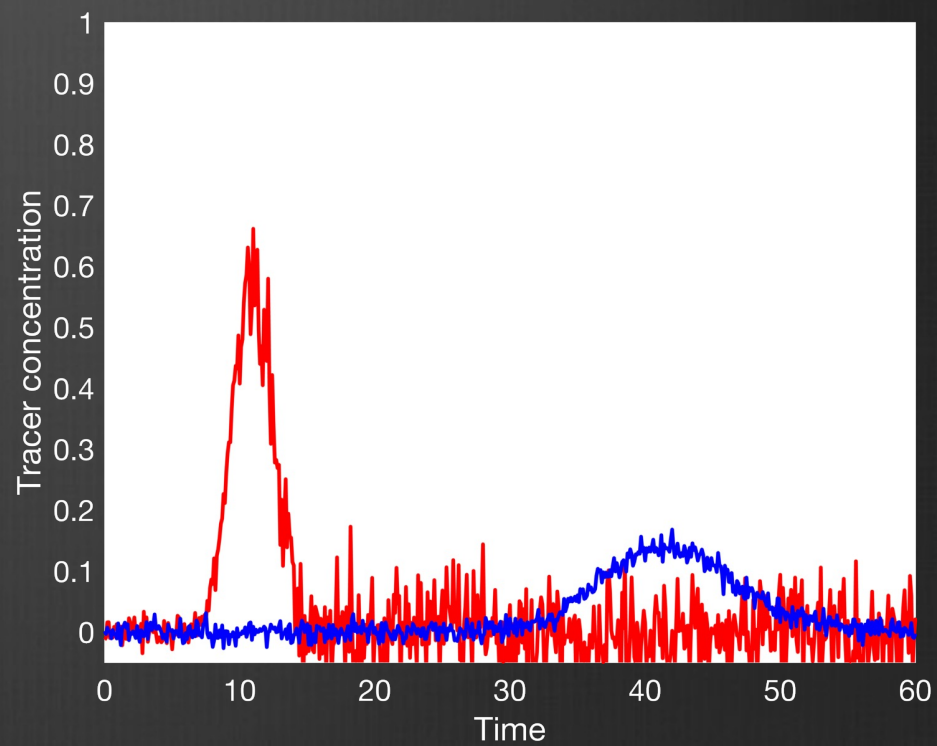
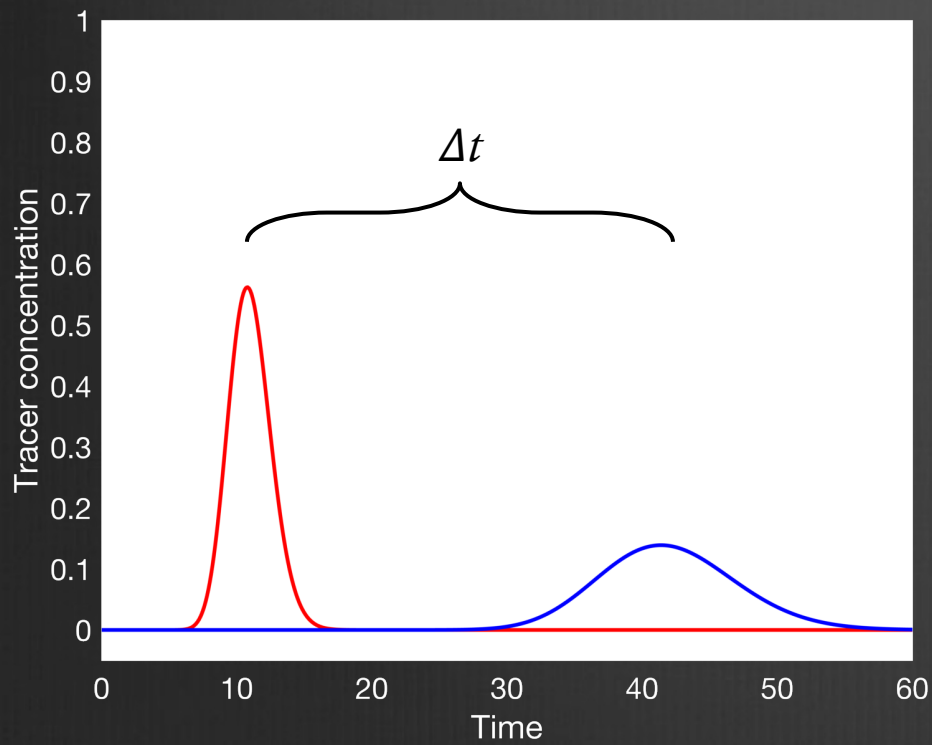
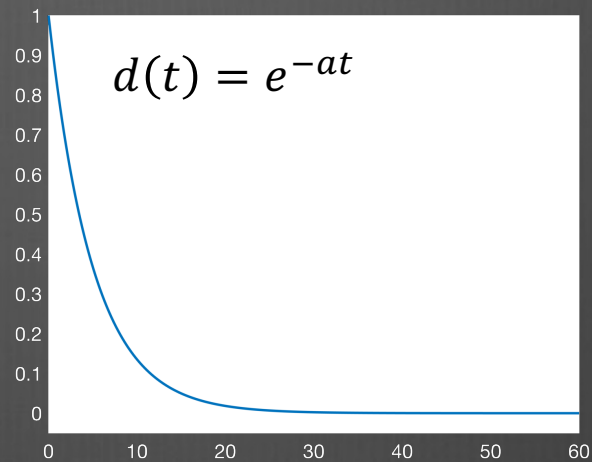
Tracer functions

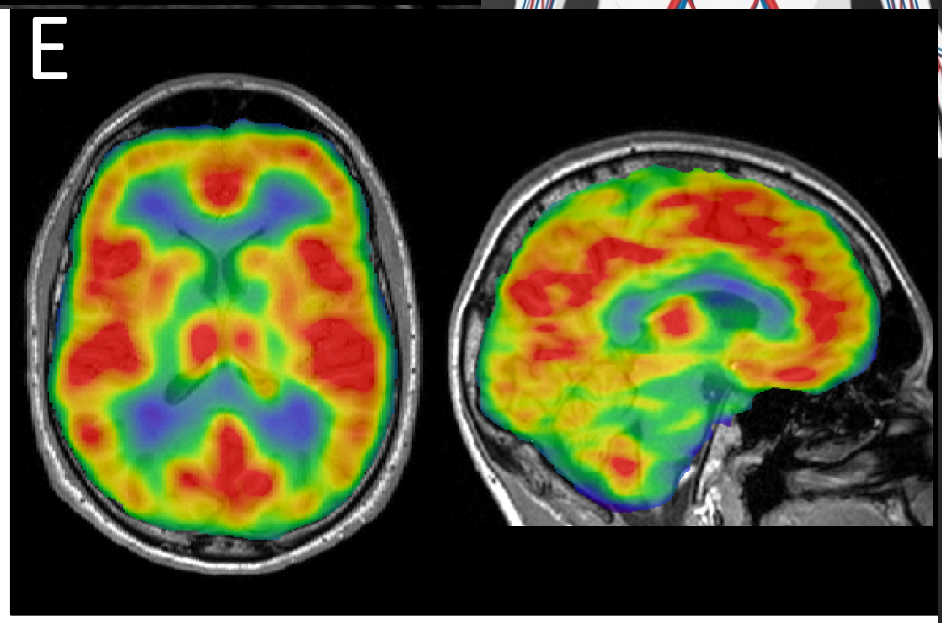
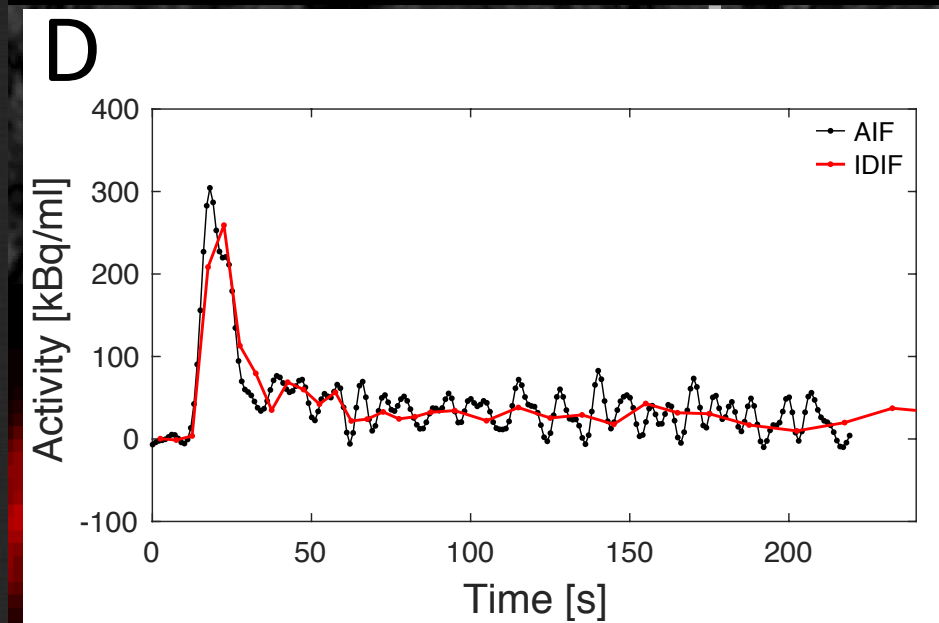
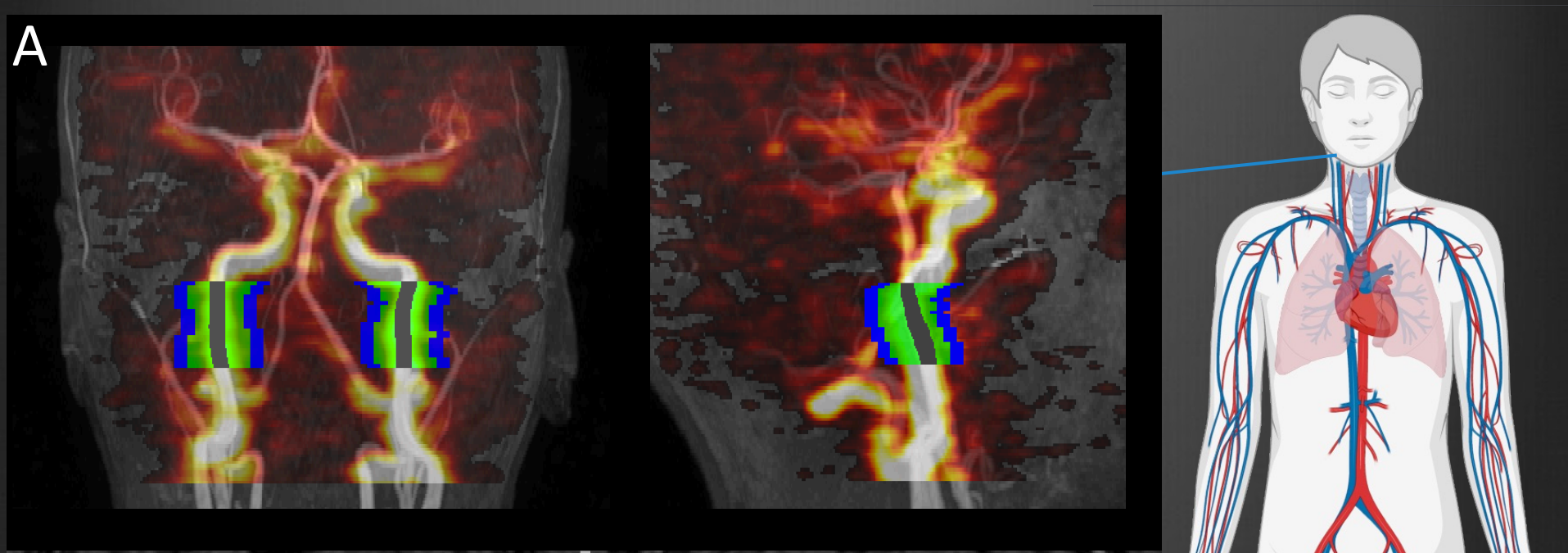
- $C_{\text{tissue}}(t)$
 - Scanners
- $C_a(t)$
 - Scanners, image-derived input function
 - Blood sampling
- $C_{\text{tissue}}(t)$ and $C_a(t)$ must be in same units or same reference

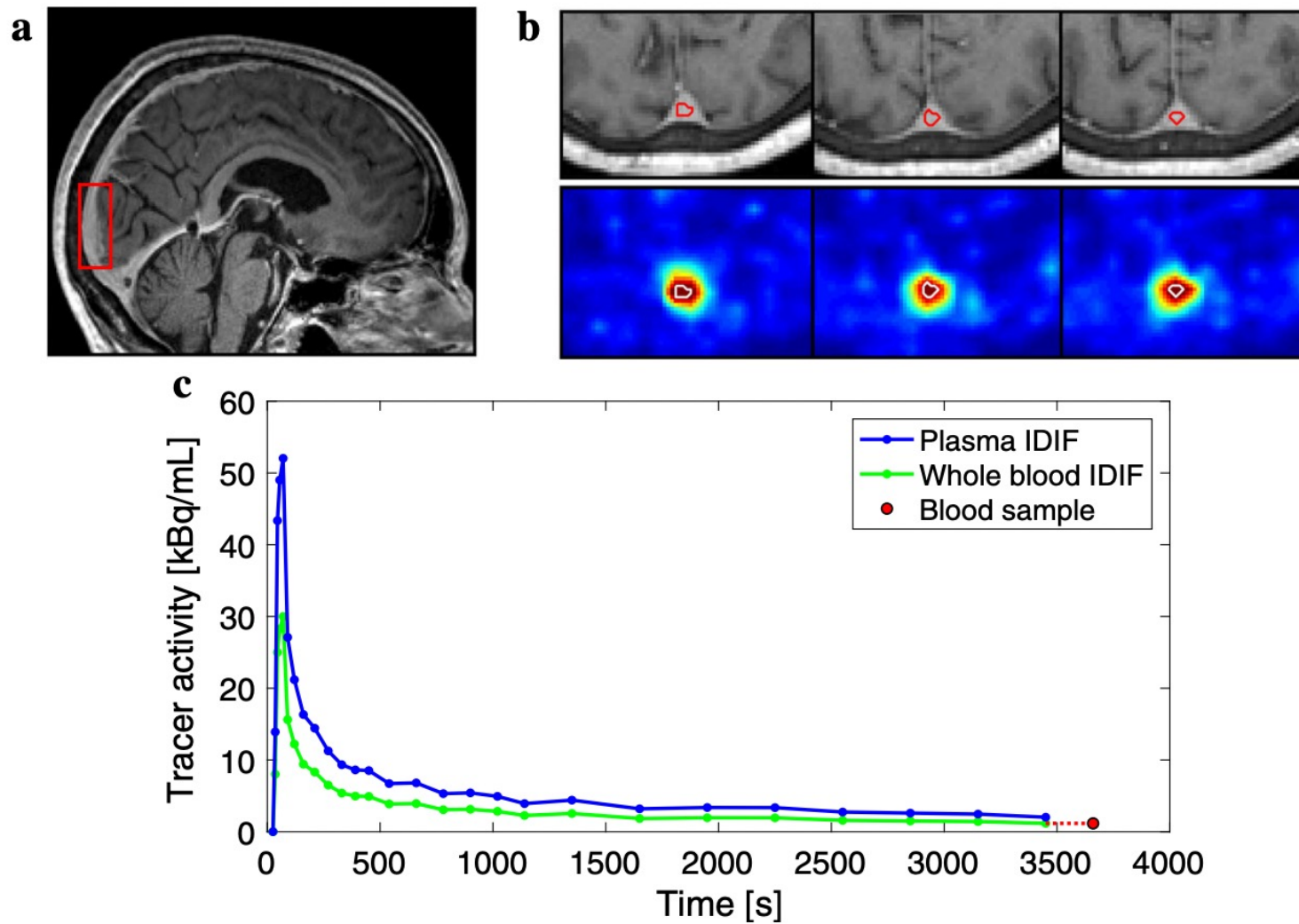


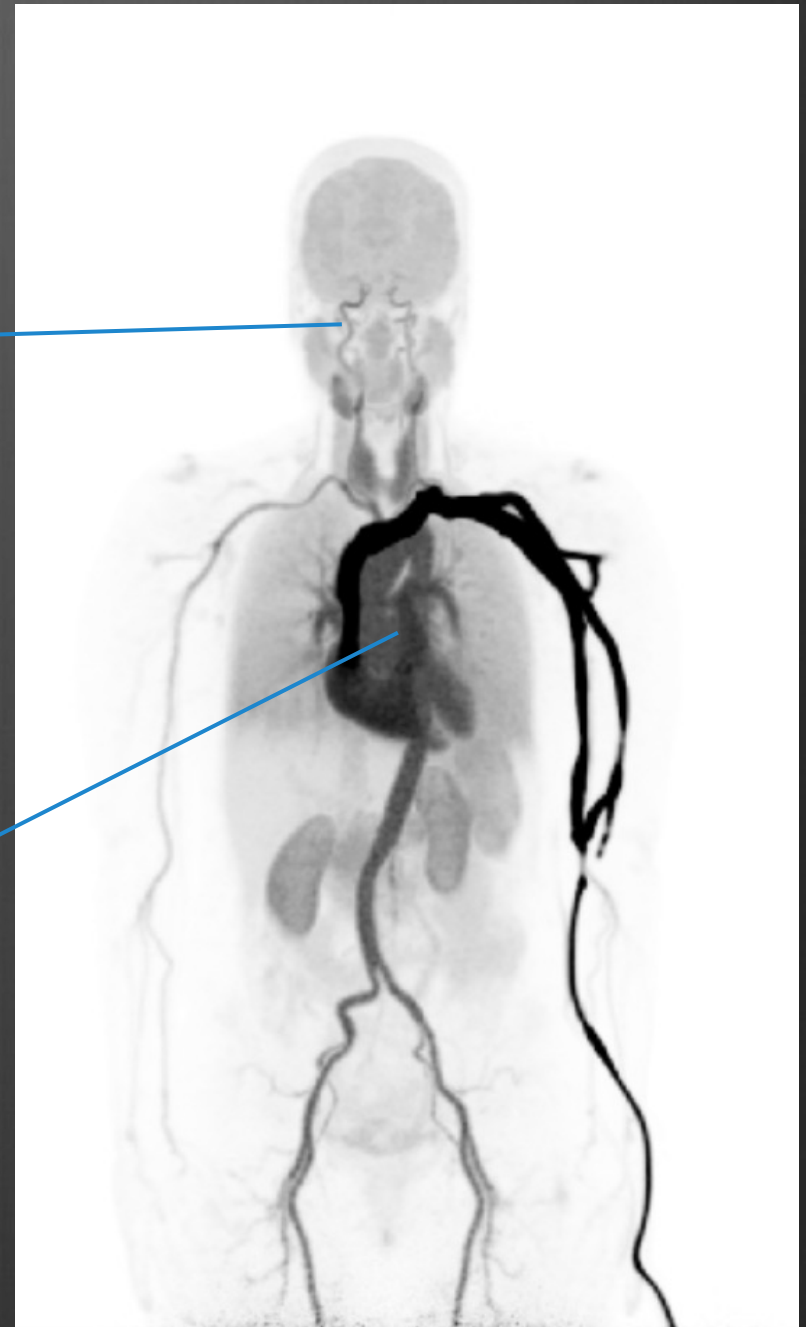
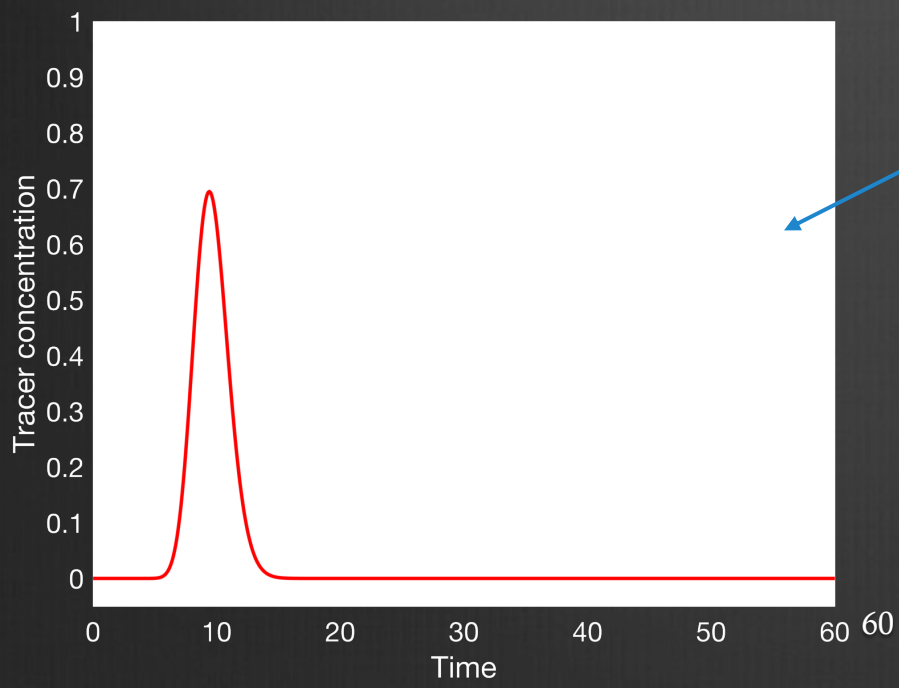
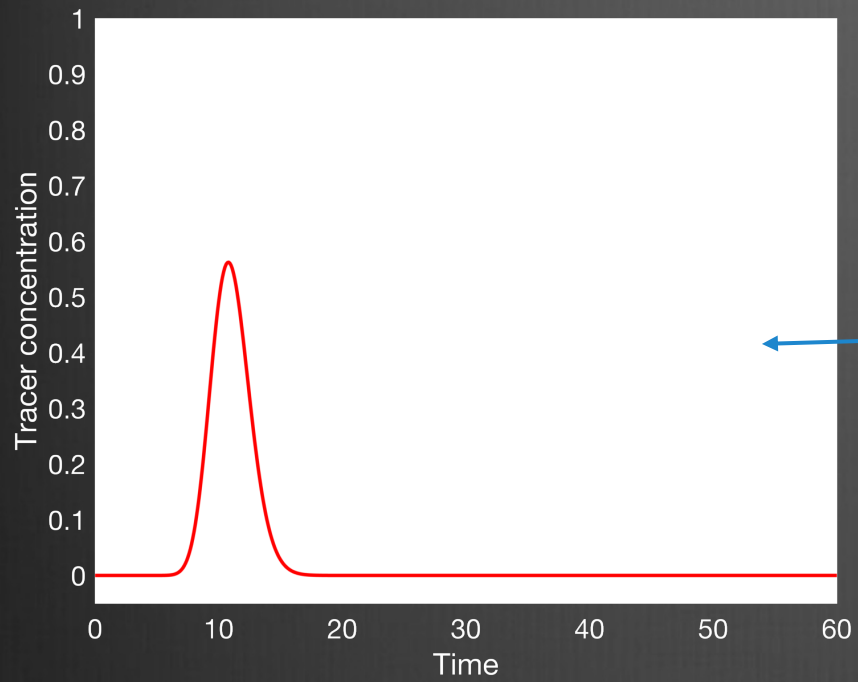


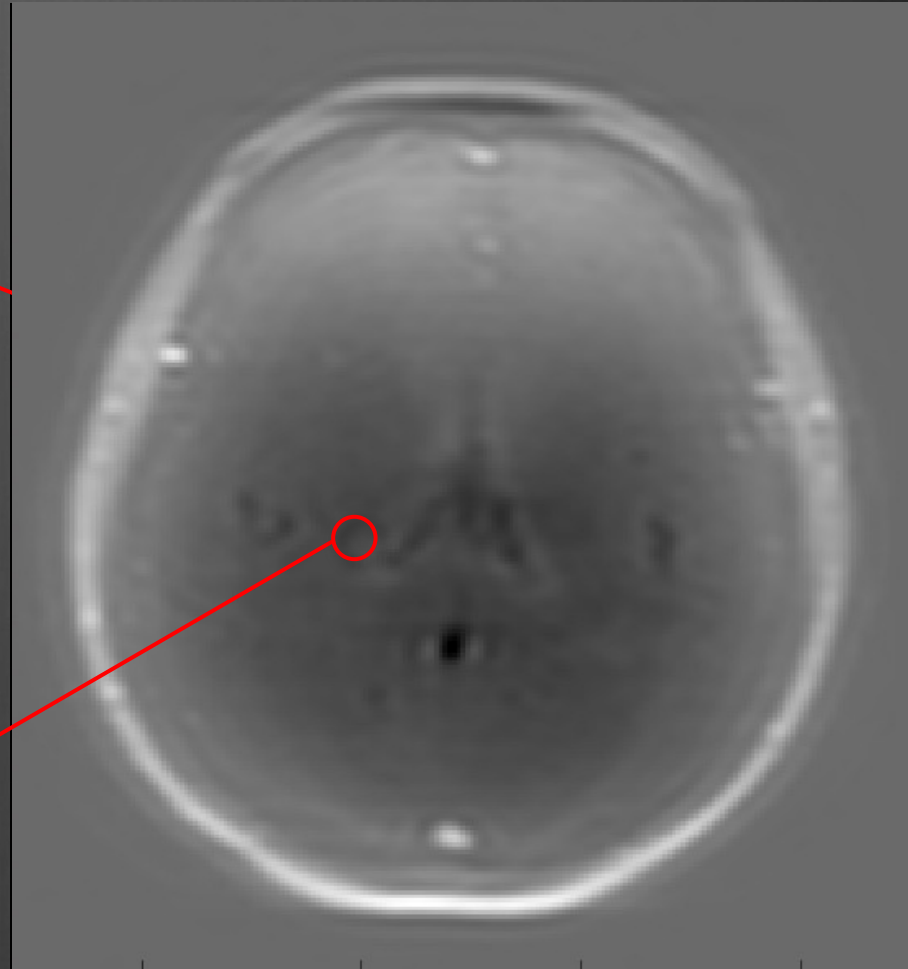
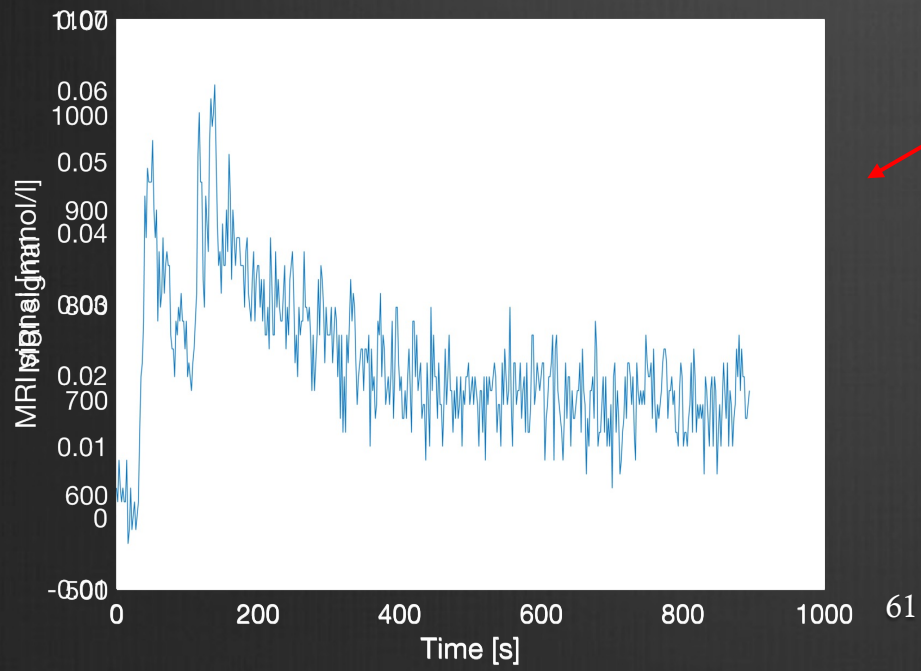
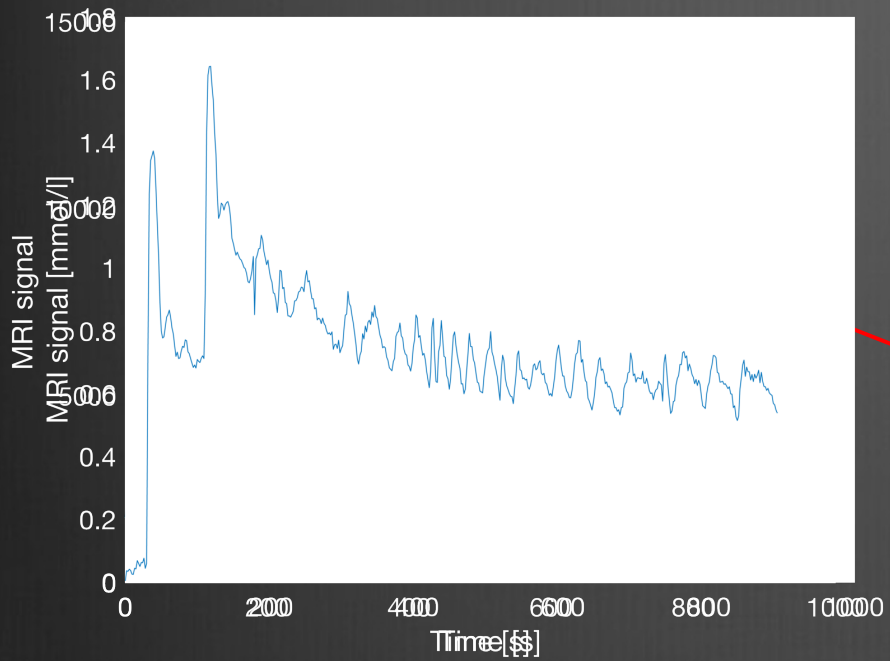
$$C_{\text{meas}}(t) = C_{\text{true}}(t) \otimes d(t)$$

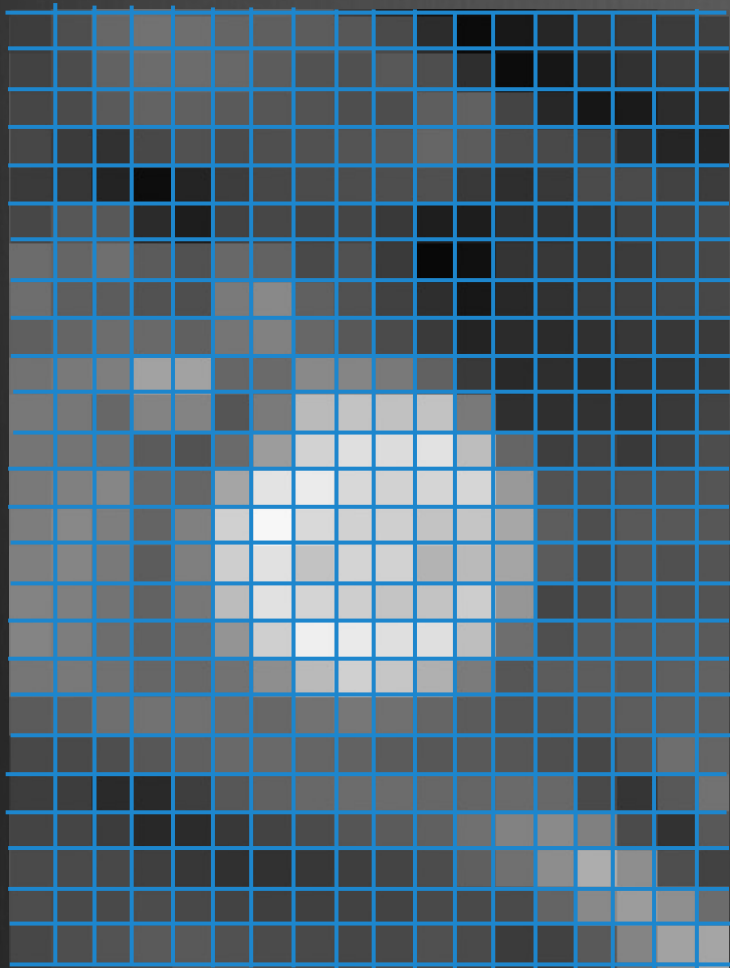


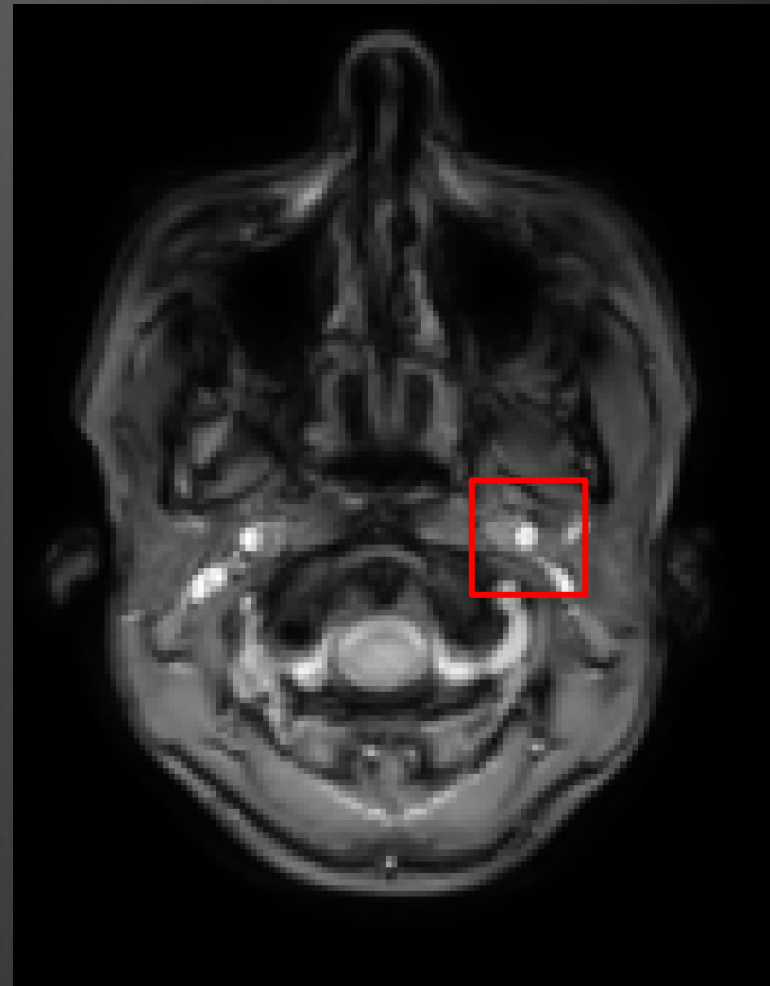
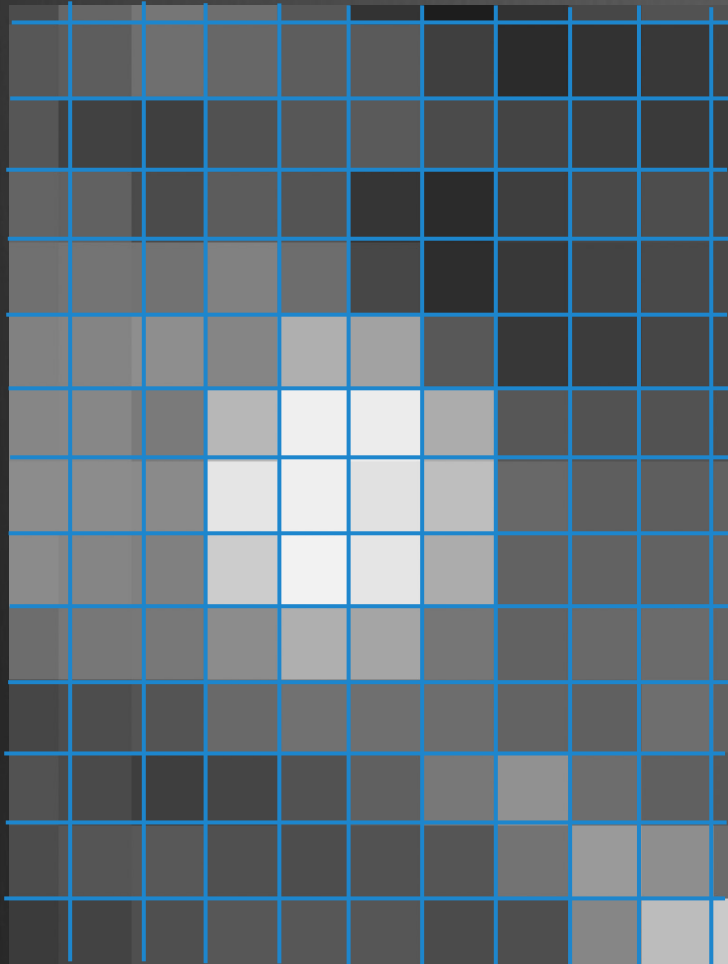




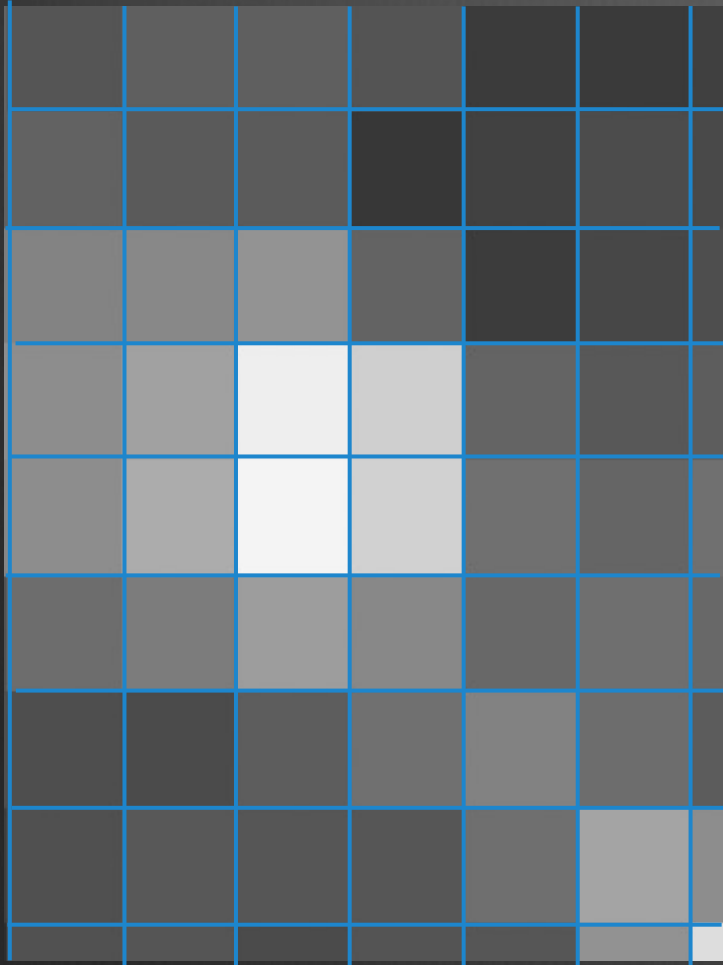




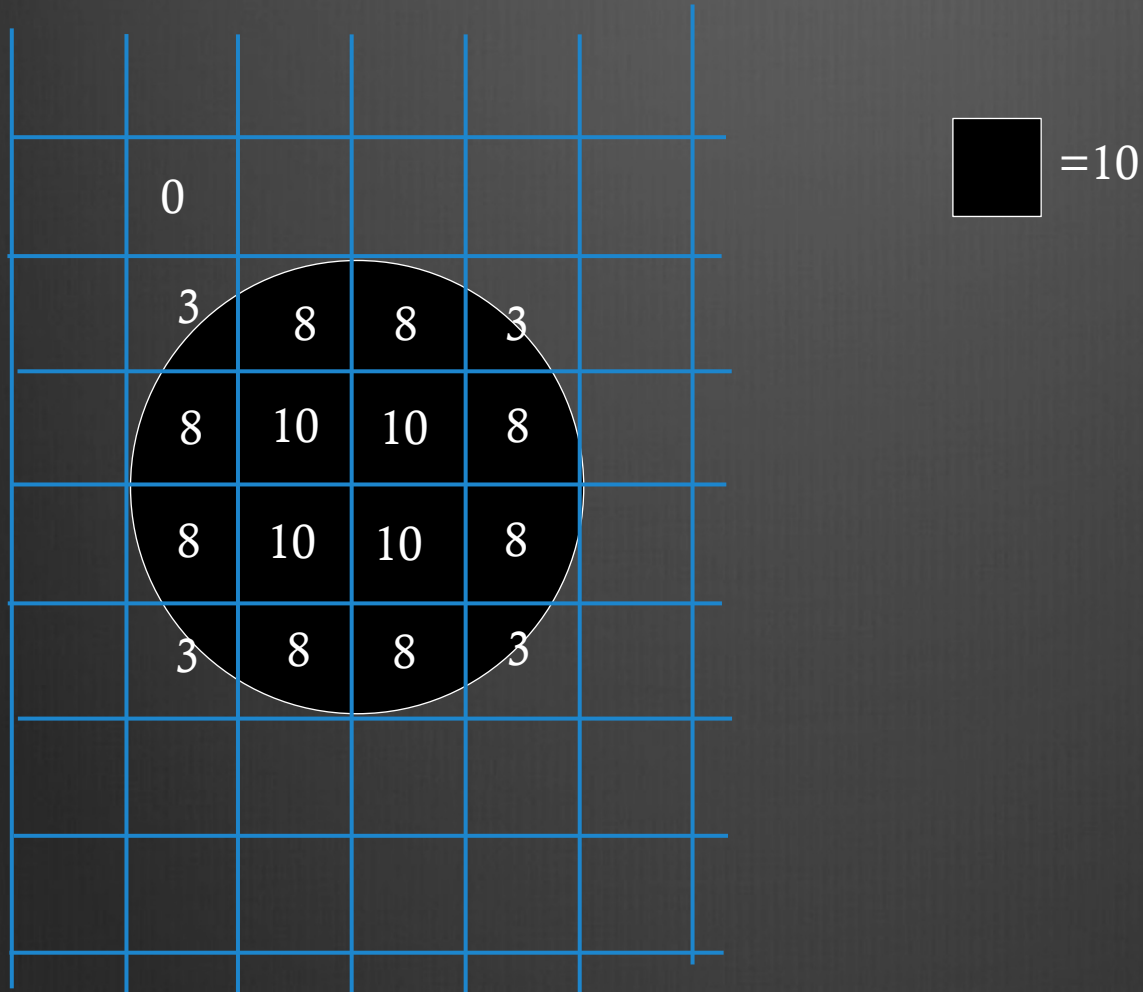




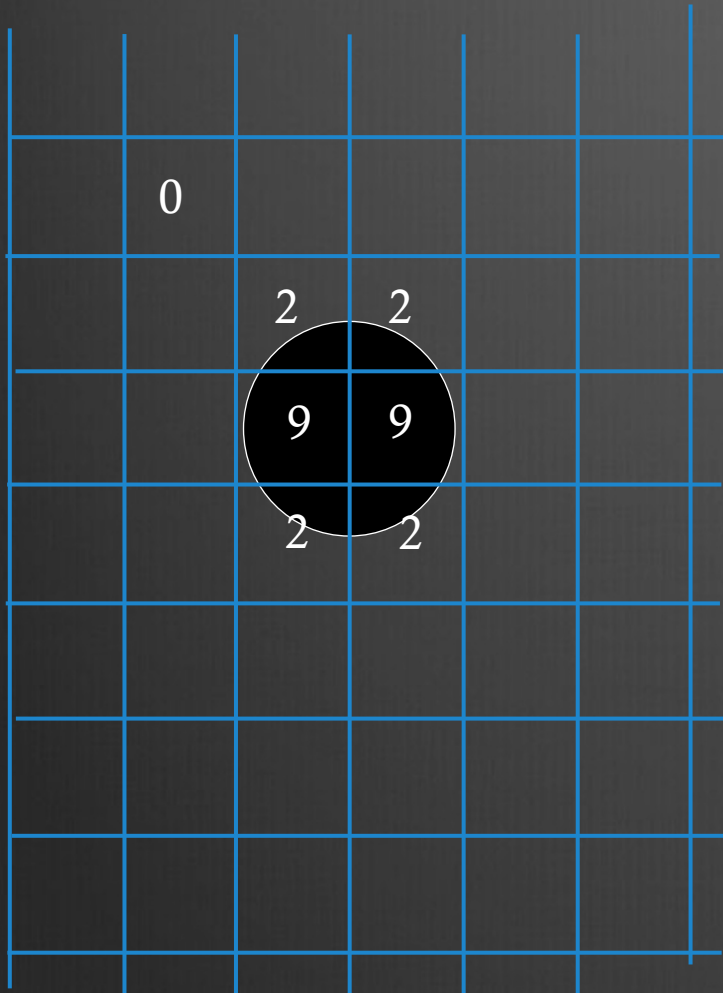
Partial volume errors




Partial volume errors

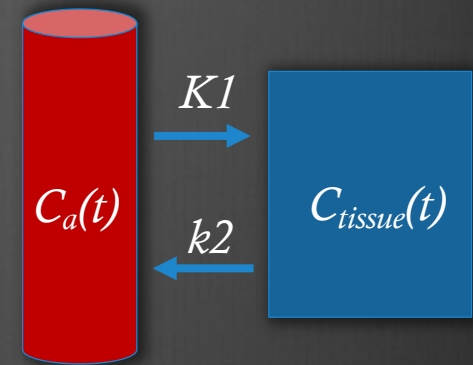


Partial volume errors

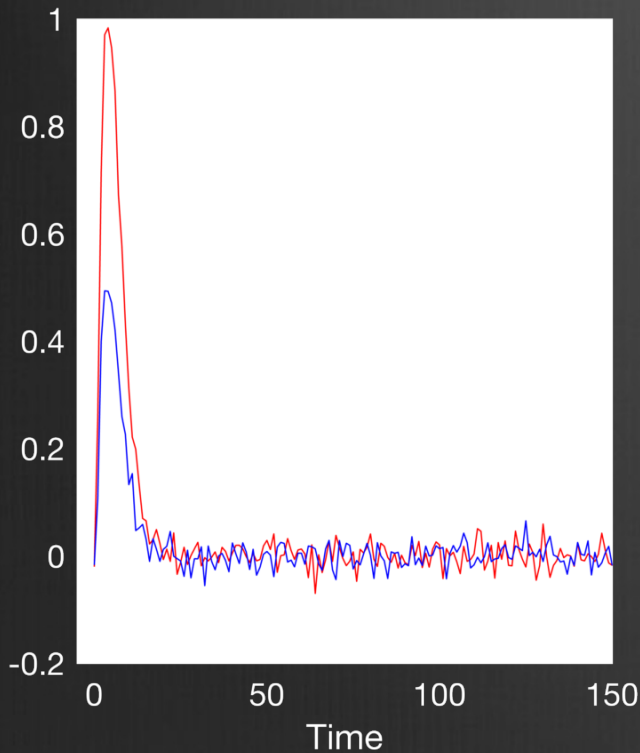


 = 10

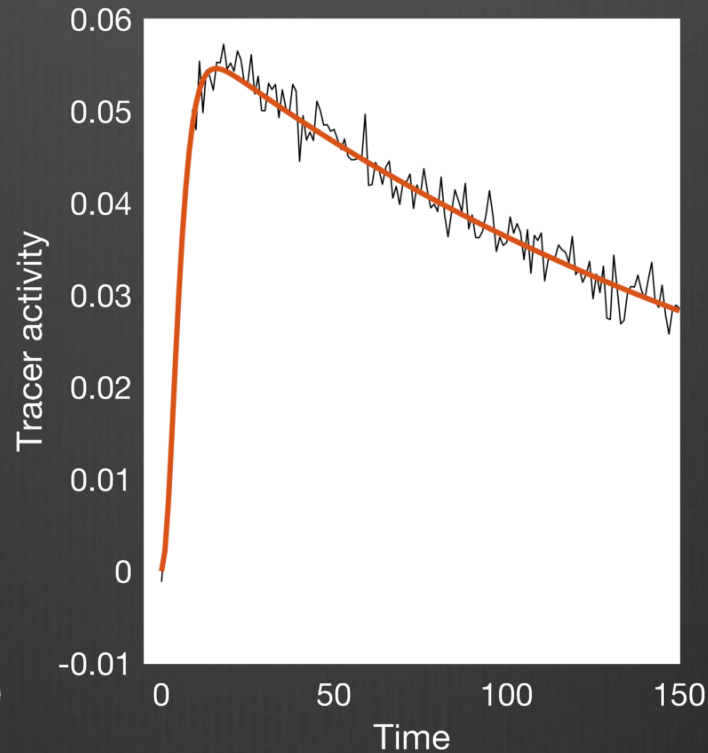
$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t}$$



Input function, $C_a(t)$



Tissue function, $C_{tissue}(t)$

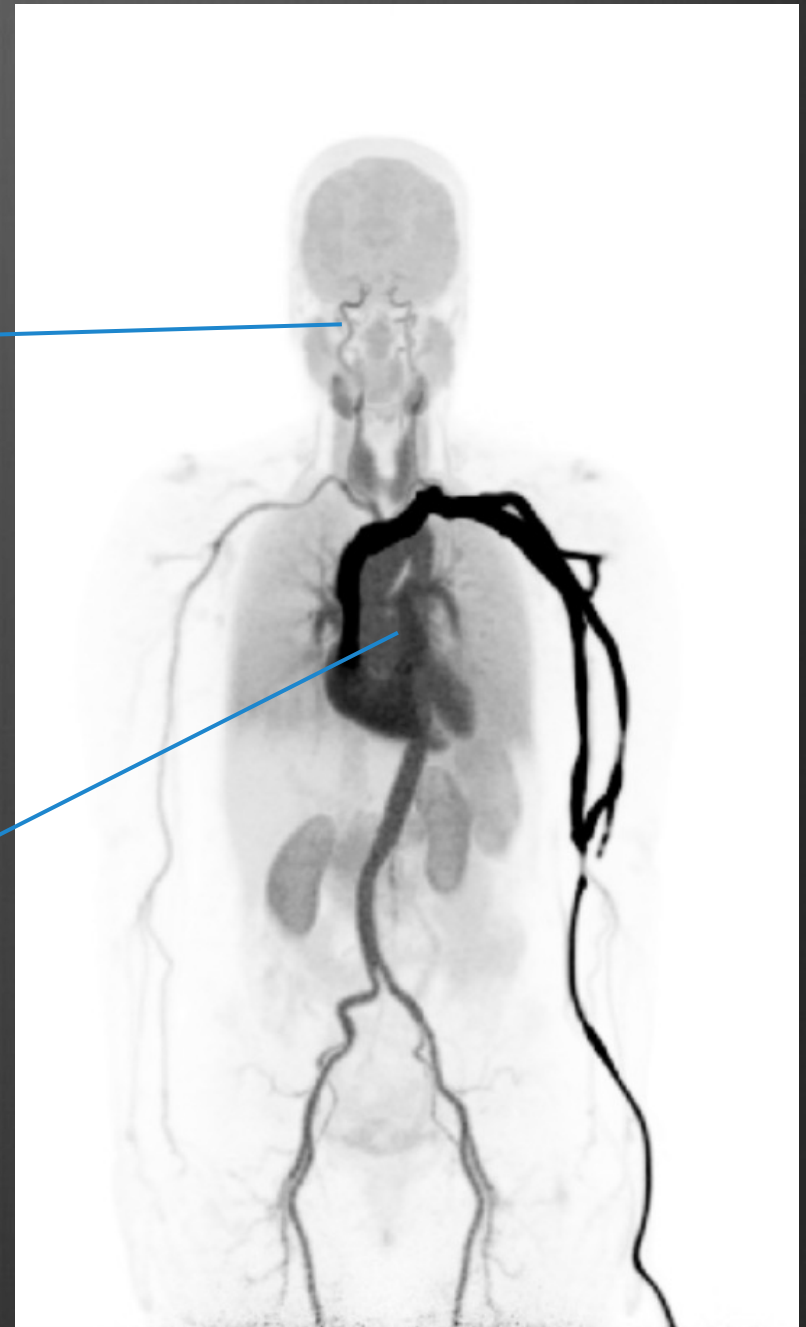
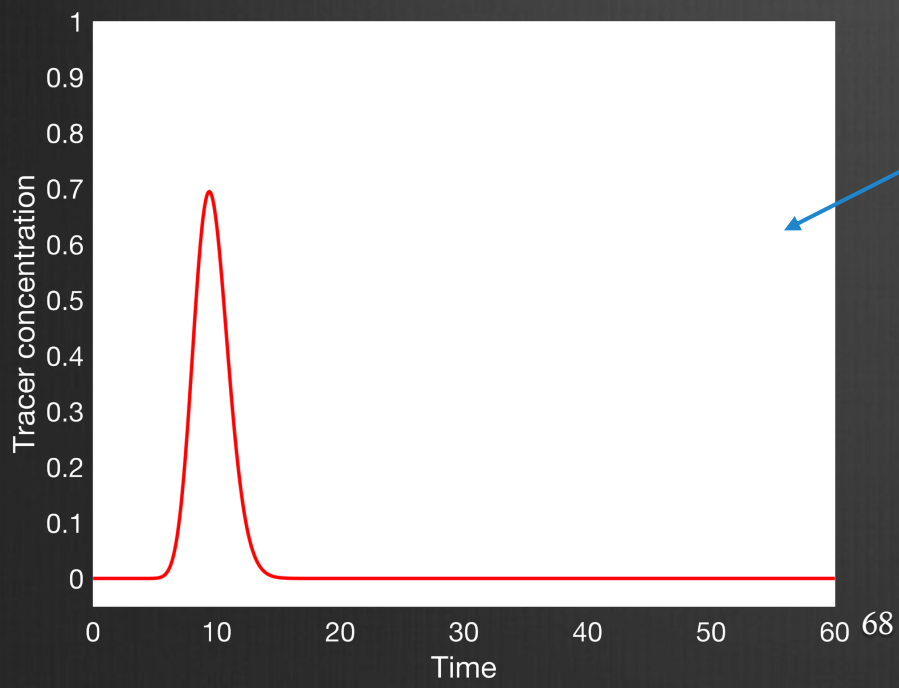
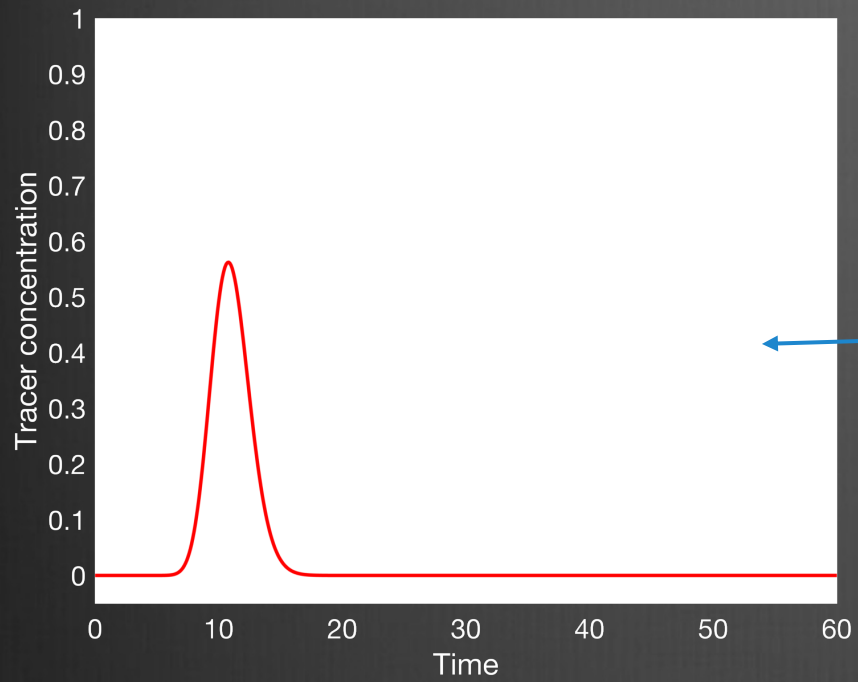


$$C_{tissue}(t) = C_a(t) \otimes 0.95 e^{-0.005 t}$$

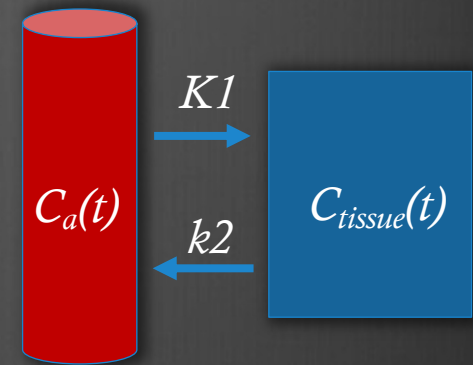
$K1=0.9$
 $k2=0.005$

$$C_{tissue}(t) = C_a(t) \otimes 0.95 e^{-0.005 t}$$

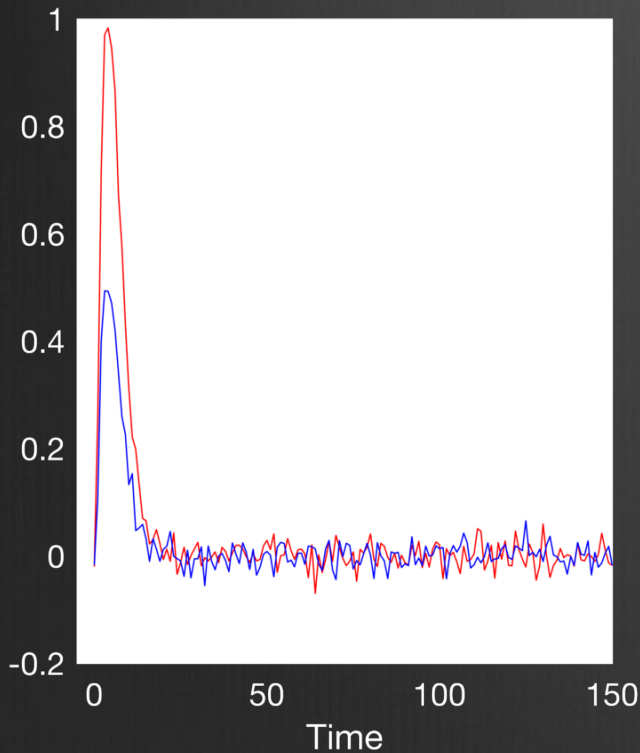
$K1=1.8$
 $k2=0.005$



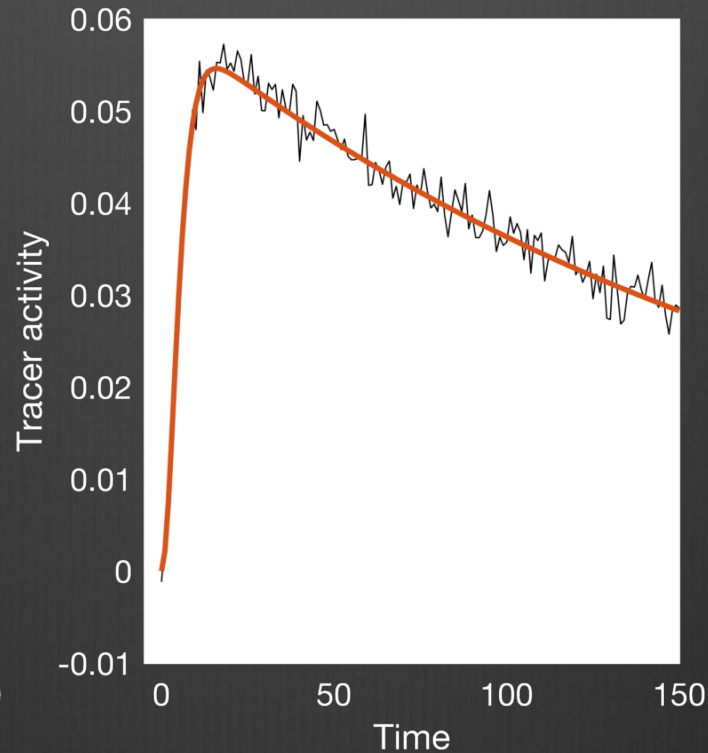
$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t}$$



Input function, $C_a(t)$



Tissue function, $C_{tissue}(t)$



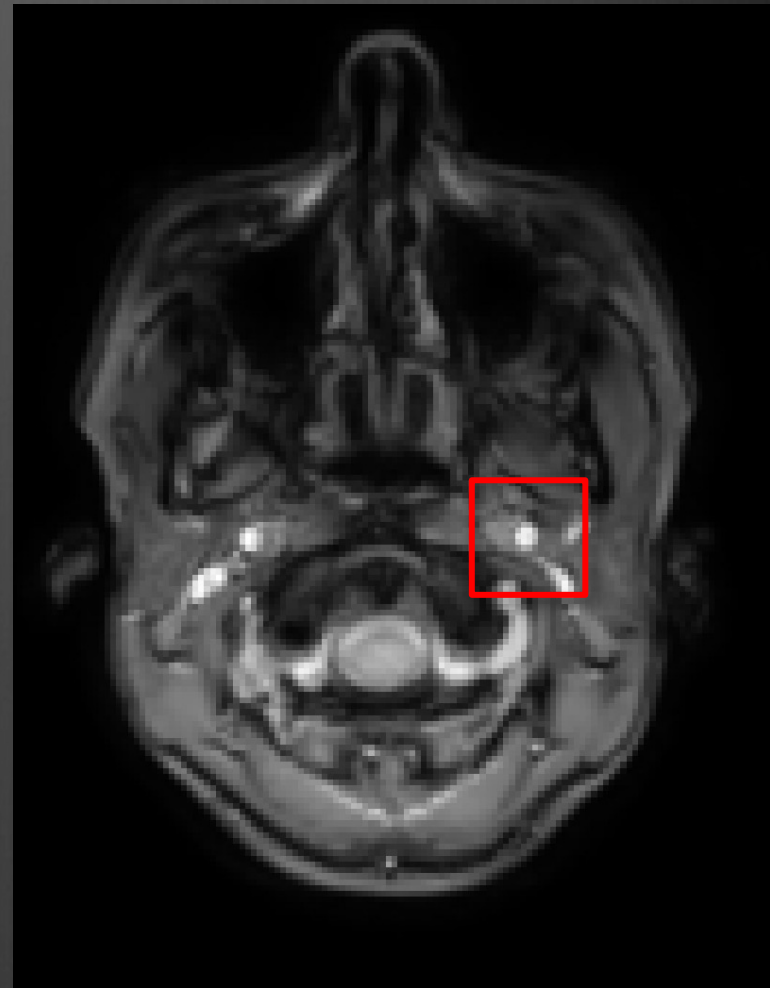
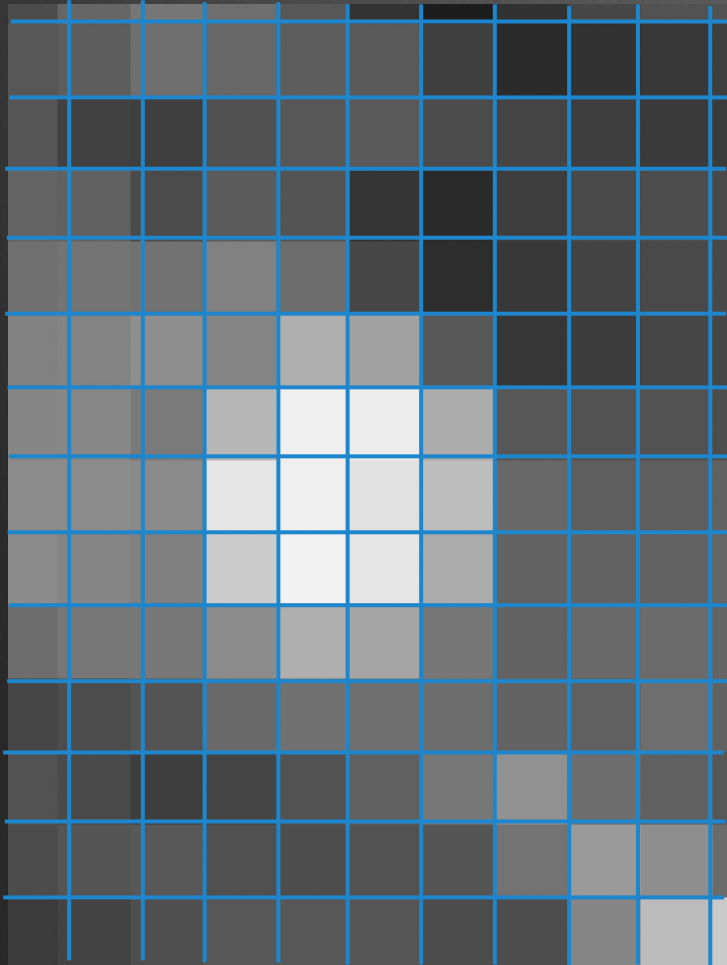
$$C_{tissue}(t) = C_a(t) \otimes 0.95 e^{-0.005 t}$$

$K1=0.9$
 $k2=0.005$

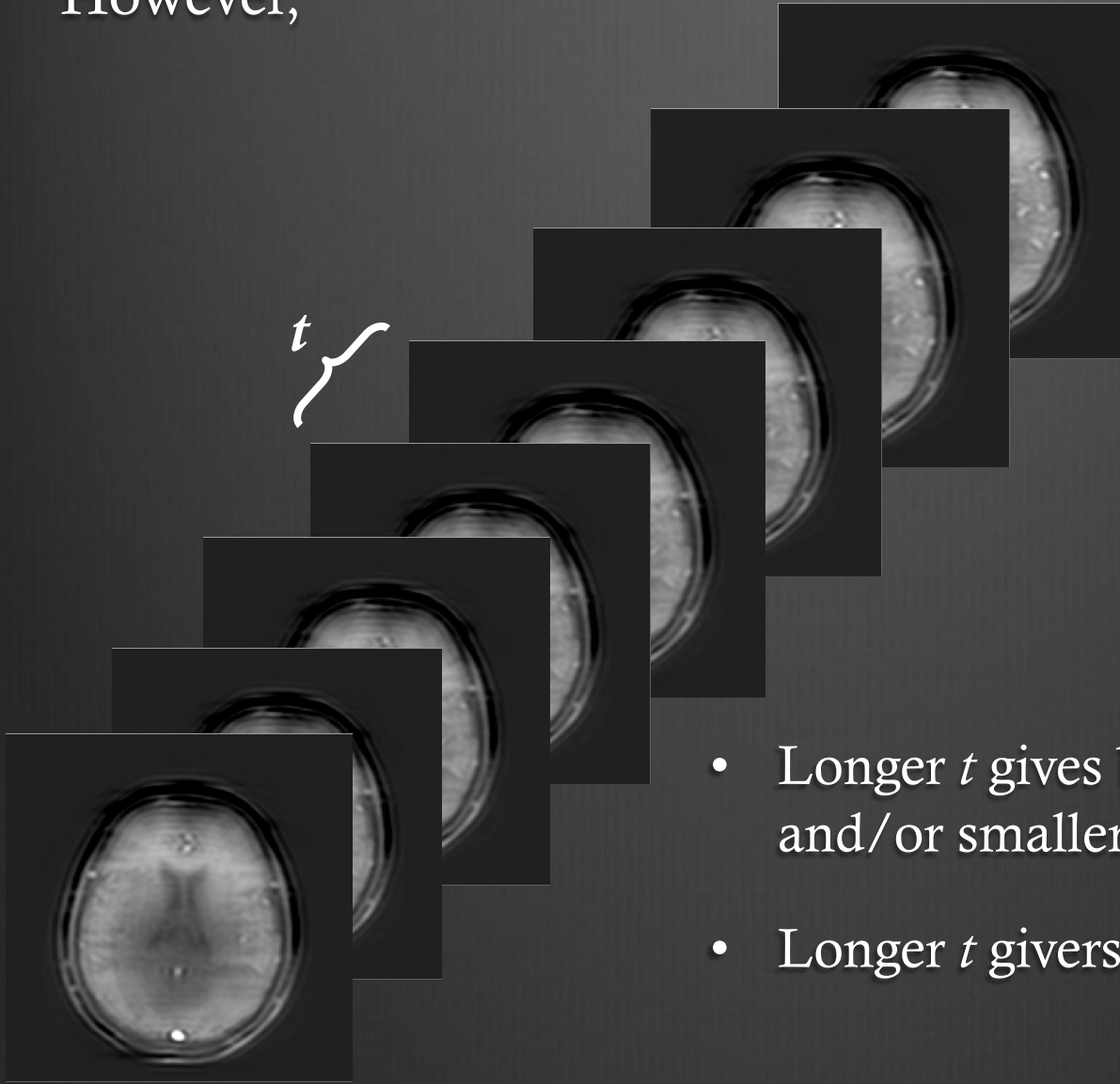
$$C_{tissue}(t) = C_a(t) \otimes 0.95 e^{-0.005 t}$$

$K1=1.8$
 $k2=0.005$

Important to measure small voxels

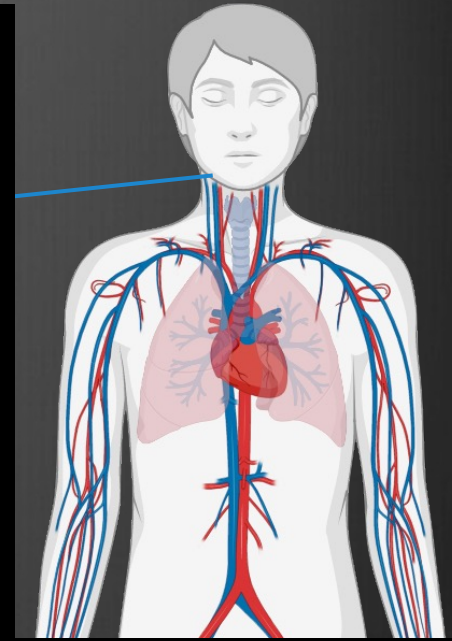
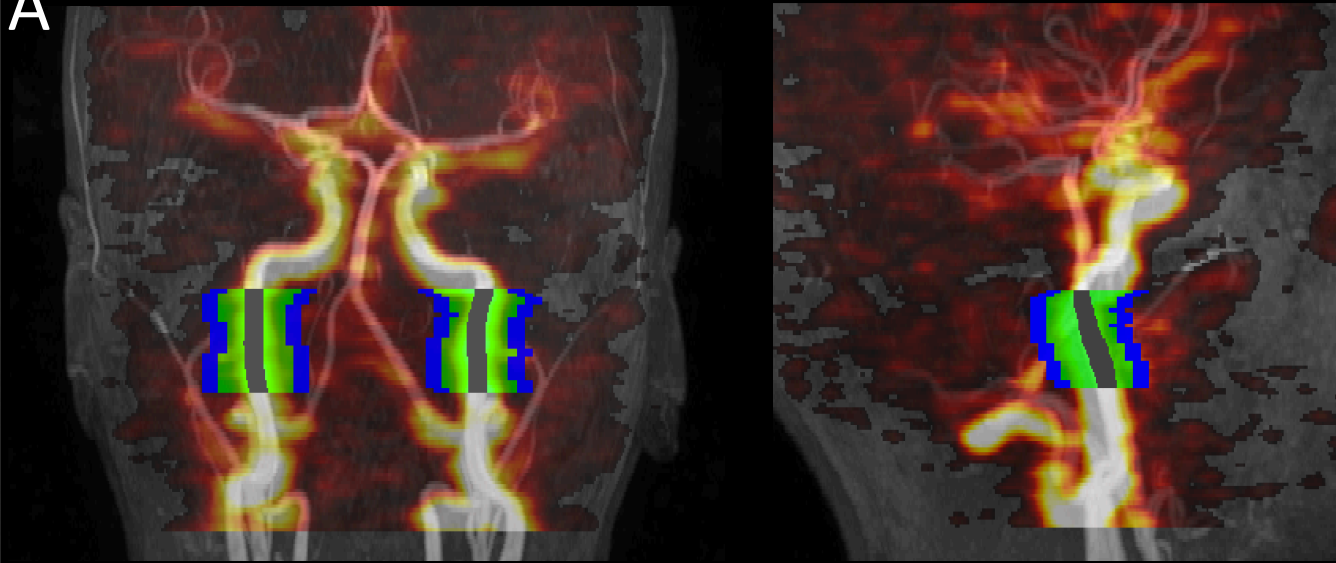


However,

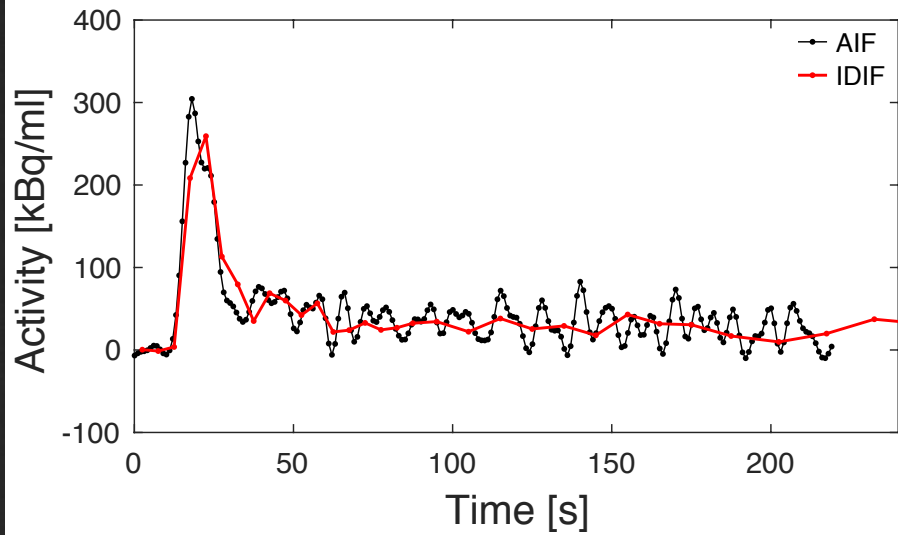


- Longer t gives better image quality and/or smaller voxel sizes
- Longer t gives poorer time resolution

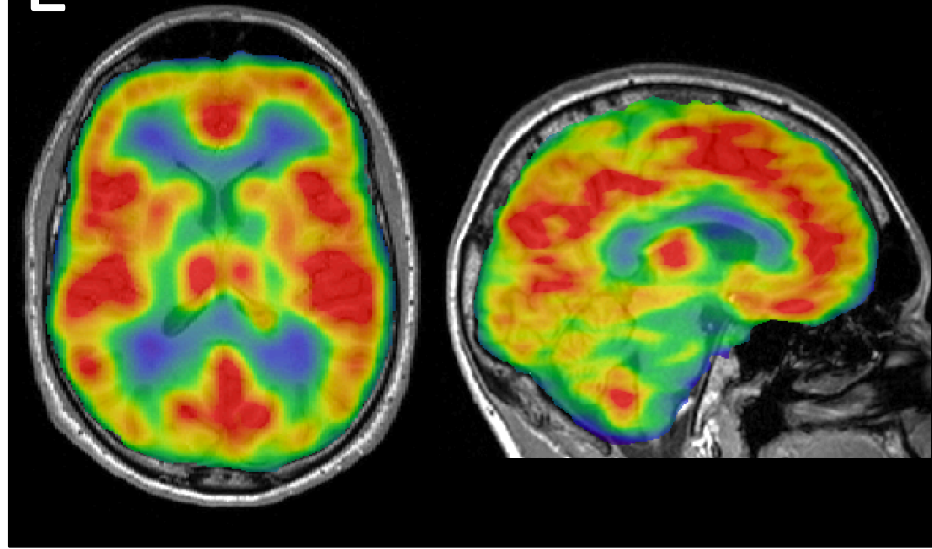
A

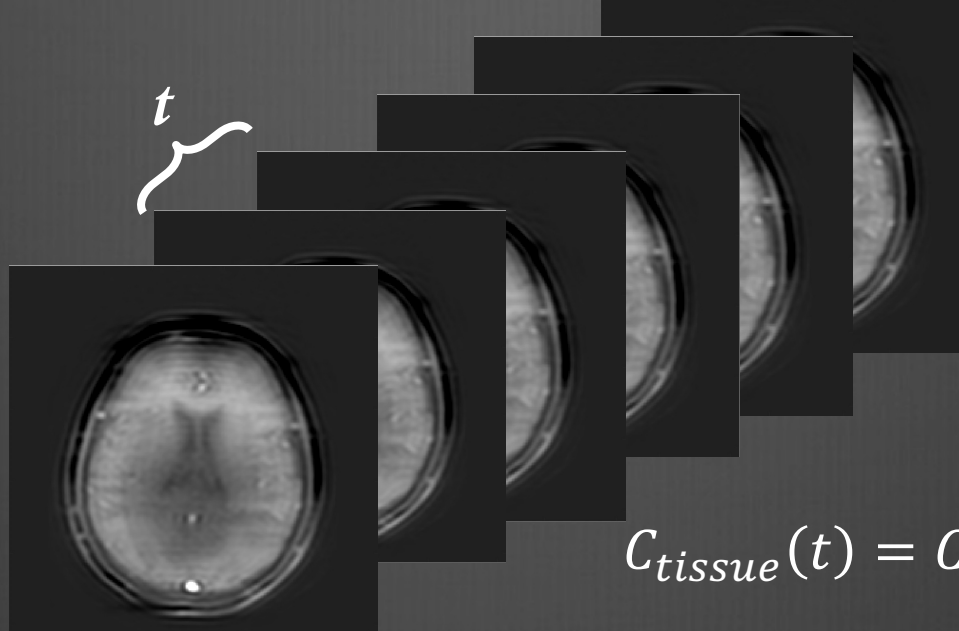


D



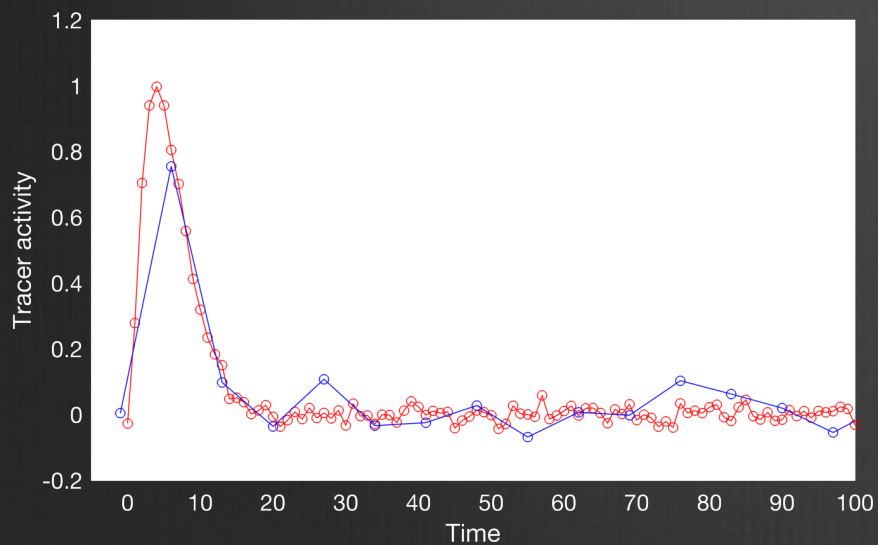
E



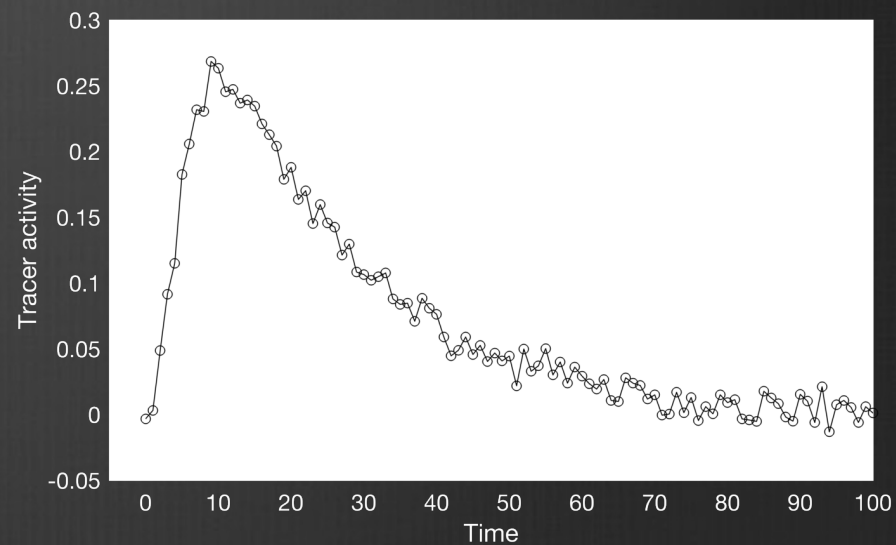


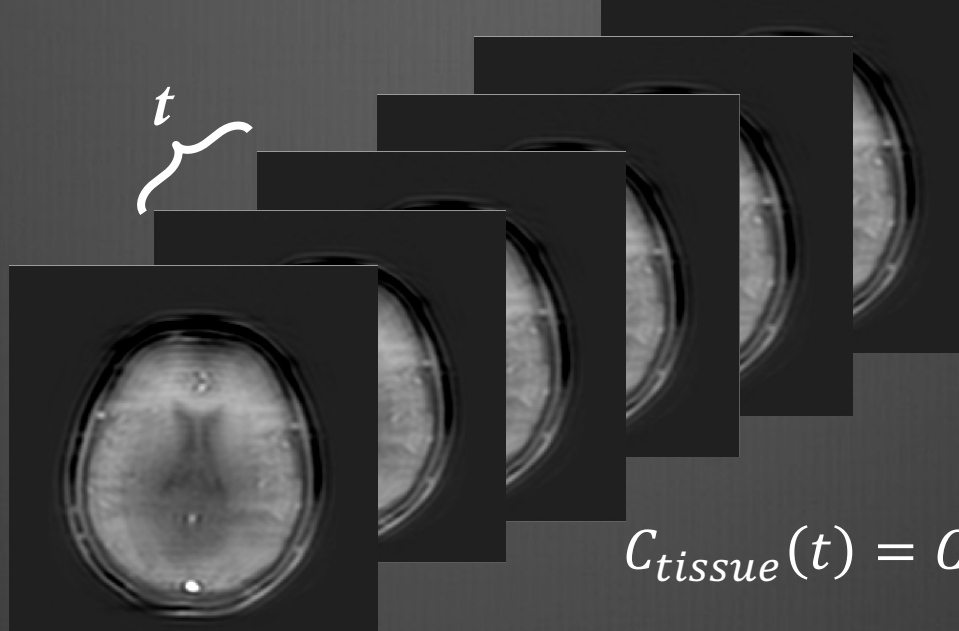
$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t}$$

Input function, $C_a(t)$



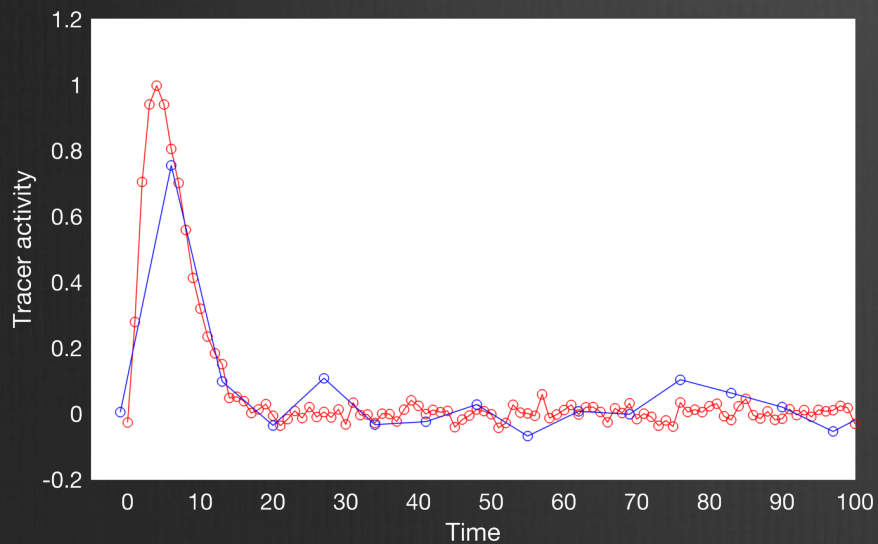
Tissue function, $C_{tissue}(t)$



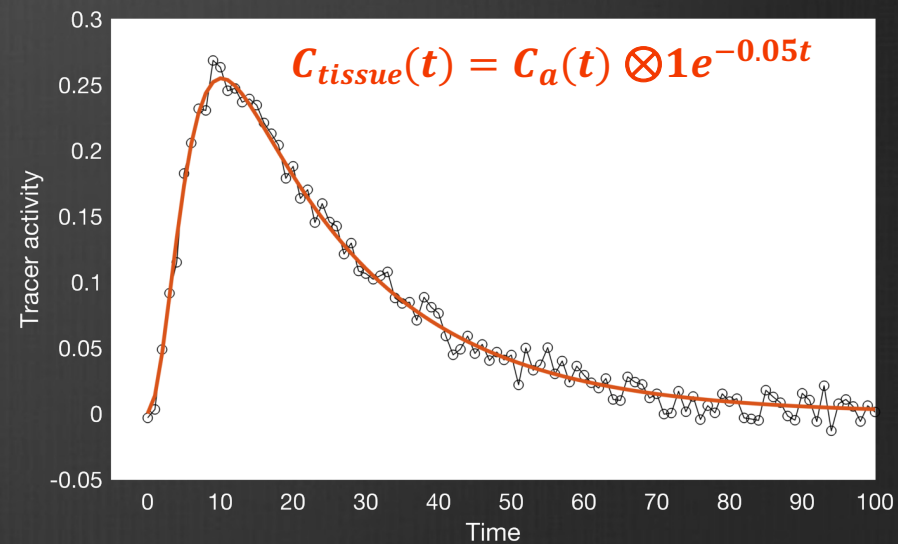


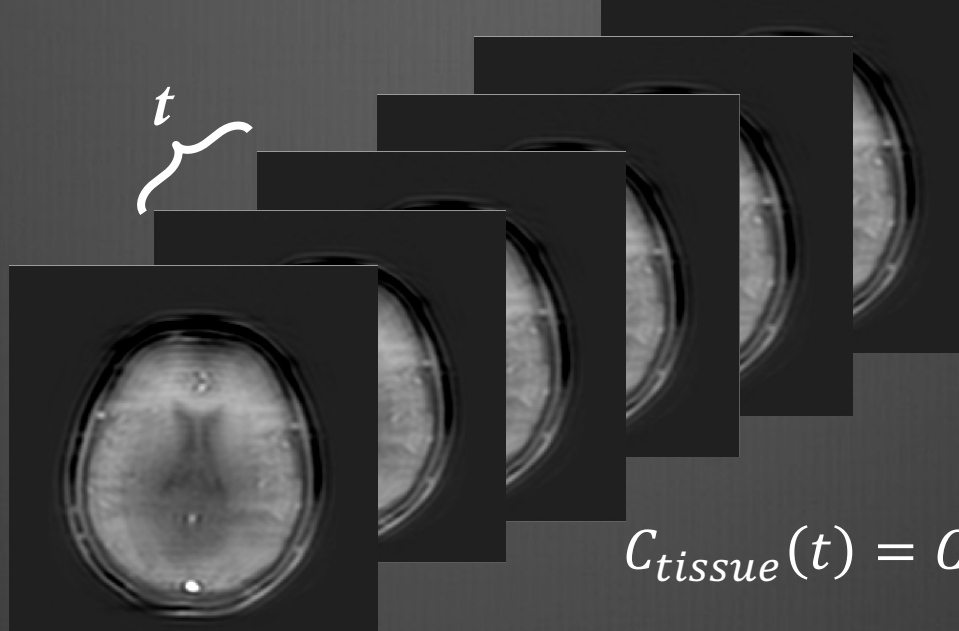
$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t}$$

Input function, $C_a(t)$



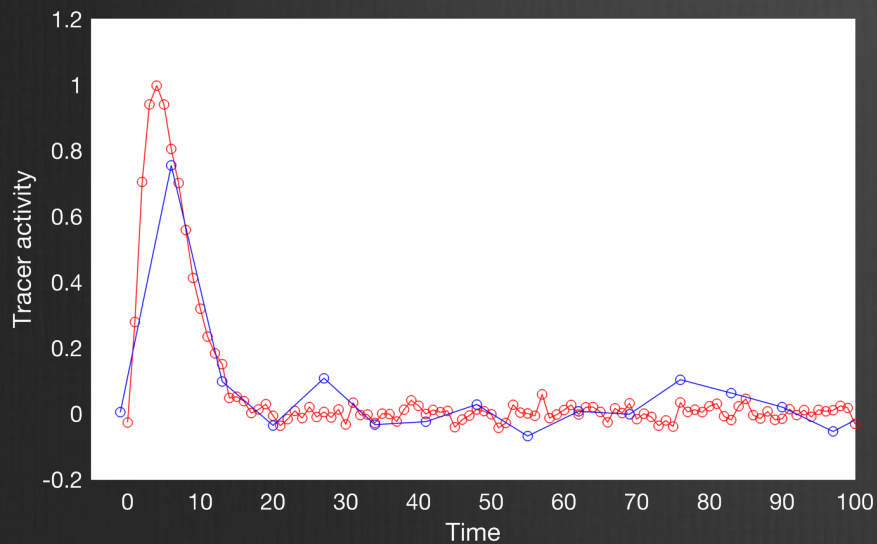
Tissue function, $C_{tissue}(t)$



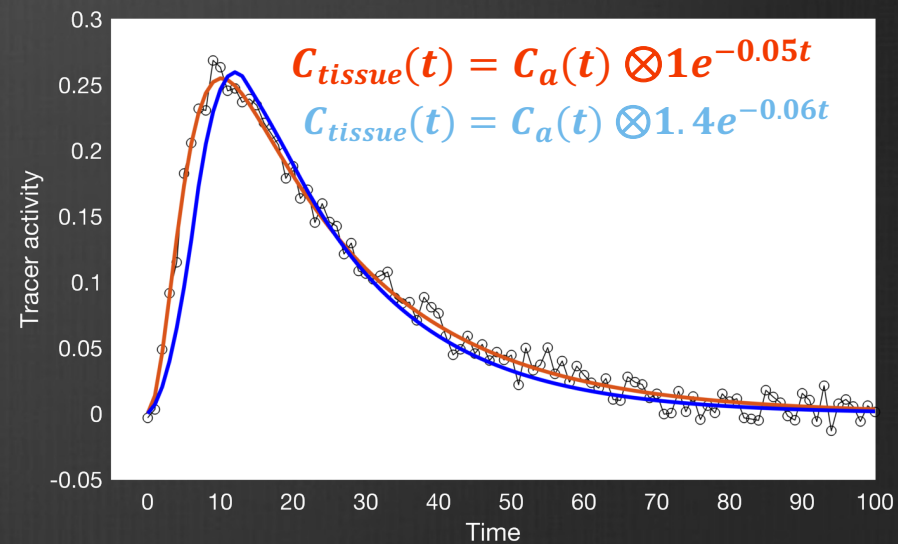


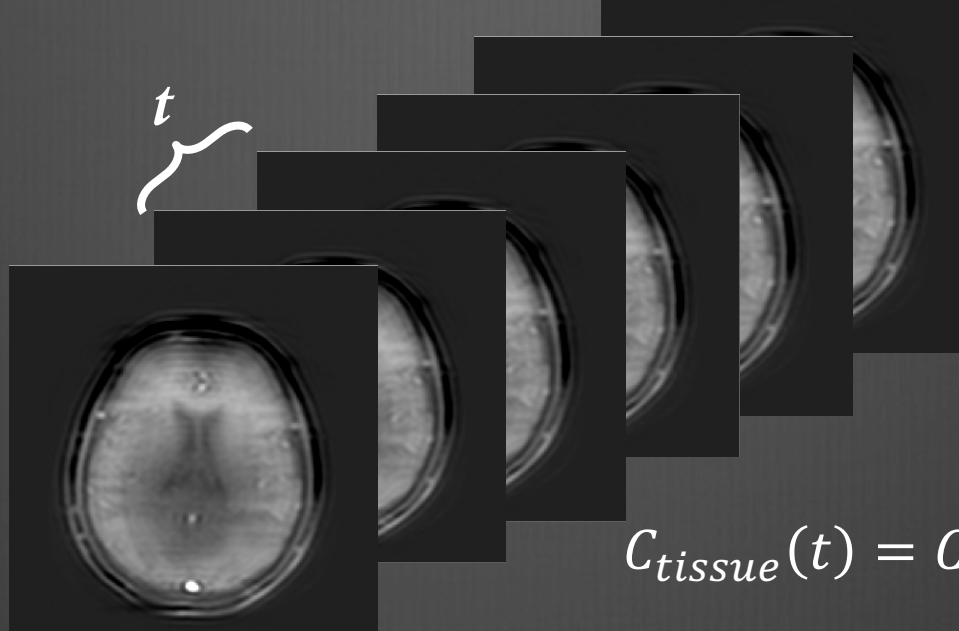
$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t}$$

Input function, $C_a(t)$



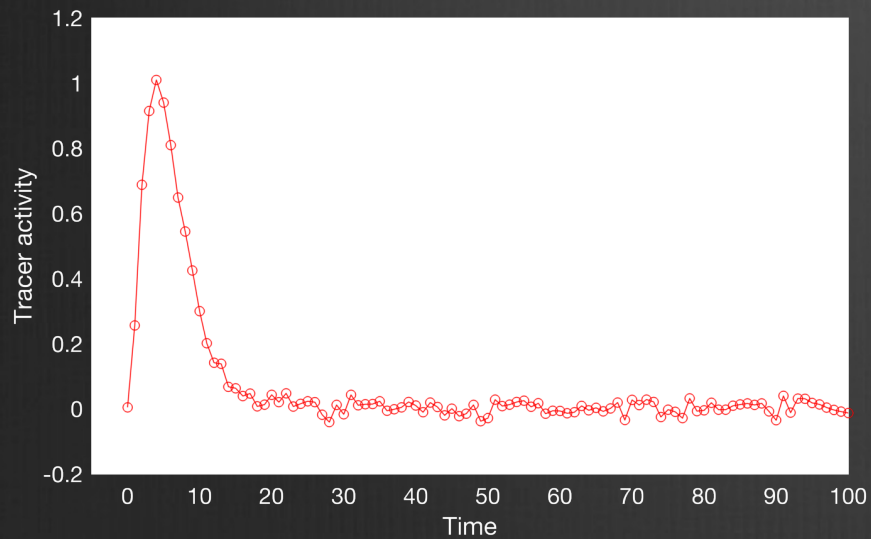
Tissue function, $C_{tissue}(t)$



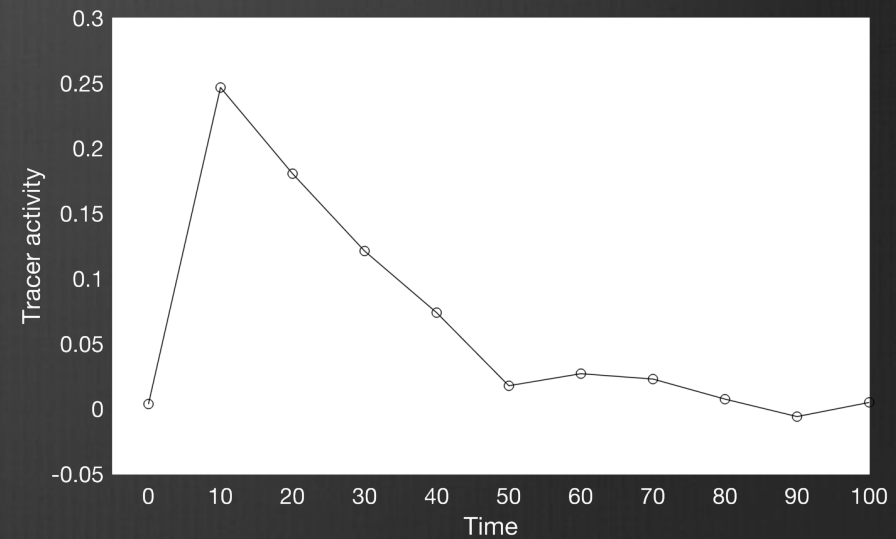


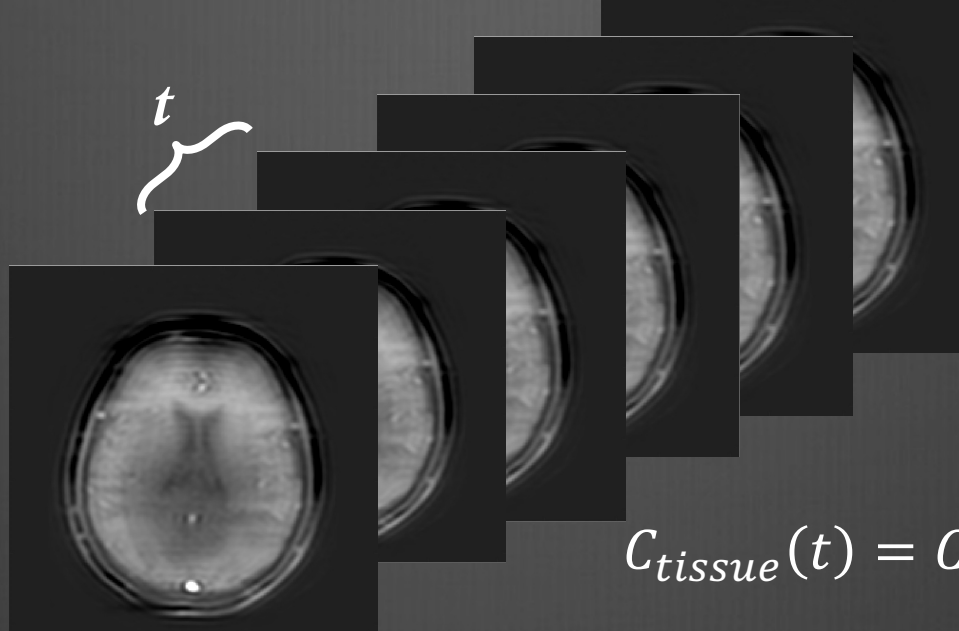
$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t}$$

Input function, $C_a(t)$



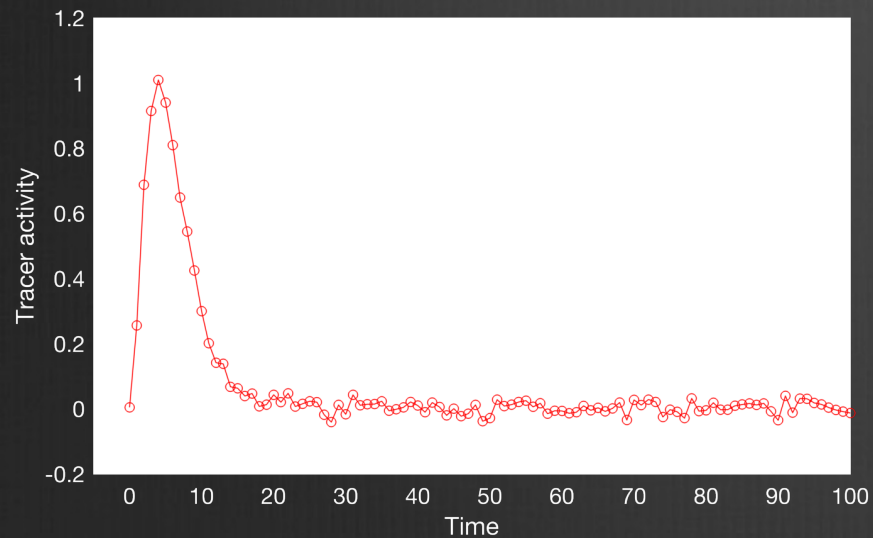
Tissue function, $C_{tissue}(t)$



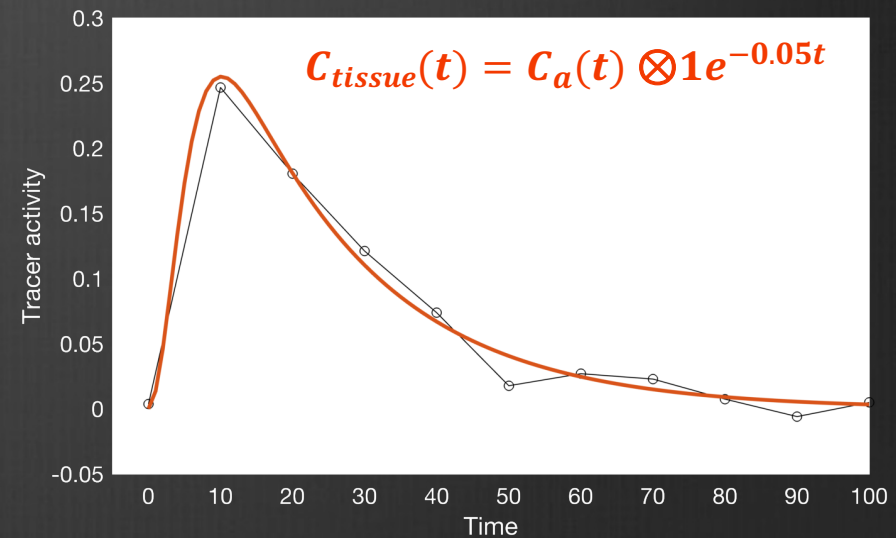


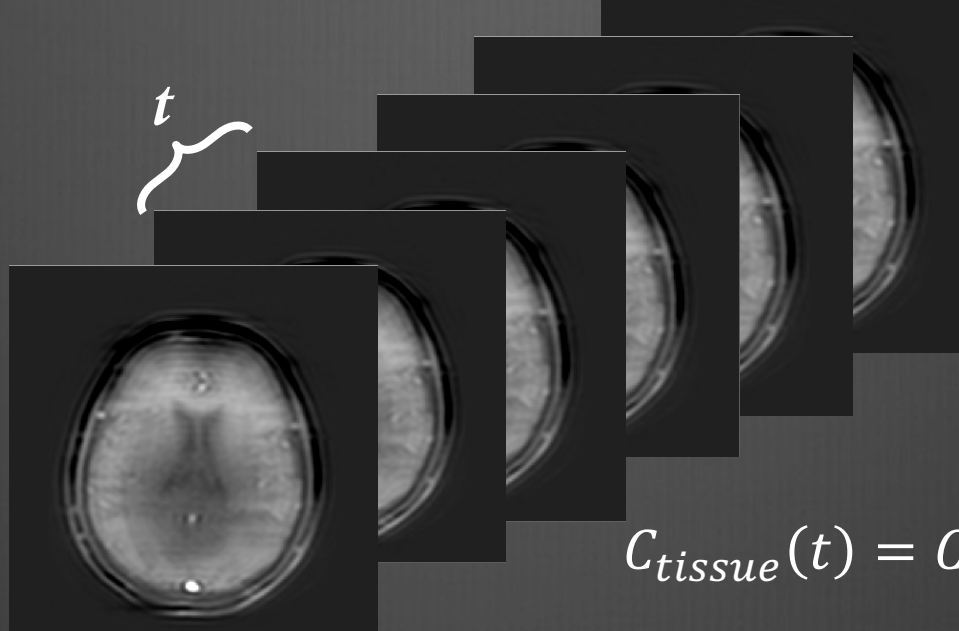
$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t}$$

Input function, $C_a(t)$



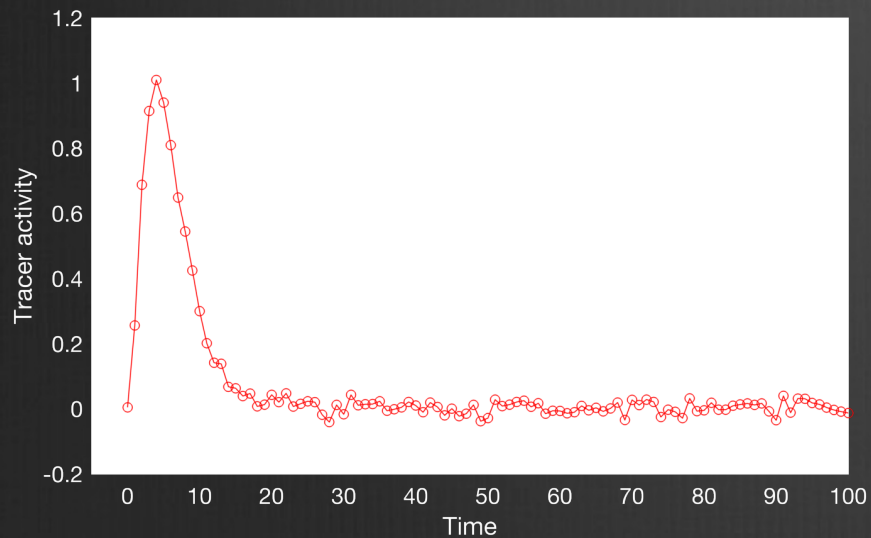
Tissue function, $C_{tissue}(t)$



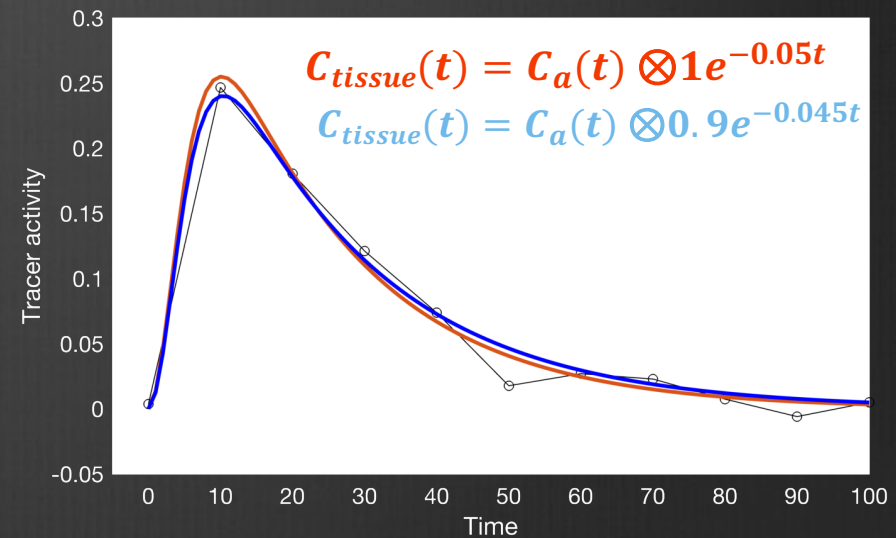


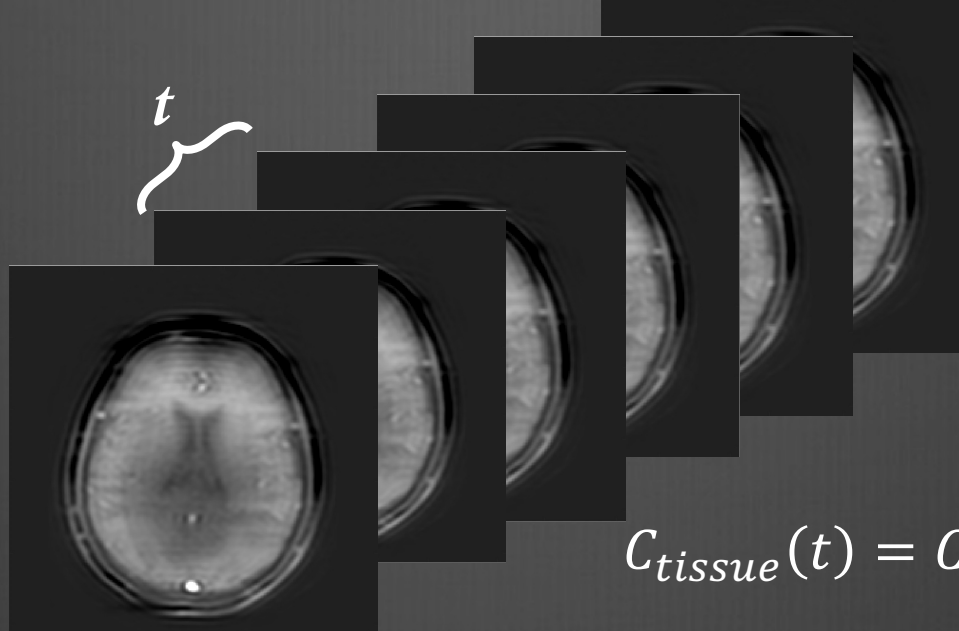
$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t}$$

Input function, $C_a(t)$



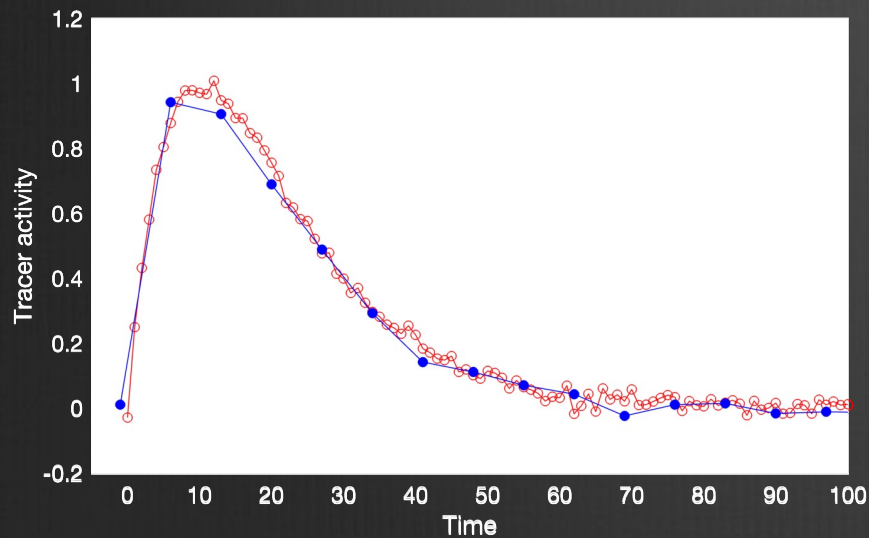
Tissue function, $C_{tissue}(t)$



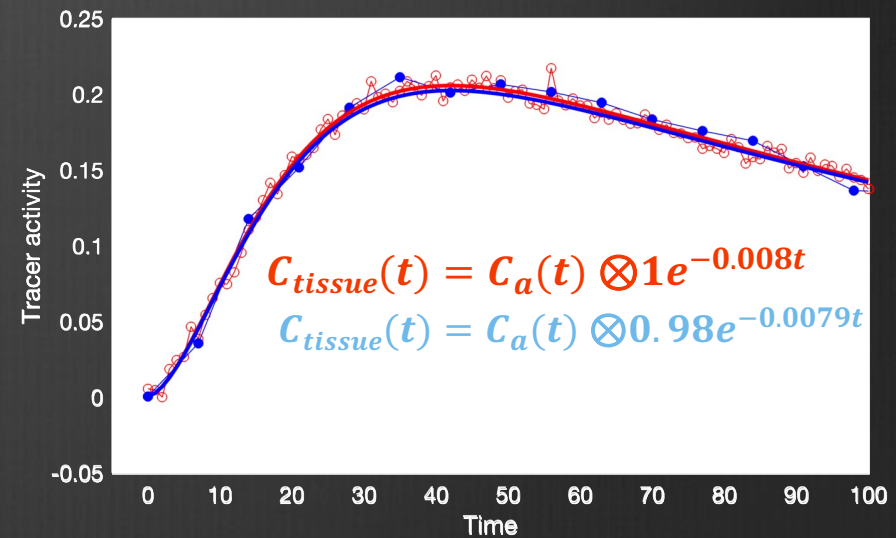


$$C_{tissue}(t) = C_a(t) \otimes K_1 e^{-k_2 t}$$

Input function, $C_a(t)$



Tissue function, $C_{tissue}(t)$



Summary

- Measurement of input function
 - Same unit or reference
 - Avoid partial volume errors from image-derived input function
 - Optimal measurement of input function depends on your equipment and experiment setup
- Spatial resolution (voxel size) vs. time resolution should be considered when acquiring data
- Poorer time resolution gives better spatial resolution and better image quality
- With poor time resolution the physiological dynamic might not be captured